



Pattern formation in models of plankton dynamics. A synthesis

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Abstract – The history of modelling plankton dynamics is already quite long and has been initiated by fishery science in the early 20th century. The main aim of modelling population dynamics is to improve the understanding of the functioning of food chains and webs and their dependence on internal and external conditions. Hence, mathematical models of biological population dynamics have not only to account for growth and interactions but also for spatial processes like random or directed and joint or relative motion of species as well as the variability of the environment. Early attempts began with physicochemical diffusion, exponential growth and Lotka-Volterra type interactions. These approaches have been continuously refined to more realistic descriptions of the development of natural populations. The aim of this paper is to give an extensive introduction to the subject and the bibliography. The fascinating variety of spatio-temporal patterns in such systems and the governing mechanisms of their generation and further dynamics are described and related to plankton. © 2001 Ifremer/CNRS/IRD/Éditions scientifiques et médicales Elsevier SAS

Résumé – Mode de formation des modèles de dynamique planctonique. Une synthèse. L'histoire de la modélisation de la dynamique du plancton est déjà plutôt longue puisqu'elle a débuté au début du 20^e siècle avec les études sur les pêches. L'axe de cette modélisation est d'améliorer la compréhension du fonctionnement du réseau trophique et de ses relations avec les facteurs externes et internes. Aussi, les modèles mathématiques de dynamique des populations doivent non seulement tenir compte des déplacements des espèces au hasard ou dirigés, relatifs ou combinés ainsi que de la variabilité de l'environnement. Les premiers essais débutèrent avec la diffusion physico-chimique, la croissance exponentielle et les interactions de type Lotka-Volterra. Ces approches ont été régulièrement affinées vers des descriptions plus réalistes du développement des populations naturelles. L'objectif de cet article est d'introduire ce sujet et la bibliographie afférente. La variété infinie des schémas spatio-temporels dans de tels systèmes et les mécanismes directs de leur naissance ainsi que les futures dynamiques sont décrits et reliés au plancton. © 2001 Ifremer/CNRS/IRD/Éditions scientifiques et médicales Elsevier SAS

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1. INTRODUCTION

The exploration of pattern formation mechanisms in non-linear complex systems is one of the central problems of natural, social, and technological sciences. The development of the theory of self-organized temporal, spatial or functional structuring of non-linear systems far from equilibrium has been one of the milestones of structure research (Haken, 1977; Nicolis and Prigogine, 1977). The occurrence of multiple steady states and transitions from one to another after critical fluctuations, the phenomena of excitability, oscillations, waves and, in general, the emergence of macroscopic order from microscopic interactions in various non-linear non-equilibrium systems in nature and society has required and stimulated many theoretical and, if possible, experimental studies. Mathematical modelling has turned out to be one of the useful methods to improve the understanding of such structure generating mechanisms.

2. PLANKTON AND MODELS OF PLANKTON DYNAMICS: OVERVIEW

In the 17th century, the Dutch pioneer microscopist Anton van Leeuwenhoek was probably the first human being to see minute creatures, which he called *animalcules*, in pond water (Hallegraeff, 1988). The German Victor Hensen who organized Germany's first big oceanographic expedition in 1889 (Hensen, 1892; Porep, 1970) introduced the term plankton (from the Greek *planktos* meaning made to wander).

Phytoplankton are microscopic plants that drive all marine ecological communities and the life within them. Due to their photosynthetic growth, the world's phytoplankton generate half of the oxygen that mankind needs for maintaining life and it absorbs half of the carbon dioxide that may be contributing to global warming. It is not only oxygen and carbon dioxide but also other substances and gases that are recycled by phytoplankton, e.g. phosphorus, nitrogen and sulphur compounds (Bain, 1968; Ritschard, 1992; Duinker and Wefer, 1994; Malin, 1997). Hence, phytoplankton are one of the main factors controlling the further development of the world's climate and there is a vast literature supporting that (cf. Charlson et al., 1987, Williamson and Gribbin, 1991).

Zooplankton are the animals in plankton. In marine zooplankton, both herbivores and predators occur; herbivores graze on phytoplankton and are eaten by zooplankton predators. Together, phyto- and zooplankton form the basis for all food chains and webs in the sea. In its turn, the abundance of the plankton species is affected by a number of environmental factors such as water temperature, salinity, sunlight intensity, biogen availability etc. (Raymont, 1980; Sommer, 1994). Temporal variability of the species composition is caused by seasonal changes and trophical prey-predator interactions between phyto- and zooplankton. The latter have first been introduced by Lotka (1925) and Volterra (1926).

Because of its apparent importance, the dynamics of plankton systems have been under continuous investigation during more than a hundred years. It should be noted that, practically from the very beginning, regular plankton studies have combined field observations, laboratory experiments and mathematical modelling. It was in the 19th century that fisheries stimulated the interest in plankton dynamics because strong positive correlations between zooplankton and fish abundance were found. The already mentioned German plankton expedition of 1889 was mainly motivated by fisheries interests. At the same time, fishery science began to develop. In the beginning of the 20th century, the first mathematical models were developed in order to understand and to predict fish stock dynamics and its correlations with biological and physical factors and human interventions (cf. Cushing, 1975; Gulland, 1977; Steele, 1977).

The contemporary mathematical modelling of phytoplankton productivity has its roots in the work of Fleming (1939), Ivlev (1945), Riley (1946), Odum (1956) and others. A review of the developments has been given by Droop (1983). Recently, a collection of the most frequently used models has been published (Behrenfeldt and Falkowski, 1997).

The control of phytoplankton blooming by zooplankton grazing has been modelled first by Fleming (Fleming, 1939), using a single ordinary differential equation for the temporal dynamics of phytoplankton biomass. Other approaches have been the construction of data-fitted functions (Riley, 1946, 1963) and the application of standard Lotka-Volterra equations to describe the prey-predator relation of phytoplankton and zooplankton (Segel and Jackson, 1972; Dubois, 1975; Levin and Segel,

1976; Vinogradov and Menshutkin, 1977; Mimura and Murray, 1978). More realistic descriptions of zooplankton grazing with functional responses to phytoplankton abundance have been introduced by Ivlev (1945) with a certain modification by Mayzaud and Poulet (1978). Holling-type response terms (Holling, 1959) which are also known from Monod or Michaelis-Menten saturation models of enzyme kinetics (Michaelis and Menten, 1913; Monod and Jacob, 1961) are just as much in use (cf. Steele and Henderson, 1981, 1992a, 1992b; Scheffer, 1991a, 1998; Malchow, 1993; Truscott and Brindley, 1994a, 1994b).

Observed temporal patterns are the well-known stable prey-predator oscillations as well as the oscillatory or monotonous relaxation to one of the possible multiple steady states. Excitable systems are of special interest because their long-lasting relaxation to the steady state after a supercritical external perturbation like a sudden temperature increase or nutrient inflow is very suitable to model red or brown tides (Beltrami, 1989, 1996; Truscott and Brindley, 1994a, 1994b).

Regarding the temporal variability of plankton species abundance, the limits of its predictability are of particular interest. At early stages, the development of mathematical models of marine ecosystems was driven by the idea that the more species were explicitly included into the model the higher would be its predictive ability. As a result, a number of many-species models appeared allowing for a detailed structure of the food web of the community (cf. DeAngelis, 1992; Jørgensen, 1994; Yodzis, 1994). However, the real predictive ability of this class of models is not very high and rarely exceeds a few weeks. Moreover, an increasing number of model agents may sometimes even worsen the properties of the model. This apparent paradox can be explained in terms of dynamical chaos (May, 1974). It should be noted that, although the strict evidence of chaotic behaviour of natural populations is still absent, stronger and stronger indications in favour of its existence are appearing (Scheffer, 1991b, 1998; Costantino et al., 1995, 1997; Dennis et al., 1995; Godfray and Hassell, 1997; Huisman and Weissing, 1999). Chaotic population dynamics essentially changes the approach to the system predictability (cf. Scheffer, 1991b), and makes conceptual few-species models of as much use as many-species ones. Moreover, few-species models can sometimes be even more instructive since they take into account only the principal features of the community functioning (cf. Pascual, 1993; Petrovskii and Malchow,

1999, 2001). Another interesting problem is the dynamics of externally forced systems. This ideally periodic forcing appears rather naturally due to daily, seasonal or annual cycles of photosynthetically active radiation, temperature, nutrient availability, etc. (Evans and Parslow, 1985; Truscott, 1995; Popova et al., 1997; Ryabchenko et al., 1997). Natural forcings are of course subject to a certain environmental noise. A number of forced models for parts or for the complete food chain (from nutrients, phytoplankton and zooplankton to planktivorous fish) have been investigated and many different routes to chaotic dynamics have been demonstrated (Kuznetsov et al., 1992; Asciti et al., 1993; Doveri et al., 1993; Rinaldi and Muratori, 1993; Rinaldi et al., 1993; Steffen and Malchow, 1996a, 1996b; Scheffer et al., 1997; Steffen et al., 1997).

The abundance of plankton species is not only subject to temporal changes but also depends on space. The distinct spatial heterogeneity of plankton distribution (patchiness) is found in many field observations (Steele, 1974, 1978; Fasham, 1978; Mackas and Boyd, 1979; Greene et al., 1992; Abbott, 1993). This phenomenon takes place on all scales, from centimetres to thousands of kilometres. A number of explanations has been suggested, particularly, relating the spatial structure of a plankton system to marine turbulence (Platt, 1972) or to the unhomogeneity of the temperature field in the ocean (Denman, 1976). A well-studied stripy plankton pattern is due to the trapping of populations of sinking microorganisms in Langmuir circulation cells (Stommel, 1948; Leibovich, 1993). Other physically determined plankton distributions such as steep density gradients due to local temperature differences, nutrient upwelling, turbulent mixing or internal waves have also been reported (Yoder et al., 1994; Franks, 1997; Abraham, 1998).

On a small spatial scale of some tens of centimetres and under relative physical uniformity, differences in the 'diffusive' mobility of individuals and the ability of locomotion might create finer spatial structures, e.g. due to bioconvection and gyrotaxis (Platt, 1961; Winet and Jahn, 1972; Pedley and Kessler, 1992; Timm and Okubo, 1994). Until now for certain bacteria but not for plankton, the mechanism of diffusion-limited aggregation (Witten and Sander, 1981) has been proposed and experimentally proven for the spatial fingering of colonies (Matsushita and Fujikawa, 1990; Ben-Jacob et al., 1992).

Thus, mathematical models of plankton population dynamics have not only to account for growth and interactions but also for spatial processes like random or directed and joint or relative motion of species as well as the variability of the environment. According to a widely accepted point of view, it is the interplay of phytoplankton and zooplankton growth, interactions and transport that yields the whole variety of spatio-temporal population structures, in particular the phenomenon of plankton patchiness (cf. Fasham, 1978; Okubo, 1980). The mathematical modelling requires the use of reaction-diffusion and perhaps advection equations. A good introduction to the latter field has been provided by Holmes et al. (1994).

Since the classic paper by Turing (1952) on the role of non-equilibrium reaction-diffusion patterns in biomorphogenesis, dissipative mechanisms of spontaneous spatial and spatio-temporal pattern formation in a homogeneous environment are of continuous interest in theoretical biology and ecology. Turing showed that the non-linear interaction of at least two agents with considerably different diffusion coefficients can give rise to spatial structure. Segel and Jackson (1972) were the first to apply Turing's idea to a problem in population dynamics: the dissipative instability in the prey-predator interaction of phytoplankton and herbivorous copepods with higher herbivore motility. Levin and Segel (1976) suggested this scenario of spatial pattern formation for a possible origin of planktonic patchiness. Recently, local bistability, predator-prey limit-cycle oscillations, plankton front propagation and the generation and drift of planktonic Turing patches were found in a minimal phytoplankton-zooplankton interaction model (Malchow, 1993, 1994) that was originally formulated by Scheffer (1991a), accounting for the effects of nutrients and planktivorous fish on alternative local equilibria of the plankton community.

Kierstead and Slobodkin (1953) and Skellam (1951) were perhaps the first to think of the critical size problem for plankton patches, presenting their nowadays called Kiss model with the coupling of exponential growth and diffusion of a single population. Of course, their patches are unstable because this coupling leads to an explosive spatial spread of the initial patch of species with surprisingly the same diffusive front speed as the asymptotic speed of a logistically growing population (Luther, 1906; Fisher, 1937; Kolmogorov et al., 1937).

Populations with an Allee effect (Allee, 1931; Allee et al., 1949), i.e. when the existence of a minimum viable number of species of a population yields two stable population states – extinction and survival – at its carrying capacity, show a spatial critical size as well (Schlöggl, 1972; Nitzan et al., 1974; Ebeling and Schimansky-Geier, 1980; Malchow and Schimansky-Geier, 1985; Lewis and Kareiva, 1993; Petrovskii, 1994). Population patches greater than the critical size will survive, the others will go extinct. However, bistability and the emergence of a critical spatial size do not necessarily require an Allee effect, and logistically growing preys with a parametrized predator of type II or III functional response can also exhibit two stable steady states and the related hysteresis loops (cf. Ludwig et al., 1978; Wissel, 1989).

The consideration of dynamic predation leads to the full spectrum of spatial and spatio-temporal patterns such as regular and irregular oscillations, propagating fronts, target patterns and spiral waves, pulses as well as stationary spatial patterns. Many of these structures were first known from oscillating chemical reactions (cf. Field and Burger, 1985), but have never been observed in natural plankton populations. However, spirals have been seen in the ocean as rotary motions of plankton patches on a kilometre scale (Wyatt, 1973). Furthermore, they have been found to be important in parasitoid-host systems (Boerlijst et al., 1993). For other motile microorganisms, travelling waves such as targets or spirals have been found in the cellular slime mold *Dictyostelium discoideum* (Gerisch, 1968, 1971; Keller and Segel, 1970; Segel and Stoeckly, 1972; Segel, 1977; Newell, 1983; Alt and Hoffmann, 1990; Siegert and Weijer, 1991; Steinbock et al., 1991; Ivanitsky et al., 1994; Vasiev et al., 1994; Höfer et al., 1995). These amoebae are chemotactic species, i.e. they move actively up the gradient of a chemical attractant and aggregate. Chemotaxis is a kind of density-dependent cross-diffusion (Keller and Segel, 1971a, 1971b) and it is an interesting open question whether there is preytaxis in plankton or not. However, there is some evidence of chemotaxis in certain phytoplankton species (Ikegami et al., 1995). Bacteria like *Escherichia coli* or *Bacillus subtilis* also show a number of complex colony growth patterns (Shapiro and Hsu, 1989; Shapiro and Trubatch, 1991), different to the already mentioned diffusion-limited aggregation patterns. Their emergence requires cooperativity as well as active motion of the species which

has also been modelled as density-dependent diffusion and predation (Kawasaki et al., 1995a, 1995b).

An important point is that the spatial dimensions of the plankton community functioning also provide new routes to chaotic dynamics. The emergence of diffusion-induced spatio-temporal chaos has been found along a linear nutrient gradient (Pascual, 1993). Chaotic oscillations behind propagating diffusive fronts are found in a prey-predator model (Sherratt et al., 1995, 1997); a similar phenomenon is observed in a mathematically similar model of a chemical reactor (Merkin et al., 1996; Davidson, 1998).

Recently it has been shown that the appearance of chaotic spatio-temporal oscillations in a prey-predator system is a somewhat more general phenomenon and must not be attributed to front propagation or to an inhomogeneity of environmental parameters (Petrovskii and Malchow, 1999, 2001). Conditions for the emergence of three-dimensional spatial and spatio-temporal patterns after differential-flow-induced instabilities (Rovinsky and Menzinger, 1992) of spatially uniform populations were derived (Malchow, 1995, 1996, 1998) and illustrated by patterns in Scheffer's model (Scheffer, 1991a). Instabilities of the spatially uniform distribution can appear if phytoplankton and zooplankton move with different velocities regardless of which one is faster. This mechanism of generating patchy patterns is more general than the Turing mechanism which depends on strong conditions on the diffusion coefficients; thus, one can expect a wide range of its application in population dynamics.

Thus, the dynamics of the plankton communities, particularly processes of pattern formation, have been under intensive investigation during the past few decades. As a result, considerable progress in understanding principal features of plankton system functioning has been achieved. Still, many mechanisms of the spatio-temporal variability of natural plankton populations are not known yet. Pronounced physical patterns like thermoclines, upwelling, fronts and eddies often set the frame for the biological processes. However, under conditions of relative physical uniformity, the temporal and spatio-temporal variability can be a consequence of the coupled non-linear biological and chemical dynamics (Levin and Segel, 1976; Steele and Henderson, 1992a). Sommer (1994, 1996) has emphasized the importance of biological dynamics during phytoplankton blooms. Daly and Smith (1993) concluded "... that biological processes may

be more important at smaller scales where behaviour such as vertical migration and predation may control the plankton production, whereas physical processes may be more important at larger scales in structuring biological communities ...". O'Brien and Wroblewski (1973) introduced a dimensionless parameter, containing the characteristic water speed and the maximum specific biological growth rate, to distinguish parameter regions of biological and physical dominance (cf. also Wroblewski et al., 1975; Wroblewski and O'Brien, 1976).

Physical and biological processes may differ significantly not only at spatial but also at temporal scales. Particularly, the effect of external hydrodynamical forcing on the appearance and stability of non-equilibrium spatio-temporal patterns has been studied (Malchow and Shigesada, 1994), making use of the separation of the different time scales of biological and physical processes. A channel under tidal forcing served as a hydrodynamical model system with a relatively high matter detention time. Examples were provided at different time scales: the simple physical transport and deformation of a spatially non-uniform initial plankton distribution as well as the biologically determined formation of a localized spatial maximum of phytoplankton biomass. Plankton pattern formation is essentially dependent on the interference of various physical (light, temperature, hydrodynamics) and biological factors (nutrient supply, predation) (cf. Platt, 1972; Denman, 1976; Fasham, 1978). In nature, it has been observed that the direction of motion of plankton patches does not always coincide with the direction of the water flow (Wyatt, 1971, 1973), and as the spatial scale becomes greater than approximately 100 m, phytoplankton behaves successively less like a simple passive quantity distributed by turbulence (Nakata and Ishikawa, 1975; Powell et al., 1975; Powell and Okubo, 1994). Similarly, the spatial variability of zooplankton abundance differs essentially from the environmental variability at scales less than a few dozens kilometres (Weber et al., 1986). This indicates that biological factors play an essential role in the emergence of plankton patchiness (Steele and Henderson, 1981).

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