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# Understanding what controls the spawning distribution of North Sea whiting (*Merlangius merlangus*) using a multi-model approach

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#### Abstract:

The processes that control the spatial distribution of North Sea whiting (Merlangius merlangus) spawning adults are investigated using a statistical multi-model approach. Models of external and internal controls on the population, such as environmental conditions, spatial constraints, present or past spatial distribution, and demographic state of the population, are evaluated, compared and ranked to select those that are the best able to predict the observed distribution of spawning adults. Model selection is greatly influenced by the selection method, either based on data fitting or prediction, as well as by the threshold value used to stop the selection. Model selection based on prediction tends to select simpler models than selection based on data fitting. The hypotheses underlying the selected models are inferred to play a significant role in controlling North Sea whiting spatial distribution. The multi-model inference approach developed in this study enables comparison of several theoretical concepts and hypotheses and the results provide important clues on the processes involved in the control of the spatial distribution of whiting. We conclude that whiting has a high spatial fidelity to spawning site which can be linked to either geographical attachment or year-to-year persistence of the spatial distribution of the population. Environmental factors - temperature and salinity - appear to influence the geographical extent of spawning whiting distribution, whereas local abundance levels are primarily controlled by internal factors, i.e., population size and spatial segregation between ages.

**Keywords:** Akaike information criterion; hypotheses inference; model selection; North Sea; spawning distribution; whiting

# INTRODUCTION

North Sea whiting (*M. merlangus*) is one of the key species of the North Sea demersal fish assemblages (Greenstreet and Hall, 1996) as well as the third most exploited gadoid fish in Scotland (Stratoudakis et al., 1999). Not studied as much as cod and haddock, there are nevertheless several studies on population structure (Hislop and MacKenzie, 1976; Rico et al., 1997; Charrier et al., 2007), stock assessment (Pope and Macer, 1996), diet (Hislop et al., 1991; Pedersen, 1999) and spatial distribution (Zheng et al., 2001; Zheng et al., 2002; Atkinson et al., 2004). Whiting has one of the longest spawning periods among North Sea species, lasting from February to June, with a peak in April (Gibb et al., 2004). Spawning progressively occurs later in the season at increasing latitudes. Whiting becomes mature at 2 years old. Adults are predominantly found in shallow waters, at temperatures between 6 and 9°C, and have a protracted spawning period of between 6 weeks and 2 months. Eggs are pelagic and released in the water in several batches (ICES, 2005). As for many fish species in the North Sea, whiting stock abundance has substantially declined since the 1970s (Hislop, 1996; Serchuk et al., 1996) because of increasing fishing mortality since the 1940s (Greenstreet and Hall, 1996), a high discard rate (Stratoudakis et al., 1999) and poor recruitment in the 1980s and 1990s (ICES, 2008). Gibb et al. (2004) indicate that this decline may be associated with a contraction in the spatial distribution and a loss of distinct reproductive populations. However, Daan et al. (1990) highlight that little information on spawning distribution and the factors that determine spawning ground selection is available (Coull et al., 1998; Gibb et al., 2004; ICES, 2005).

Many processes related to both external and internal controls of fish population can explain spatio-temporal variations in spawning fish distribution (Planque *et al.*, 2010). External controls, such as environmental constraints, are independent from

population condition. Internal controls are directly linked to the status of the population under study and include density-dependent processes, the effect of demographic structure, trophic interactions and past conditions of the population. Environment constraint is by far the most commonly considered process, as it is based on the well developed ecological niche theory of Hutchinson (1957). A common spatial structure may be shared by species and environment conditions, as the environment is highly structured in space and many species have ecological preferences for specific environmental ranges. However, individual interactions, especially during reproduction, can also lead to spatial dependency in fish spatial distribution. It may be difficult to separate pure environmental control from combined space-environment control, but recent studies have developed ways to evaluate this shared component (Borcard et al., 1992; Borcard and Legendre, 1994; Borcard and Legendre, 2002; Borcard et al., 2004). Other processes related to the internal condition of the population, mainly its density and demographic structure, may also influence fish spatial distribution. According to the ideal free distribution (Fretwell and Lucas, 1970; Sutherland, 1983) and the densitydependent habitat selection (McCall, 1990; Rosenzweig, 1991), fish populations may have a contracted spatial distribution at low level of population density whilst expanding at high abundance, leading to an abundance-area relationship (Swain and Morin, 1996; Fisher and Frank, 2004; Blanchard et al., 2005). Old and young individuals may also be found in distinct geographical areas in variable proportions, thus the relative abundance of different age classes in a given year may partly control the population's spatial distribution (Zheng et al., 2001). Finally, recurrent spawning areas are commonly found for many fish species, indicating a strong geographical attachment. This ability to return to a specific location from year to year may result from geographical attachment and/or from a number of mechanisms which promote

## **Fisheries Oceanography**

persistence, or conservatism, in spatial distribution patterns (Corten, 2002; Petitgas et al., 2006). We group the latter processes under the term of 'population memory'. A more complete description of the various ecological hypotheses on the control of fish population spatial distributions is provided in Plangue *et al.* (2010).

To elucidate the relative importance of hypotheses that control spawning fish spatial distribution, a multi-inference model and information theoretic approach may be used (Hilborn and Mangel, 1997; Burnham and Anderson, 2002; Johnson and Omland, 2004; Stephens et al., 2007; Diniz-Filho et al., 2008). Using such an approach, Loots et al., (2010) have successfully compared several models reflecting various hypotheses of control based on a metric distance between model predictions and observations. Hypotheses underlying the selected set of reasonably good models can thus be inferred to represent the dominant controls of the spatio-temporal variability of a population's distribution pattern. Based on the approach developed in Planque et al. (2010) and applied in Loots et al. (2010), the present study aims to determine what are the dominant controlling factors of the spatial distribution of North Sea whiting at the beginning of its spawning season. We investigate several processes of control using statistical models that are evaluated, compared and selected. In addition, the sensitivity of the model selection and inference to datasets and selection thresholds are investigated.

#### MATERIAL AND METHODS

## The biological response

The spatial distribution of whiting at the beginning of its spawning season was investigated using the 1980 to 2007 abundance data of spawning adult whiting from the first quarter of the International Bottom Trawl Surveys (January-March) (Fig. 1). These abundances have been computed for the seven standard roundfish areas of ICES (International Council for the Exploration of the Sea, Fig. 1), from the available proportion of stage 3 adults (corresponding to spawning adults with fluent gonads, ICES, 2004) within any given length class (Fig. 2). Males and females data were merged together as the data were insufficient to calculate proportions of spawning adults for each sex. The total number of trawling stations available was 9435. For each of these stations, total abundance of spawning adults was calculated as the product of the total abundance and the corresponding proportion of spawning adults within each size class.

#### Modelling the control hypotheses

Ten possible factors of control have been modelled: persistent and non-persistent environment, three scales of spatial dependency, population size, annual and spatial age 130 structure, geographical attachment and population memory. Persistent environment consists of environmental conditions that are spatially structured but do not display interannual variations during the study period (e.g. bottom depth). Non-persistent environment are environmental conditions that are also spatially structured but have changed during the study period (e.g. temperature). Spatial dependency (resulting in 135 spatial autocorrelation) describes the spatial structure present in the distribution of whiting. Spatial dependency may potentially be shared by other controls like persistent

#### **Fisheries Oceanography**

and non-persistent environment. Population size is the size of the population in biomass and number of individuals by year. Annual age structure (referred to as annual demography) corresponds to the proportions of each year-class in the whole area, whereas spatial age structure (referred to as spatial demography) is the spatial distribution of each year-class at each trawling station. Geographical attachment corresponds to absolute geographical coordinates and population memory depicts the degree of persistence of whiting distribution from one year to the next. Geographical attachment supposes that whiting returns to the same spawning site every year whereas population memory reflects that current spatial distribution depends upon recent past distribution(s). Geographical attachment is equivalent to local random processes with a fixed mean, with no memory in the process, but if the variance is low, the different realizations will be close to the mean and therefore local abundance is similar between years. Population memory is equivalent to an autoregressive process. There is memory in the process and the mean is not fixed, therefore local abundance is expected be more similar between consecutive years than between years that are separated in time.

Five environmental variables were used: depth (m), bottom temperature (°C), salinity, seabed stress (N.m<sup>-2</sup>) and sediment type. Depth, bottom temperature and salinity were measured at each trawl location from 1980 to 2007. Seabed stress is a measure of water shear friction on the seabed due to the tidal current and is provided by the Proudman Oceanographic Laboratory (POL, Aldridge and Davies, 1993). Sediment type is taken from the MARGIS project seafloor sediment of the North Sea (Schlüter and Jerosch, 2008). Sediment classification was aggregated into five classes: fine sand, coarse sand, mud, pebbles and gravel. A value of seabed stress and a class of sediment were allocated to each trawl by resampling corresponding maps at trawl location using ArcMap's Hawth's Analysis Tools extension (Beyer, 2004). Depth, seabed stress and

sediment type were grouped to represent persistent environment, whereas bottom temperature and salinity were grouped to represent non-persistent environment.

Control through spatial dependency between individuals was modelled using principal coordinates of neighbour matrices (PCNM). PCNM variables result from the diagonalized distance matrix and represent a spectral decomposition of the spatial relationships among the study sites. They produce orthogonal maps that maximise spatial auto-correlation patterns that may arise at different spatial scales within the sampling network. The PCNM variables resulting from a given sampling design are independent from any response variables observed by the mean of this sampling strategy. As such, they can be directly linked to the spatial patterns of the response distribution to evaluate which spatial scales and auto-correlation patterns are most relevant to the studied response. Extraction of the PCNM was achieved following the method of Borcard and Legendre (2002). A Euclidean distance matrix was built using latitude and corrected longitude (longitude cos((latitude p)/180) of the 9435 trawling stations. This distance matrix was then truncated by recoding all the distances above a particular threshold up to four times this threshold. The threshold was taken as the maximum distance between two neighboring stations in order to keep all the stations connected together. A principal coordinate analysis was then performed on this truncated distance matrix, leading to 9435 potential PCNM, from which only positive PCNM (eigenvectors with positive eigenvalues) were kept. Then, PCNM that described all the scales relevant to whiting distribution were selected, based on the method described by Blanchet et al. (2008). In order to remove the significant spatial trend that cannot be modelled using PCNM, log-transformed abundances were detrended prior to selection using a quadratic trend based on latitudinal and corrected longitudinal coordinates of the trawling stations, as prescribed by Borcard and Legendre (2002).

### **Fisheries Oceanography**

PCNM were then selected from these detrended log-transformed abundances and a global test including all the positive PCNM was performed to model the biological response. As this test was significant, the analysis was carried on to the next step which consisted in the forward selection. The significance of each PCNM was assessed using a 999 Monte Carlo permutations test and, according to a p-value and the adjusted- $r^2$ (explained variance) of the model calculated with all the PCNM. PCNM were tested successively and the selection procedure stopped if the newly added PCNM was not significant at the chosen p-value threshold or, if it made the adjusted- $r^2$  of the whole model increase more than the value calculated for the model with all the PCNM. Spatial scale of the selected PCNM was determined following the method outlined in Bellier et al. (2007). A Gaussian model, used as a theoretical variogram, was fitted to each spatial predictor to determine their range, which represents the spatial scale described by each PCNM. PCNM describing similar spatial scale were grouped together by plotting their eigenvalue against their range. Finally, three scales corresponding to three spatial submodels were determined and used as distinct hypotheses of control (see Loots et al., 2010 for more details).

Age structure control was expressed as the relative proportions of each cohort (1 to 5 year olds) for the whole area (annual demography) and for each trawling station (spatial demography). Estimations of annual abundances for the five cohorts are available since 1980 (ICES, 2008). Proportions of each cohort at each trawling station were calculated from the 1980 to 2007 biometric data of the International Bottom Trawl Surveys.

Population size was expressed using the spawning stock biomass (SSB) and the 210 total size of the population provided since 1980 (ICES, 2008, Fig. 3). Although some discrepancies between stock assessments using Extended Survivors Analysis (XSA) and

those using survey indices have been identified before 1990 (ICES, 2009), the XSAbased SSB and total population size are considered to be the best estimates, as they are based on all available sources of data during the time-period considered and over the whole distribution area of this species.

The ICES statistical rectangles were used as a categorical variable to represent the geographical location. Memory of the population was expressed using the observed abundance of spawning adults in the previous year. For trawling positions with no observation in the previous year, the observed abundance of the closest location was used. This reduced the total available number of trawling stations from 9435 to 8098 for the 1981 to 2007 period.

#### Model structures

Generalised additive models (GAM, Hastie and Tibshirani, 1990; Guisan et al., 2002; Wood and Augustin, 2002) were used to construct the models (Loots et al., 2010). The modelling procedure was split into two steps: a binomial model with a logit link was built on presence-absence (where positive abundances are recoded as 1) and a Gaussian model with an identity link was constructed for non-null log-transformed abundances (Stefánsson, 1996; Le Pape et al., 2003). This modelling design allows for the appropriate handling of zero-inflated log-normal distribution, and also permits the investigation and distinction between factors that control the geographical extent of the distribution from those that control the geographical patterns of abundance (Koubbi et al., 2006; Loots et al., 2010). For the binomial model, the following hypotheses of control were tested: geography, persistent and non-persistent environment, the three spatial sub-models, annual demography, population size and memory. For the Gaussian model, the spatial demography was also added.

## Model adjustment and prediction

In order to study the impact of the size of the prediction dataset on model complexity, years of the calibration and prediction datasets were chosen to retain a larger prediction dataset as advised by Loots *et al.* (2010). Also, the prediction dataset 240 was constrained to be within the environmental and biological range covered by observations in the calibration data (Table 1). Nine years (1986-1989 and 2003-2007) were used for the calibration dataset, which corresponds to 2943 and 2753 stations used for fitting the binomial and Gaussian models. The remaining 18 years (1981-1985 and 1990-2002) were used for the prediction dataset, which represents 4150 stations used for the binomial model and 3894 for the Gaussian model. Degrees of smoothing were adjusted simultaneously on the corresponding fitting period for all the variables of the same hypothesis (Table 2). Finally, for each class of model (either binomial or Gaussian), all the combinations of the hypotheses were calculated resulting in  $2^n$ -1 candidate models (with *n*, the number of hypotheses).

#### Model selection procedures

Models were selected for their ability to fit and predict the spatial distribution of whiting. Models were ranked based on their goodness of fit using Akaike Information Criterion (AIC, Akaike, 1974) and AIC difference ( $\Delta_i$ , Burnham and Anderson, 2002; Johnson and Omland, 2004). The best model among all candidates is the one with the lowest AIC value (i.e. the model with the best compromise between adjustment to observed data and parsimony in the number of explanatory variables). Other models were compared to this best model by calculating the  $\Delta_i$  (i.e. the difference of AIC between the best model and each model). Loots *et al.* (2010) indicated that the 260 conventional threshold value of 10 for  $\Delta_i$ , advised by Burnham and Anderson (2002), was too restrictive. Here, we use a range of threshold values from 0 to 60 as the criteria for stopping the selection and the comparison of results was used to study the influence of the selection threshold on model complexity.

Models were also compared for their predictive abilities, using the log-likelihood 265 between observations and predictions (McCullagh and Nelder, 1989; Burnham and Anderson, 2002). The best model is the one with the highest log-likelihood value. Other models were compared to it using a likelihood ratio test (LRT, Burnham and Anderson, 2002). Models were ranked according to their LRT from smallest to largest. The same selection threshold of 60 (as for  $\Delta_i$ ) was used in order to keep only a reduced set of 270 selected models. Details on calculation of the AIC,  $\Delta_i$ , log-likelihood and likelihood ratio test can be found in the references above and in Loots *et al.* (2010).

#### Model evaluation

Binomial and Gaussian models selected based on the likelihood ratio test were 275 re-applied on the 3894 stations of the prediction dataset that were used to fit Gaussian models. Predicted probabilities of presence and log-transformed abundances were then combined in a delta approach. The delta approach consists of multiplying predicted probabilities of presence by predicted abundances (conditional on presence) at each location in order to derive the predicted spatial distribution (Stefánsson, 1996; Le Pape *et al.*, 2003). This resulted in several predicted distributions that were compared to the observed distribution using a Taylor diagram (Taylor, 2001).

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## RESULTS

## PCNM extraction and spatial sub-models

Principal Coordinates of Neighbour Matrices were used to depict spatial
dependency in the spatial distribution of North Sea whiting spawning adults. A threshold of 1.13 (decimal degrees of latitude) was used to truncate the distance matrix between stations. Overall, 3832 positive PCNM were extracted from the principal coordinate analysis and 22 were determined as significant by the forward selection (p-value ≤ 0.001, adjusted R<sup>2</sup> ≥ 0.003). Three sub-models representing three spatial scales
were determined (Fig. 4): broad scale (166-355 km), medium scale (55-166 km) and fine scale (< 55 km). Three PCNM accounted for the broad scale, ten for the medium scale and nine for the fine scale.</li>

## Complexity of models selected

On the basis of the hypotheses tested, 512 binomial and 1024 Gaussian models
were constructed, evaluated and ranked. Using a limit threshold of selection of 60 for Δ<sub>i</sub> and LRT, a total number of 320 models were finally retained. Selected models varied according to the selection procedure and retained hypotheses varied with the type of model (binomial or Gaussian). Selected models based on data fitting performances were on average more complex, in terms of number of hypotheses and explanatory variables
they contained, than models selected on predictive capabilities (Fig. 5). Selected Gaussian models were also more complex than selected binomial models (Fig. 5).

Complexity of the selected models varied with the selection threshold (Fig. 5). In binomial models selected on the basis of fitting performances ( $\Delta_i < 60$ ), the number of hypotheses and explanatory variables contained decrease as the selection threshold increased. This was not the case for binomial models selected based on prediction performances (LRT < 60). Selected models with lower LRT value (0-20) contained fewer hypotheses and explanatory variables than models with higher LRT values (20-60). Selected Gaussian models based on fitting contained a similar number of hypotheses and explanatory variables, independently of the threshold considered. This was not the case for models selected on the basis of prediction. Models with low LRT values (0-30) contained fewer hypotheses and explanatory variables than models with higher LRT values (30-60).

# Frequency of the hypotheses

Frequencies of each control hypothesis were calculated from the 24 binomial and 17 Gaussian models retained in the selection procedure based on predictive performances (Table 3). Frequencies of the various hypotheses differ between binomial and Gaussian models and vary with the value of the selection threshold (Table 4).

For binomial models, three hypotheses dominate regardless of the threshold value: non-persistent environment, medium spatial scale and population memory. Control by population size is seen in models with LRT values between 10 and 20. The number of hypotheses shifts from four to six in models with a LRT value between 20 and 40, with persistent environment and broad scale sub-model as supplementary hypotheses. Control by fine spatial scale is not frequent and only present in models with a LRT value between 50 and 60. Geography and annual demography are not present in selected models.

For Gaussian models, six hypotheses dominate in models regardless of the selection threshold value: geographical attachment, permanent and non-persistent environment, population size, spatial demography and population memory. Persistent and non-persistent environment are less frequent in models with LRT values between 20 and 60. The three scale sub-models are not present in models with LRT values

## **Fisheries Oceanography**

between 0-10, whereas they become increasingly frequent in models with higher LRT values. Annual demography is never retained in the selected models.

# Evaluation of delta models

The 17 binomial and 24 Gaussian selected models (Table 3) were combined in a 335 delta approach, resulting in 408 predictions. These predictions were evaluated using the Taylor diagram (Fig. 6). The Taylor diagram indicates that all the models have comparable values of Spearman correlation (close to 0.8), Root Mean Square Error (close to 0.6) and standard deviation (between 0.7 and 0.8).

This is confirmed by the maps of predicted distribution of spawning whiting,
illustrated for the years 1992 and 1998 (Fig. 7). These two years show similar pattern of distribution with higher abundances in the northern and southern parts of the North Sea. Abundances are lower for year 1998, especially in the southern part. For each year, predictions of the simplest and the most complex models among those selected (see Table 3 for formulae) have been mapped. Whereas these models do not have the same
LRT value or complexity, they are both able to depict the observed distribution for both years.

#### DISCUSSION

Based on a set of 28 years of biological and environmental data collected in the North Sea, the statistical modelling approach used in this study revealed the key mechanisms which are involved in the control of the geographical extent of spawning whiting and the spatial distribution of its abundance during the spawning season. We discuss below new and important insights on the technical aspects of the analysis as well as on the ecological implications of the results obtained.

## Selection based on prediction versus selection based on fitting

In this study, the prediction dataset was much larger than the calibration dataset and therefore potentially supports more variability and a higher number of autocorrelated data. Thus, we could have supposed that more complex models might have been selected from prediction than from fitting. However, this was clearly not the case as models selected on predictive performances were less complex on average than models selected from fitting. These results support those obtained by Loots et al. (2010). In their first attempt to perform multi-model selection, they built a calibration dataset larger than the prediction dataset and shown that selected models from prediction were less complex that those selected from fitting. The present study confirms that this was not due to the size of the datasets because in the present study the prediction dataset was larger and the models selected from prediction were still less complex compared to those selected from fitting. This is an important insight as it supports the principle that once processes that control the spatial distribution have been correctly identified through hypotheses selection, they will be able to depict the observed distribution whatever the complexity of the spatial pattern. The present study has shown that this feature could be better achieved using prediction-based selection 

#### **Fisheries Oceanography**

rather than fitting-based selection (see also discussion on this aspect in Planque *et al.*, 2010).

Consequently, we argue that the difference in complexity between models selected from fitting compared to those selected from prediction is not due to the size of the datasets, but to the principles underlying the calculation of the AIC, as argued in Planque *et al.* (2010). The AIC is designed to favour models with high data fitting performance whilst penalizing models of high complexity. In the presence of autocorrelated data, the amount of data is much greater than the number of true independent observations, and the AIC is heavily skewed towards favouring fitting performance rather than model parsimony. In such situation the use of the AIC can lead to the selection of overfitted and more complex models, as is observed from the current data.

This problem is absent when testing performances using the LRT on predictions because the selection criteria is independent from the true number of independent observations in the fitting dataset. Based on the results of Loots et al. (2010) and the present study, it appears that spatial autocorrelation acts as a statistical nuisance when model selection is based on data fitting (using AIC) and it should be recommended that model selection be based on prediction as a more robust method to infer the role of the various hypotheses.

## 390 Impact of a the selection threshold

We chose a wide range of LRT threshold values to evaluate how these can affect model selection and hypotheses inference. Unexpectedly, evaluation of delta models has revealed that all the predictions have similar correlation with the observations and depict the same associated error (Taylor diagram in Fig. 6). This highlights that all selected models can predict the main patterns of observed spatial distributions with

relatively similar skills, even though they may have different quantitative performances, as revealed by LRT values.

Although the selected models display similar predictive skills, they can have different levels of complexity and include different sets of hypotheses. In the selection process based on prediction, simple models were selected first and hypotheses that were determined as the most important (i.e. the most frequent) in these first selected models remained the most important in following models. Therefore, considering a large number of models does not lead to undermining of the most important hypotheses, but it may lead to attributing too much importance to secondary hypotheses.

One may wonder which value of selection threshold should be chosen. For the binomial models of this study, the simplest model was in the set of models that have a LRT lower than 10. In this case, restricting the selection threshold to 10 allows for the selection of a model with a small number of underlying hypotheses which is also the best model. For Gaussian models, the simplest model is not within models with an LRT value of 10 or less and restricting the selection threshold to 10 led to the exclusion of a simple model which has a predictive power similar to more complex ones. This reveals that choosing a too restrictive selection threshold, even with prediction based selection, can restrict the choice to models that are too complex, whereas simple models, that are not automatically within the threshold of 10 (as advised by Burnham and Anderson, 2002), may have similar predictive performances. Therefore, the present study demonstrates that model ranking should not be considered as the only criterion for model selection when using biological data. Rather, it can be used as a first step to evaluate and compare a selection of models. Once the various models have been ranked, models of equivalent predictive power should be examined.

 420 Control of the spatial distribution of whiting

In our study, a selection threshold of 10 for binomial models and 20 for Gaussian models appears to be appropriate to evaluate the relevance of the different hypotheses. Selected binomial models were clearly different from selected Gaussian models. The results reveal that the geographical extent of the spawning population and geographical distribution of abundance are not controlled by the same processes. The geographical extent of the population (i.e. distribution of areas of presence-absence) is controlled by non-persistent environment and population memory. Within this, the distribution of high abundances of spawning whiting is influenced by geographical attachment, population size, age structure and population memory. Ecologically, this 430 reveals that the level of abundance of whiting in an area is determined by a more complex association of factors than is the geographical spread of the population. This was also observed for plaice (*Pleuronectes platessa*) in the North Sea by Loots *et al.* (2010).

The importance of the memory hypothesis shows that the areas of presenceabsence tend to be maintained in time as the presence-absence of whiting for one year is highly related to that of the previous year. Whereas the importance of the memory hypothesis reveals a high conservatism in spawning migrations, Zheng et al. (2001, 2002) argued that the spatial pattern of sea surface temperature has an important influence on the spatial distribution of whiting, in particular during winter and spring.
Although our study can not rule out the effects of temperature of whiting distribution at the time of spawning, it appears that such effects are likely minor because whiting has a wide area of presence and few areas of absence (only 6% of zeros) in the North Sea.

The relevance of the memory hypothesis as well as the geographical attachment highlights a strong persistence of whiting distribution and abundance from year to year.

445 Such persistence may reflect population strategy which can ensure life cycle closure, despite unpredictable variations in the environmental conditions from year-to-year. Such mechanism creates a time lag between environmental changes and changes in the spatial distribution of a species which allows endurance of exceptional environmental conditions (Corten, 2002). In the short term, this can result in poor recruitment in a specific year because eggs and larvae may not be released in optimal conditions for their survival. On the other hand, such strategy may ensure good average recruitment over decadal time scales.
Our results indicate that temporal variations in abundance may be influenced by

the size and age structure of the population. The overall declining trend in population
size seemed to better match the apparent contraction of whiting distribution in recent
years, which probably contributed to the importance of this control factor in explaining
whiting spatial distribution in the present study. Control through population size
suggests a density dependent effect where the spatial extent of areas of high
concentrations of spawning adults may vary in relation to population abundance. In
addition, our results indicate segregation between young individuals, that are mainly
distributed in shallow areas, and old individuals distributed in deeper areas (Zheng *et al.*, 2001). This age-dependent segregation pattern is important to explain and predict
the spatial distribution of abundance of spawning whiting, in particular in the face of
changes in the population age-structure.

 In summary, although environmental factors such as temperature and salinity may play a role in the location and extent of whiting distribution, year-to-year persistence in the spatial distribution allows North Sea whiting to buffer for short term environmental variations. Therefore, as long as changes in present environmental conditions remain within the fundamental niche of whiting, it should be expected that

#### **Fisheries Oceanography**

470 the geographical configuration of spawning areas will vary little. This may not be the case if future ocean climate changes beyond the niche range of whiting. Numerical simulations of future climate (coupled with the selected models) will be necessary to assess the impact of such changes on whiting spawning distribution. However, this may remain a difficult challenge, if the environmental and biological ranges encompassed by scenarios are not within those of the calibration dataset, the model will extrapolate so that the predictions will be poorly reliable.

Inside the areas of presence, the areas of high abundances are also persistent in time. Variations in their extent are no longer determined by the environment, but rather by internal population controls, mainly population size and demography. A high level of abundance as well as a higher diversity in the age structure of the population result in wider spatial coverage of the spawning population. When such a situation occurs, eggs and larvae are released over a wide range of environmental conditions, which can then limit the risk of recruitment failure. Within this context, the loss of a part of the population abundance as well as the truncation of the age pyramid due to fishing mortality can strongly reduce the spatial coverage of spawning, thereby increasing the risk of recruitment failure caused by poor environmental conditions.

# CONCLUSION

The present study concludes that model selection based on data fitting performances - as still commonly practised in fisheries and marine ecology studies -490 leads to selection of overly complex and overfitted models. Instead, prediction-based selection provides a valuable way for model selection and hypothesis inference and should be recommended over fitting or cross validation based selection.

The multi-model approach developed in this study reveals that a large amount of model uncertainty exists, due to the difficulty of selecting an appropriate final set of models that may differ in their complexity and hypotheses involved, but that share similar predictive performance. We contend that a range of models, supported by different hypotheses, can be selected as good candidates to explain and predict the spatial distribution of spawning whiting. These results support the idea that accounting for only one or two hypotheses and considering only one (best) model, as it is commonly performed, may lead to erroneous conclusions in understanding the distribution of fish population and predicting it under different climatic or biological change scenarios.

Despite such uncertainty, the selected models revealed that whiting distribution is primarily controlled by population memory and geographical attachment, leading to the conservation of spatial distribution over years, whilst variations are mainly due to population size and demography. Recent fluctuations in environmental conditions seem to play a minor role.

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## FIGURES

Figure 1: The North Sea International Bottom Trawl Surveys. Black dots indicate trawl stations of the first quarter (January-March) from 1980 to 2007, for which the abundance of spawning adult North Sea whiting is given. Countries involved in the surveys, ICES statistical rectangles, standard roundfish areas and main locations are also indicated.

Figure 2: Proportions of adult stage 3 (spawning adults) North Sea whiting per size class, for the seven standard roundfish areas. The datapoints represent the proportions observed, and the lines the adjusted proportions using a smoothing spline for missing size classes.

Figure 3: ICES estimation (ICES Working Group) of North Sea whiting population size (thousands of fish) and spawning stock biomass ('000 t) from 1980 to 2007.

Figure 4: PCNM spatial sub-models. Left, plot of the range values of the 22 selected PCNMs against their eigenvalue. Broad scale, eigenvectors with a range between 166 km and 355 (1.5-3.2 decimal degrees of latitude); medium scale, eigenvectors with a range between 55 km and 166 km (0.5-1.5 decimal degrees of latitude); fine scale, eigenvectors with a range between 0 and 55 km (<0.5 decimal degrees of latitude).</li>
Right, maps of the spatial sub-models (arbitrary unit) giving the scale of aggregation of spawning North Sea whiting. Top, broad scale sub-models; center, medium scale sub-models; right, fine scale sub-models. Black lines denote zero values for PCNM.

Figure 5: Complexity of selected binomial and Gaussian models. Complexity is represented by the mean number of hypotheses and explanatory variables within selected models. They are given according to the selection procedure and for different value of selection threshold for  $\Delta_i$  and LRT between 0 and 60.

## **Fisheries Oceanography**

Figure 6: Plot of the Taylor diagram. Only the part representing a positive correlation is shown. Predictions of delta models (triangle) are compared to the observations using the standard deviation, the root mean square error (RMSE) and the Spearman correlation.
Observations are symbolized as a point referred to as the reference point and are normalized so that the standard deviation is equal to 1, the correlation equal to 1 (the correlation between the observations and themselves) and the RMSE equal to 0 (the difference between the observations and themselves). Values of the indices for the predictions are plotted with the standard deviation on the y-axis, the correlation on the radii of the circle and the RMSE on concentric circles around the reference point.

Figure 7: Maps of spawning adult whiting. Maps for the most simple and complex models among those selected (see Table 3 for formulae of the models) were computed for years 1992 and 1998. The corresponding maps of the observed distribution of spawning adults for the same two years are also shown.

# TABLES

**Table 1.** Environmental and biological ranges encompassed by the calibration and the prediction datasets for building the binomial and the Gaussian models.

Table 2. The formulae for the hypotheses. The explanatory variables for each
hypothesis for the binomial and the Gaussian models were fitted on the calibration
dataset. An s means that a smoothing function has been used and the corresponding
degree of smoothing is indicated in parentheses. PCNM are denoted by the term Ax.
Hypotheses: Geo. Att., geographical attachment; Pers. Envt., persistent environment; N.
Pers. Envt., non-persistent environment; Br. Sc., broad scale sub-model, Med. Sc.,
medium scale sub-model; Fine Sc., fine scale sub-model; Pop. Size , population size;
Ann. Dem., annual demography; Spa. Dem., spatial demography; Pop. Mem.,
population memory.

Table 3. The formulae for the models selected from the prediction. The best model is the one with a value of LRT of 0. Values of Δ<sub>i</sub> are also given. Formulae of the simplest
(1) and the most complex (2) delta models used for figure 7 are indicated. Hypotheses: Geo. Att., geographical attachment; Pers. Envt., persistent environment; N. Pers. Envt., non-persistent environment; Br. Sc., broad scale sub-model; Med. Sc., medium scale sub-model; Fine Sc., fine scale sub-model; Pop. Size, population size; Spa. Dem., spatial demography; Pop. Mem., population memory.

**Table 4.** Frequencies of the different hypotheses, giving the percentage of the model selected from prediction in which each hypothesis is present, for different threshold of selection. Recoding was according to five levels: 0 (absence), + (<25%), ++ (25-50%), +++ (50-75%), ++++ (75-100%). Hypotheses: Geo. Att., geographical attachment; Pers. Envt., persistent environment; N. Pers. Envt., non-persistent environment; Br. Sc., broad scale sub-model; Med. Sc., medium scale sub-model; Fine Sc., fine scale sub-model;</li>

Pop. Size, population size; Ann. Dem., annual demography; Spa. Dem., spatial demography; Pop. Mem., population memory.



Figure 1: The North Sea International Bottom Trawl Surveys. Black dots indicate trawl stations of the first quarter (January-March) from 1980 to 2007, for which the abundance of spawning adult North Sea whiting is given. Countries involved in the surveys, ICES statistical rectangles, standard roundfish areas and main locations are also indicated.

79x62mm (300 x 300 DPI)

Page 35 of 45



Figure 2: Proportions of adult stage 3 (spawning adults) North Sea whiting per size class, for the seven standard roundfish areas. The datapoints represent the proportions observed, and the lines the adjusted proportions using a smoothing spline for missing size classes. 160x80mm (600 x 600 DPI)



Figure 3: ICES estimation (ICES Working Group) of North Sea whiting population size (thousands of fish) and spawning stock biomass ('000 t) from 1980 to 2007. 74x74mm (600 x 600 DPI)



Figure 4: PCNM spatial sub-models. Left, plot of the range values of the 22 selected PCNMs against their eigenvalue. Broad scale, eigenvectors with a range between 166 km and 355 (1.5-3.2 decimal degrees of latitude); medium scale, eigenvectors with a range between 55 km and 166 km (0.5-1.5 decimal degrees of latitude); fine scale, eigenvectors with a range between 0 and 55 km (<0.5 decimal degrees of latitude). Right, maps of the spatial sub-models (arbitrary unit) giving the scale of aggregation of spawning North Sea whiting. Top, broad scale sub-models; center, medium scale sub-models; right, fine scale sub-models. Black lines denote zero values for PCNM.

156x103mm (600 x 600 DPI)





Figure 5: Complexity of selected binomial and Gaussian models. Complexity is represented by the mean number of hypotheses and explanatory variables within selected models. They are given according to the selection procedure and for different value of selection threshold for and LRT between 0 and 60. 160x80mm (600 x 600 DPI)





Figure 6: Plot of the Taylor diagram. Only the part representing a positive correlation is shown.

Predictions of delta models (triangle) are compared to the observations using the standard deviation, the root mean square error (RMSE) and the Spearman correlation. Observations are symbolized as a point referred to as the reference point and are normalized so that the standard deviation is equal to 1, the correlation equal to 1 (the correlation between the observations and themselves) and the RMSE equal to 0 (the difference between the observations and themselves). Values of the indices for the predictions are plotted with the standard deviation on the y-axis, the correlation on the radii of the circle and the RMSE on concentric circles around the reference point. 80x80mm (600 x 600 DPI)



Figure 7: Maps of spawning adult whiting. Maps for the most simple and complex models among those selected (see Table 3 for formulae of the models) were computed for years 1992 and 1998. The corresponding maps of the observed distribution of spawning adults for the same two years are also shown.

160x84mm (300 x 300 DPI)

Bin Min	omial	Car				Prediction dataset				
Min		Binomial Gaussian			omial	Gaussian				
171111	Max	Min	Max	Min	Max	Min	Max			
10	195	10	195	10	194	10	194			
-1.4	9.8	-1.4	9.8	-1.2	9.7	-0.8	9.7			
26	35.4	26	35.4	26.8	35.4	26.8	35.4			
0	2.8	0	2.8	0	2.8	0	2.8			
78,045	299,684	78,045	599,684	139,540	276,842	139,540	276,842			
549,997	5,661,687	549,997	5,661,687	1,465,866	3,624,792	1,465,866	3,624,792			
32.04	77.8	32	77.8	49.4	72.3	49.4	72.3			
10.97	31	10.9	31	15	27.5	15	27.5			
5.18	19.1	5.1	19.1	5.5	17.2	5.5	17.2			
1.53	13.3	1.5	13.3	1.9	7.6	1.9	7.6			
0.35	8.6	0.3	8.6	0.7	2.9	0.7	2.9			
	10 -1.4 26 0 78,045 549,997 32.04 10.97 5.18 1.53 0.35	10       195         -1.4       9.8         26       35.4         0       2.8         78,045       299,684         549,997       5,661,687         32.04       77.8         10.97       31         5.18       19.1         1.53       13.3         0.35       8.6	1019510-1.49.8-1.42635.42602.8078,045299,68478,045549,9975,661,687549,99732.0477.83210.973110.95.1819.15.11.5313.31.50.358.60.3	1019510195-1.49.8-1.49.82635.42635.402.802.878,045299,68478,045599,684549,9975,661,687549,9975,661,68732.0477.83277.810.973110.9315.1819.15.119.11.5313.31.513.30.358.60.38.6	10 $195$ $10$ $195$ $10$ $-1.4$ $9.8$ $-1.2$ $26$ $35.4$ $26$ $0$ $2.8$ $0$ $2.8$ $0$ $2.8$ $0$ $2.8$ $0$ $78,045$ $299,684$ $78,045$ $599,684$ $549,997$ $5,661,687$ $549,997$ $5,661,687$ $32.04$ $77.8$ $32$ $77.8$ $49.4$ $10.97$ $31$ $10.9$ $31$ $15$ $5.18$ $19.1$ $5.1$ $19.1$ $5.5$ $1.53$ $13.3$ $1.5$ $13.3$ $1.9$ $0.35$ $8.6$ $0.3$ $8.6$ $0.7$	101951019510194-1.49.8-1.49.8-1.29.72635.42635.426.835.402.802.802.878,045299,68478,045599,684139,540276,842549,9975,661,687549,9975,661,6871,465,8663,624,79232.0477.83277.849.472.310.973110.9311527.55.1819.15.119.15.517.21.5313.31.513.31.97.60.358.60.38.60.72.9	10 $195$ $10$ $195$ $10$ $194$ $10$ $-1.4$ $9.8$ $-1.2$ $9.7$ $-0.8$ $26$ $35.4$ $26$ $35.4$ $26.8$ $35.4$ $26.8$ $0$ $2.8$ $0$ $2.8$ $0$ $2.8$ $0$ $78,045$ $299,684$ $78,045$ $599,684$ $139,540$ $276,842$ $139,540$ $549,997$ $5,661,687$ $549,997$ $5,661,687$ $1,465,866$ $3,624,792$ $1,465,866$ $32.04$ $77.8$ $32$ $77.8$ $49.4$ $72.3$ $49.4$ $10.97$ $31$ $10.9$ $31$ $15$ $27.5$ $15$ $5.18$ $19.1$ $5.1$ $19.1$ $5.5$ $17.2$ $5.5$ $1.53$ $13.3$ $1.5$ $13.3$ $1.9$ $7.6$ $1.9$ $0.35$ $8.6$ $0.3$ $8.6$ $0.7$ $2.9$ $0.7$			

Hypotheses	Binomial models	Gaussian models
Geo. Att	as.factor(StatisticalRectangle)	as.factor(StatisticalRectangle)
N. Pers. Envt.	s(Depth, 4) + s(Bedstress, 4) + as.factor(Sediments)	s(Depth, 4) + s(Bedstress, 4) + as.factor(Sediments)
Pers. Envt.	Temperature + s(Salinity, 3)	s(Temperature, 4) + s(Salinity, 4)
Br. Sc.	s(Ax1, 3) + s(Ax2, 4) + s(Ax4, 4)	s(Ax1, 4) + s(Ax2, 4) + s(Ax4, 4),
Med. Sc.	Ax11 + s(Ax13, 2) + Ax14 + s(Ax16, 4) + s(Ax18, 3) + Ax20 + Ax21 + Ax25 + s(Ax26, 3) + s(Ax28, 1)	s(Ax11, 4) + s(Ax13, 4) + s(Ax14, 4) + s(Ax16, 4) + s(Ax18, 4) + Ax20 + s(Ax21, 4) + s(Ax25, 4) + Ax26 + s(Ax28, 4)
Fine Sc.	s(Ax31, 4) + Ax33 + s(Ax36, 4) + s(Ax39, 1) + s(Ax54, 2) + Ax70 + s(Ax73, 1) + Ax104 + s(Ax110, 2)	s(Ax31, 4) + s(Ax33, 4) + s(Ax36, 3) + s(Ax39, 4) + s(Ax54, 4) + s(Ax70, 3) + s(Ax73, 4) + s(Ax104, 3) + s(Ax110, 4)
Pop. Size	PopulationSize + s(SpawningStockBiomass,1)	PopulationSize + s(SpawningStockBiomass, 4)
Ann. Dem.	s(Age1a, 4) + Age2a + Age3a + Age4a + Age5a	Age1a + Age2a + s(Age3a, 3) + s(Age4a, 4) + Age5a
Spa. Dem.	<u> </u>	s(Age1s, 2) + s(Age2s, 4) + s(Age3s, 1) + s(Age4s, 3) + s(Age5s, 4)
Pop. Mem.	s(PreviousYearAbundance, 2)	s(PreviousYearAbundance, 4)

Models	Formula								
	N. Pers. Envt. + Pop. Mem. (1)								
	N. Pers. Envt. + Med. Sc. + Pop. Mem.								
	N. Pers. Envt. + Pop. Size + Pop. Mem.								
	N. Pers. Envt. + Med. Sc. + Pop. Size + Pop. Mem.								
	N. Pers. Envt. + Br. Sc. + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Br. Sc. + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Med. Sc. + Pop. Mem.								
	N. Pers. Envt. + Br. Sc. + Pop. Size + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Br. Sc. + Med. Sc. + Pop. Mem.								
F	Pers. Envt. + N. Pers. Envt. + Br. Sc. + Pop. Size + Pop. Mem.								
mi	N. Pers. Envt. + Br. Sc. + Med. Sc. + Pop. Mem.								
ino	Pop. Mem.								
B	N. Pers. Envt. + Med. Sc.								
	Pers. Envt. + N. Pers. Envt. + Pop. Size + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Med. Sc. + Pop. Size + Pop. Mem.								
	N. Pers. Envt. + Fine Sc. + Pop. Mem.								
	Pop. Size + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Br. Sc. + Med. Sc. + Pop. Size + Pop. Mem. (2)								
	N. Pers. Envt. + Br. Sc. + Med. Sc. + Pop. Size + Pop. Mem.								
	Med. Sc. + Pop. Mem.								
	Pers. Envt. + Br. Sc. + Pop. Mem.								
	N. Pers. Envt. + Med. Sc. + Fine Sc. + Pop. Mem.								
	N. Pers. Envt.								
	Geo. Att. + Pers. Envt. + N. Pers. Envt. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Pop. Size + Spa. Dem. + Pop. Mem. (1)								
	Pers. Envt. + N. Pers. Envt. + Med. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Pers. Envt. + N. Pers. Envt. + Br. Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Pers. Envt. + N. Pers. Envt. + Med. Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Br. Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
sian	Geo. Att. + Med. Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
ssm	Geo. Att. + Pers. Envt. + N. Pers. Envt. + Br. Sc. + Med. Sc. + Pop. Size + Pop. Mem.								
Ga	Geo. Att. + Br. Sc. + Med. Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Br. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Pers. Envt. + N. Pers. Envt. + Br. Sc. + Med. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem. (2)								
	Geo. Att. + N. Pers. Envt. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Med. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Br. Sc. + Med. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo. Att. + Pers. Envt. + N. Pers. Envt. + Med. Sc. + Fine Sc. + Pop. Size + Spa. Dem. + Pop. Mem.								
	Geo Att + N Pers Envt + Br Sc + Pon Size + Sna Dem + Pon Mem								

#### **Fisheries Oceanography**

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54.34 9.21 10.10

17.54 46.96

27.54 5.71

31.27 12.41

33.82 17.46

38.51 36.80

38.90 10.02

42.65 9.87

44.40 11.39

45.59 15.11

45.70 0.98

50.36 73.41

50.47 21.24

51.43 32.80

52.43 7.59

53.47 38.21 53.80 61.15 53.80 10.49

58.89 8.68

59.60 83.98

0 42.65 11.21 160.69 16.50 244.76

16.95 55.97 21.69 106.13 21.74 50.90 23.47 166.84 23.69 162.04

26.93 61.75 30.22 166.72 34.04 116.02 37.27 245.29

39.13 90.28 40.37 118.85

47.12 129.28

53.37 0.10

58.74 97.84

0 55.52 27.97 57.93 36.53

54.59

Binomial models								Gaussian models					
	[0-10[	[0-20[	[0-30[	[0-40[	[0-50[	[0-60[		[0-10[	[0-20[	[0-30[	[0-40[	[0-50[	[0-60
Geo. Att	0	0	0	0	0	0		++++	++++	++++	++++	++++	+++-
N. Pers. Envt.	++++	++++	++++	++++	++++	++++		++++	++++	+++	+++	++	+++
Pers. Envt.	0	0	0	++	++	++		++++	++++	+++	++	++	++
Br. Sc.	0	0	0	+	+++	++		0	+	++	++	++	++
Med. Sc.	+++	++	+++	++	++	++		0	+	++	++	++	++
Fine Sc.	0	0	0	0	0	+		0	+	+	++	++	++
Pop. Size	0	++	+++	+	++	++		++++	++++	++++	++++	++++	++++
Ann. Dem.	0	0	0	0	0	0		0	0	0	0	0	0
Spa. Dem.	-	-	-	-	-	-		++++	++++	++++	++++	++++	++++
Pop. Mem.	++++	++++	++++	++++	++++	++++		++++	++++	++++	++++	++++	++++