
Modelling the variability in fish spatial distributions over time with empirical orthogonal functions: anchovy in the Bay of Biscay

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Abstract :

Characterizing the space–time variability in spatial distributions as well as understanding its drivers is basic to designing robust spatial management plans. As a prerequisite, we analyse here how this variability relates to population dynamics in conjunction with environmental conditions. For that, spatio-temporal statistical approaches are needed but seldom used in fisheries science. To fill this gap, we showcase the usefulness of the method of empirical orthogonal functions (EOFs). Guidelines are given to apply the method on a series of gridded maps as derived from fisheries survey dataseries that now span over decades. The method is applied to the series, 2000–2012, of the spatial distributions of European anchovy in the Bay of Biscay at spawning time. Across the series, the EOF decomposition allowed to identify three main types of spatial distributions. One type corresponded to an extended distribution, another to a restricted distribution in core areas, and the third to a very coastal distribution. The coastal spawning distribution corresponded to a low population growth rate as it was never followed by a large recruitment in the subsequent year. We did not attempt to explain the spatial patterns per se but the drivers of change from one type of distribution to another. Stock size and fish size as well as bottom temperature and water column stratification were the covariates that controlled the variability in the spatial distributions over time. Further, the spatial distribution at spawning time related to recruitment in the following year, meaning that variability in the spatial distribution of spawning affected population dynamics. The typology of maps based on EOF decomposition summarized this spatial variability into spatial spawning configurations, which may serve spatial planning.

Keywords : anchovy, Bay of Biscay, density-dependence, EOF, habitat, spatial distribution

1. Introduction

Habitats represent the environmental conditions that are favourable for an organism (e.g., for its presence, growth) and thus habitat maps provide the space-time envelopes of suitable conditions. Statistical regression has been widely used to model the habitats of the presence of species (Guisan and Zimmermann, 2000; Austin, 2007) or fish populations (Planque et al., 2011; Le Pape et al., 2014). But although closely related, habitats and spatial distributions are different concepts. Even if habitats are potentially suitable, their occupation will rely on the ability of the fish to colonize them with varying density. Thus to link habitats (suitable conditions) to fish spatial distributions, one needs to consider the mechanisms of habitat occupancy. These mechanisms involve factors internal to the population (e.g., abundance, demography, behaviour) as well as interactions in the ecosystem (e.g., trophic interactions, connectivity across the life cycle). We shall here focus on the former factors. Density-dependent habitat selection models have been used to explain how population spatial distributions vary with overall population abundance in different ways (Shepherd and Litvak, 2004; MacCall, 1990). Also physiological and behavioural mechanisms have been invoked to explain the recolonisation of past habitats during the rebuilding phase of a stock after its collapse (Petitgas et al., 2010). Thus we shall here consider that variability in spatial distributions results from variability in environmental conditions and internal population behaviour (Fig.1).

Further, we hypothesize that the spatial distribution of a population at spawning time is not independent of its demographic dynamics as it affects subsequent recruitment and therefore there is a feed-back (Fig. 1) implying that a particular spatial spawning

63 configuration is associated with a given recruitment regime. Such hypothesis is perhaps
64 more relevant for short lived species, which show greater variability in their spatial and
65 demographic dynamics. Indeed, sensitivity analyses using coupled physical-biological
66 models demonstrate the importance of initial spawning conditions on larval dispersion
67 and survival for European anchovy (Ospina-Alvarez et al., 2013; Huret et al., 2010). Here
68 the hypothesis is tested by identifying particular types of spawning spatial distributions in
69 fisheries survey data series. We suggest a space-time method for doing so, that extracts
70 principle spatial modes in the distribution. Further, we showcase how the method offers
71 the possibility to relate these principal spatial modes to covariates obtained at different
72 spatial resolutions.

73

74 To characterize and understand the variability of fish spatial distributions over time, this
75 study intends to showcase the usefulness of applying the space-time decomposition
76 method of Empirical Orthogonal Functions (EOF: Preisendorfer, 1988) on fisheries
77 survey data series. In contrast to habitat models where focus is on explaining the mean
78 distribution and its potential change with external drivers only, we here focus with EOFs
79 on characterizing the observed variability around the mean and explaining it with both
80 external and internal population drivers.

81

82 In a fisheries management context, characterizing the variability in spatial distributions
83 and understanding their consequences is important for at least two reasons. Marine
84 Protected Areas (MPA) are often designed based on habitats of particular life history
85 stages (Le Pape et al., 2014). However, variation in the spatial occupancy across years
86 may generate uncertainty in the temporal effectiveness of an MPA as the fish may
87 colonize other areas than the MPA (van Keeken et al. 2007). Further, indicators of spatial
88 distributions have been shown to relate to population parameters (e.g., recruitment,
89 demography, mortality) over a large range of stocks (Woillez et al. 2006). Thus the
90 characterization of how spatial distributions vary over time will add robustness to
91 population diagnostics as well as spatial management plans.

92

93 Empirical Orthogonal Functions have long been used in meteorology and physical
 94 oceanography to decompose the time and space variability of a time series of maps.
 95 Fisheries survey series now span more than ten years and thus offer sufficient space-time
 96 information on the spatial distributions of fish populations to consider the use of EOFs
 97 for analysing the variability in their spatial distributions. Here we apply this approach to
 98 the time series of European anchovy (*Engraulis encrasicolus*) spatial distributions at
 99 spawning time to extract the main features of variability in spatial occupancy. On that
 100 basis, we identify major spatial configurations of the spawning population. We then relate
 101 these to year class strength in the subsequent year. We also explain the spawning
 102 configurations with population and environmental parameters. In doing so, we showcase
 103 how EOFs provide a methodological framework to understand the ecology of population
 104 dynamics in its spatio-temporal dimensions.

105

106 **Material and Methods**

107 **Method of Empirical of Orthogonal Functions**

108 The method of EOF (Preisendorfer 1988) is a particular Principal Component Analysis
 109 (PCA) applied to a series of gridded maps, which allows to decompose the space-time
 110 (residual) variability in the time series of maps into principal spatial modes and their
 111 amplitudes. The decomposition is a linear factorisation of spatial components
 112 (eigenvectors) that are constant in time and amplitudes (principal components) that are
 113 variable in time. The variability around the mean map is thus modelled as the sum of
 114 time-invariant spatial components that are weighted by their time-varying amplitudes :

$$115 \quad Z(t,s) = \bar{Z}(\cdot, s) + \sum_{m=1}^q U_m(t) E_m^T(s) \quad [1]$$

116 where:

117 $Z(t,s)$ is the variable under study at time t and spatial coordinate s ,

118 $\bar{Z}(\cdot, s)$ the time average at each coordinate s ,

119 $E_m(s)$ the eigen vectors or EOFs (principal spatial modes) scaled to unity,

120 $U_m(t)$ the EOF amplitudes (principal components) scaled to $\sqrt{\lambda_m}$, where the λ_m are the

121 q non null eigen values associated with the EOFs

122

123 To achieve the decomposition, the method proceeds as follows. $Z(t,s)$ is a matrix
124 containing the gridded maps as line vectors with similar spatial order, thus having $t = 1,$
125 \dots, N lines and $s = 1, \dots, K$ columns. Each grid cell must be valued. In case of missing
126 information interpolation is needed or use of a coarser grid for data averaging. In each
127 grid cell, the cell time average is subtracted, which results in a matrix of anomalies on
128 which to perform the EOF decomposition: $X(t,s)=Z(t,s)-\bar{Z}(.,s)$. Matrix $S = X^T X / N$ is
129 then the covariance in space over time and matrix $Sa = X X^T / K$ the covariance in time
130 over space. A principal components analysis of matrix S (or equivalently Sa) leads to
131 computing the eigenvalues λ_m , eigenvectors $E_m(s)$ and principal components $U_m(t)$.

132

133 To retain the most meaningful EOFs and interpret their spatial patterns we used the eigen
134 values (overall variance accounted for by the components) and in addition the ‘local’
135 explained variance (Schrum et al. 2006, Woillez et al. 2010). The ‘local’ explained
136 variance at location s associated with EOF of order m , $\eta_m(s)$, is the proportion of variance
137 across time that $U_m(t)$ and $E_m(s)$ explain at that location :

138
$$\eta_m(s)=Var[Y_m](s)/\sum_m Var[Y_m](s) ; \text{ where } Y_m=U_m(t)E_m^T(s)$$

139 When the map of local variance shows sub-regional patterns, the EOF explains variability
140 in these areas and a biological interpretation can be looked for. Further, when the patterns
141 in the EOF (higher/ lower values) can be superimposed on that in the local explained
142 variance, the EOF is dynamically relevant in time and the EOF decomposition well suited
143 to capture the space-time variability in the series of maps. Note that the sign of $Y_m(t,s)$
144 depends on the combination of the EOF and its amplitude: it is positive when $E_m(s)$ and
145 $U_m(t)$ are of the same sign and negative when they are of opposite signs.

146

147 **Fish survey data**

148 The survey series considered was the yearly spring acoustic survey series PELGAS,
149 2000-2012, undertaken by IFREMER on board RV “Thalassa” over the French shelf of
150 the Bay of Biscay in May. The survey design is made of parallel transects, orientated
151 perpendicular to the isobaths and regularly spaced 12 nautical miles (n.m.) apart, from

152 43.5 N to 48.8 N and from coast (10 m depth) to the shelf break. Along the transects
153 38kHz acoustic records are collected continuously by day, at 10 knots (Doray et al.,
154 2010). Opportunistic pelagic trawl hauls are performed depending on the echotraces and
155 provide information on species proportions, length distributions, weight and age. During
156 night-time, conductivity–temperature–depth (CTD) profiles are performed on a regular
157 grid of stations (Fig. 2), providing measurements of environmental condition.

158

159 The anchovy population is surveyed in May at its peak spawning time and its distribution
160 is contained inside the surveyed area (ICES 2010). European anchovy is mature at age 1
161 at its first spring and spawning starts in all length groups when surface temperature is
162 above 13 °C, corresponding in the Bay of Biscay to the onset of seasonal thermal
163 stratification (Motos, 1996). Thus the surveyed population corresponds to the spawning
164 adults.

165

166 In the Bay of Biscay, because of the multi-species context and variable schooling
167 characteristics (Massé et al., 1996), the school echotraces cannot be identified to species
168 from their acoustic properties alone with the echosounder currently in use for the
169 assessment. Echotraces are identified to species at a coarser spatial resolution based on
170 pelagic trawl hauls, which are performed over several n.m. to capture aggregations of
171 echotraces. The combination of the trawl haul data with the acoustic data allow to convert
172 acoustic backscatter into fish abundance by species (MacLennan and Simmonds, 2005,
173 section 9; Doray et al., 2010). The resulting data are abundance (tonnes) by species per
174 n.m.^{-2} for each n.m. along the survey track. The survey series contains rare but very high
175 values, which may mask the regional patterns of variability. There is uncertainty in these
176 very high values because of uncertainty in allocating acoustic backscatter to species
177 (measurement error) and because extreme biological aggregation is rare and thus little
178 predictable. Thus, we followed a practice used in geoscience in the study of ore deposits
179 when measured concentrations exceed the capability of the measurement device
180 (Rivoirard et al., 2012). Values over a threshold, q , are truncated to that threshold (if
181 $Z(x,t) > q$, then $Z(x,t) = q$). The threshold considered here was 200 tonnes n.m.^{-2} , which
182 corresponded to reported maximum concentration of anchovy school aggregations (2

183 tonnes per school, 5 schools per km: Massé et al., 1996; Petitgas et al. 2001). Values
184 greater than 200 were rare with a frequency of 0.002 in the data set. We considered the
185 spatio-temporal series of these (truncated) data, with one survey per year, 2000-2012.

186

187 **Block averaging**

188 Prior to the EOF analysis, the data were averaged by block over a grid, which was the
189 same in all years. The grid mesh size selected was 0.4° in latitude and 0.4° in longitude,
190 with origin x_0 at 43°N and 6°W . The mean in block (i, j, x_0) was the simple average of the
191 data inside the block and it was positioned at the location of the block centre. The limits
192 of block (i, j, x_0) depend on the origin x_0 and therefore the samples involved in computing
193 the block mean. To decondition the block means from the grid origin, the point origin x_0
194 was randomized in the lowest left corner block one 100 times as in Petitgas et al. (2009).
195 At each randomization k , the grid origin x_k varies and the mean in block of rank (i, j) is
196 computed. Each block of rank (i, j) has then one 100 means associated to it. The mean of
197 all 100 means was then calculated and positioned at the centre of block (i, j, x_0) . This
198 blocking procedure results in an implicit kernel-like interpolation where each data takes
199 part in the block average with a frequency (weight) depending on its distance to the block
200 centre. Finally, blocks which were not valued due to lack of samples in a given year were
201 omitted in the analysis as well as the blocks which had their centre point outside the
202 polygon defining the survey area (Fig. 2). Several trials with different mesh sizes were
203 undertaken and the mesh retained was the smallest one for which the first two principal
204 components explained more than 50% of total variance. The grid mesh size retained
205 allowed a reasonable compromise between enough fine scale smoothing and sufficient
206 large and mesoscale details. Finally, instead of biomass per cell we used the percentage
207 biomass: $P(t,s)=1000Z(t,s)/\sum_s Z(t,s)$. Matrix $P(t,s)$ was then centred by column to form
208 matrix X .

209

210 **Typology of maps**

211 The EOF decomposition being a Principal Components Analysis where the years are the
212 lines (individual observations) and the map grid cells the columns (variables), it is
213 possible to perform a hierarchical clustering of the years, applying a clustering procedure

214 on the matrix of distances between years in the factorial space of the first p components
215 ($p < K$). The clustering was performed using the Ward criterium (minimize the intra group
216 variance), which aims at finding compact groups. The average map in group g , $\bar{Z}_g(.,s)$,
217 was estimated by taking the simple average of maps Z for the years of group g . The
218 clustering resulted in defining types of spatial distributions thus summarizing the
219 meaningful variability in the series of maps.

220

221 **Explicative covariates**

222 In a classical habitat statistical approach (e.g., Le Pape et al., 2014) the fish distribution
223 map (response) and the maps of (explanatory) covariates are produced on the same spatial
224 grid and each point in the maps contribute to an overall correlation model linking fish
225 presence to covariates. Here, the EOF framework proposes another approach. The EOF
226 patterns of variability are defined empirically from the data and are invariant in time. The
227 variation over time in the spatial distribution is taken in charge by the variations in the
228 weights of the EOF patterns as given by the EOF amplitude time series. We thus focussed
229 on explaining the EOF amplitudes time series with covariates. Based on our conceptual
230 approach (Fig. 1) covariates considered were population parameters affecting population
231 behaviour via density-dependent processes and hydrological conditions affecting habitat
232 suitability.

233

234 *Population parameters.* Following Cotter et al. (2009), we considered three indices to
235 characterize population status: total (spawning) biomass and two length distribution
236 percentiles. Population biomass was estimated from the survey as reported to ICES
237 (2012). The length distribution percentiles were the 25% and 75% percentiles. The length
238 distribution in the population was estimated as follows. The (local) frequency distribution
239 of length in a trawl haul was weighted by fish biomass along the acoustic transects within
240 a radius of 10 n.m. from the trawl haul position. The population length distribution was
241 the weighted average of all local distributions.

242

243 *Hydrological indices.* Hydrological condition was characterized using indices calculated
244 from the CTD profiles at the stations (Fig. 2). We considered 4 indices (Table 1) to

245 characterize typical features on the shelf in spring (Huret et al., 2013): surface and bottom
 246 temperature, a water column stratification index and a river plume index. These were
 247 calculated following the procedures detailed in Huret et al. (2013). Surface values were
 248 taken at 7 m depth. Bottom values were 5 m above bottom. The deficit of potential
 249 energy, Dep , is the energy required to homogenize the water column. The greater the
 250 Dep value the greater the stratification. It was calculated from surface to 60 m depth for
 251 the profiles where bottom depth exceeded 60 m. The equivalent fresh water height, H_{fw} ,
 252 measures the height of accumulated fresh water considering a reference sea water salinity
 253 (35.85 psu: mean bottom salinity). In comparison to surface salinity, H_{fw} is less affected
 254 by vertical mixing and thus reflects better the past history of river discharge over a few
 255 months. The indices were calculated at each station and the overall spatial mean was
 256 calculated to obtain time series of mean indices.

257

258 *Correlation between amplitudes of EOFs and covariates.* The time series of each
 259 amplitude $U_m(t)$ associated with EOF of order m was linearly regressed on that of the

$$U_m(t) = \sum_{j=0}^p a_j X_j(t)$$

260 different covariates $X_j(t)$; where $X_0(t) = 1$. For each m , the most
 261 probable model was selected using Akaike's information criterium (AIC: Burnham and
 262 Anderson, 2002). For each m , we considered the 127 possible models given the set of the
 263 seven covariates. For each m , the model retained was that with the lowest AIC value. To
 264 identify the most explanatory covariates (i.e., those involved in the most probable
 265 models) we computed their relative importance weights. For that, each covariate j
 266 involved in model i explaining amplitude U_m was attributed the model probability $p_m(i)$
 267 as deduced from its AIC value or zero if model i did not involve the covariate. The
 268 relative importance weight of covariate j in explaining amplitude U_m was the sum over

269 all model probabilities: $\sum_{i=1}^{127} p_m(i)$, where $p_m(i) = \exp[-0.5\Delta(i,m)] / \sum_{i=1}^{127} \exp[-0.5\Delta(i,m)]$ with

270 $\Delta(i,m) = AIC(i,m) - \min(AIC(i,m))$. The relative importance weight varies between 0 and 1.

271 Typically, strong explanatory covariates will have a relative importance weight around
 272 0.9, moderately explanatory between 0.6 - 0.9 and weakly explanatory between 0.5 - 0.6.
 273 Below 0.5 covariates will often be little relevant.

274

275 **Results**

276 **Patterns of variability**

277 The average distribution over all years (Fig. 3) shows anchovy to be mainly located south
278 of 46°N with low abundance in the north mainly in coastal areas. The major
279 concentration is located off the Gironde estuary (45-46°N, 1.5-2°W), along the coast and
280 on the shelf off Landes. The principal spatial modes of yearly variability around the mean
281 were extracted using the EOF decomposition technique. Four principal components were
282 retained ($m=4$). Each explained more than 10% of total variance (Table 2) and showed a
283 strong spatial pattern in their EOF as well as in the map of local explained variance (Figs.
284 4 and 5). The first EOF (Fig. 4) captured the variability along the coast of Landes and off
285 Gironde estuary: the lower the abundance along the coast of Landes, the higher the
286 concentration off Gironde. The second EOF (Fig. 4) captured a large scale pattern where
287 less abundance in the south was associated to more abundance in the north. More
288 specifically, EOF 2 captured the variability at the shelf break off Landes, the central part
289 of the shelf off Gironde and Bretagne: the lower the abundance at the coast off Gironde
290 and along the shelf break off Landes, the greater it was in Bretagne and in the central part
291 of the shelf off Gironde. The third EOF (Fig. 5) captured the variability along the coast of
292 Vendée and also in the area where the shelf break is curved (45°N, 2°W): the lower the
293 abundance on the shelf off Landes, the greater it was along the coast of Vendée. The
294 fourth EOF (Fig. 5) captured the variability along the shelf break north of 45°N: the
295 lower the abundance at the coast off Vendée and at 45°N, the higher at the shelf break.

296

297 **Typology of maps and their relationship with recruitment**

298 Using the first four principal components associated with the EOFs described previously,
299 three groups of maps were identified by hierarchical clustering (Fig. 6). The differences
300 among the average maps of each group denoted strong differences in the spatial
301 distributions over the years (Fig. 7). Group 1 (Fig. 7: maps in years 2000, 2001, 2008,
302 2009, 2011, 2012) corresponded to the largest spatial extension. The distribution
303 extended in the northern part, on the shelf break north of 45°N and along the coast of
304 Vendée and Bretagne although the largest concentration was off Gironde and on the shelf

305 of Landes. In contrast, Group 2 (Fig. 7: maps in years 2002, 2005, 2010) corresponded
306 to the smallest spatial extension and showed higher concentrations in 2 areas, off Gironde
307 and at the shelf break off Landes. Group 3 (Fig. 7: maps in years 2003, 2004, 2006, 2007)
308 corresponded to a coastal spatial distribution with high concentrations along the coast
309 south of 46°N. This typology of spatial patterns at spawning time related to biomass in
310 the current year and to recruitment (age 1 fish) in the subsequent year (Fig. 8): very
311 coastal spawning distributions of type G3 occurred when biomass was low only and at
312 low biomass level, spawning distributions G3 and G2, which had smaller spatial
313 extension than G1, were never followed by high recruitment.

314

315 **Correlates of amplitudes of EOFs**

316 Based on the AIC criteria, the selected models showed high R-square ranging 0.48 – 0.70
317 (Table 3) and made sense biologically. Temperature alone explained amplitude of EOF 4,
318 which characterized variability along the shelf break. By contrast amplitude of EOF 3
319 (which characterized variability along the coast off Vendée) was explained by population
320 parameters only. EOF amplitudes 1 and 2 were explained by a combination of population
321 and environmental indices. Population biomass intervened as covariate of the amplitudes
322 of the three first EOFs, meaning that variability in the distributions was strongly density-
323 dependent. Also, the length distribution influenced the amplitudes of EOFs 1 and 3,
324 which both involved variability in coastal waters. Bottom temperature and water column
325 stratification were covariates of the amplitudes of EOFs 1 and 2, which both involved
326 expansion to the north and variability on mid-shelf. It is noteworthy that the river plume
327 index was never selected as a covariate. The relative importance weights of the covariates
328 (Table 4) confirmed that the covariates in the models selected were the most explanatory
329 ones. Yet, for the amplitude of EOF1, the most probable model (Table 3) involved the
330 stratification index (Dep) which had a low importance weight (Table 4). The model
331 without the stratification index (i.e., with SSB, q75, and Tb only) was ranked second
332 most probable with a probability of 0.85 and thus was nearly as probable as the retained
333 model (with SSB, q75, Tb, and Dep: Table 3). The stratification index played a slightly
334 minor role relative to the other three covariates in explaining the amplitude of EOF1. For
335 the amplitude of EOF3, the most probable (Table 3) model involved SSB which also had

336 a low importance weight (Table 4). The model without SSB (with q25 and q75 only:
337 Table 3) was ranked second best model but with the low probability of 0.49, meaning that
338 SSB should nevertheless be retained as a covariate. In all, Biomass (SSB), proportion of
339 large fish (third quartile q75), bottom temperature (Tb) and water column stratification
340 (Dep) were the most explanatory covariates of the changes over time in the spatial
341 distributions.

342

343 **Discussion**

344 The EOF decomposition characterized the variability in the spatial distributions over time
345 by extracting time-invariant principal spatial modes and their time-varying amplitudes.

346 The EOF decomposition served to classify maps. The typology of the spawning spatial
347 distributions related to population subsequent recruitment. The time series of amplitudes
348 were explained by population parameters (abundance, length distribution) and
349 environmental conditions (bottom temperature, water column stratification). Thus
350 changes in the spatial distribution were modelled depending on how the time-varying
351 amplitudes (weights of the principal EOF patterns) varied with covariates.

352

353 *How meaningful are EOFs.* The EOFs characterize spatial patterns of variability around
354 the mean map that are constant in time. It is their amplitudes that vary over time not the
355 EOFs. Such mathematical decomposition is not always suited to characterize complex
356 natural space-time variability and we here discuss how to acknowledge their suitability to
357 the case study. The EOF decomposition is little adapted to situations where areas of
358 variability change location over time. The local explained variance (Schrum et al., 2006)
359 is a way to test for that. If the local explained variance displays similar spatial patterns
360 than the EOFs, the EOFs are then dynamically relevant in time. Here, EOFs and their
361 local explained variance showed similar maps. Another point of consideration is that the
362 mathematical property of spatial orthogonality in the EOF decomposition may generate
363 artifactual patterns in the spatial modes with little physical interpretation, such as, e.g.,
364 dipole structures (Dommenget and Latif, 2002). It is therefore key to be able to critically
365 interpret the spatial patterns in the EOFs by relating them to physical or biological
366 phenomena. To increase interpretation, orthogonal (Varimax) rotation of EOFs has been

367 proposed to extract more locally defined spatial patterns (e.g., Richman 1986). But this
368 approach has its limitations: the ability to extract global spatial patterns in the modes is
369 lower (Dommenget & Latif 2002) and the rotation may introduce correlation between
370 amplitudes of rotated modes (Mestas-Nunez 2000) and thus reduce the ability to
371 reconstruct the data and classify maps. Here, the EOFs identified local areas that were
372 meaningful for the stock (coast, Gironde, shelf-break), making unnecessary to find more
373 localised patterns by rotation. The EOF decomposition was thus considered suitable here
374 to characterize the space-time variability in the series of anchovy spawning spatial
375 distributions.

376

377 *Data smooting on a grid prior to the EOF decomposition.* EOFs are best interpretable
378 when their spatial patterns develop over several grid cells at regional or sub-regional
379 scale. The grid mesh size over which to block average the data should thus be adequate.
380 Here, we used the amount of variance in the EOFs to define the grid mesh size. The scale
381 in the EOF patterns was greater than 1°Latitude x 1°Longitude, which was compatible
382 with the meso-scale / subregional aggregation pattern of schools in the area (Petitgas,
383 2003). The data set contained rare extreme values, which were uncertain given current
384 knowledge of schooling aggregation in the area (Petitgas et al., 2001). To deal with them,
385 the data were truncated. The truncation threshold was not defined statistically but based
386 on known schooling behaviour, similarly as for filtering unreliable information. Morfin et
387 al. (2012) took a different approach to study the variability of spatial patterns: (i) they
388 worked on log-transformed data to diminishing the influence of high values; (ii) they
389 interpolated the transformed data by kriging on a grid of small mesh size, which amounts
390 to smoothing. In contrast, our analysis provides guidelines to work on the raw data and
391 makes full use of the local explained variance to interpret the EOFs and their dynamics in
392 time.

393

394 *Covariates.* The regression of EOF amplitudes on series of explicative covariates was a
395 flexible approach as it allowed to relate spatial patterns at regional and sub-regional
396 scales (EOFs) in the fish distribution to covariates obtained at other spatial resolutions
397 (e.g., population scale). The three major patterns of variability in the spatial distribution

398 (Table 3) amounted to range expansion to northern Biscay, coastal distribution,
399 aggregation off Gironde estuary. Their relative importance was controlled by a
400 combination of environmental conditions and population parameters. Population biomass,
401 population length distribution, bottom temperature and water-column stratification were
402 influential in making the spatial distributions vary, which agrees with the literature.
403 Range expansion with population abundance has been observed in many fish stocks
404 (Shepherd and Litvack, 2004) and was originally observed on anchovy in the California
405 current (MacCall, 1990). Also, anchovy in the bay of Biscay shows a gradient in length
406 from coast to off-shore (Petitgas et al., 2003), the smaller fish being more coastal. It is
407 therefore not surprising that the anchovy distribution varies with population abundance
408 and length distribution and our analysis models how this happens. Also bottom
409 temperature and water column stratification were influential. During day-time, anchovy
410 forms schools well below the thermocline generally 10-20 m above the bottom (Massé,
411 1996), which may explain why bottom temperature may influence habitat suitability and
412 thus anchovy spatial distribution. Water column stratification is under the influence of
413 river plumes and warming surface temperature. River plumes are related to early season
414 plankton production (Labry et al., 2001) and warming surface temperature triggers
415 spawning (Motos, 1996) that occurs at night close to surface. Water column stratification
416 is thus also naturally involved in determining spawning habitat suitability.

417

418 *EOFs and typology of maps.* Based on the EOF decomposition, we classified the varying
419 spawning distributions into 3 major types of maps: distributions extending over many
420 habitats including northern parts of Biscay (type G1), distributions contracted on two core
421 habitats in south Biscay (type G2) and distributions limited to coastal areas in south
422 Biscay (type G3). At low biomass level the distributions of type G3 and G2 that were
423 more contracted spatially and coastal were never followed by a high recruitment in the
424 following year. The coastal distribution of type G3 occurred when biomass was lower,
425 fish length smaller and water column stratification greater. In these circumstances total
426 annual fecundity can be expected to be lower because of lower spawning biomass and a
427 shorter spawning period as predicted by bioenergetics (Pecquerie et al., 2009). Also when
428 too high, water column stratification can be detrimental for larval survival (Allain et al.,

429 2007). At low biomass level, the spawning distribution of type G2 was associated with
430 larger fish and colder bottom temperature. These conditions could also result in lower
431 total fecundity over the restricted G2 habitats. Further, the spatial initial conditions for
432 larvae drifts will be more coastal and with less spatial extension for types G3 and G2 than
433 for G1 and this may also influence larval trajectories and survival probability. Whether G2
434 and G3 spawning types at biomass level can be associated with low subsequent
435 recruitment could be mechanistically tested with a coupled bio-physical larval model
436 predicting larval transport and survival. In doing so, a given spawning map type could be
437 used as initial condition to the larval model, following the approach of Ospina-Alvarez et
438 al. (2013). Using different egg maps as initial condition for their transport larval model as
439 derived from survey data, they found significant differences in larval drift trajectories.

440

441 *Dynamic update of maps.* Variability in the spatial distributions under both population
442 and environmental conditions is a useful knowledge for increasing robustness in spatial
443 management measures. Based on the regressions of EOF amplitudes on covariates, spatial
444 distributions could be predicted to update dynamically the spawning maps depending on
445 combined population and environmental scenarios. Robustness of spatial management
446 measures could then be tested on that basis. The study provides a typology of spawning
447 distributions that can be input to dynamic population spatial models.

448

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457

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556 population spatial occupation and population dynamics. ICES CM 2006/O:05
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560 Table 1: hydrological indices calculated using CTD profiles collected during the PelGas

561 cruises. ρ : water density; z : depth; H : bottom depth or 60 m when bottom depth was

562 greater; g : gravitational acceleration; s_0 : reference sea water salinity

563

Index	units	Formula
Stratification index		
Deficit of potential energy (Dep)	$\text{kg m}^{-1} \text{s}^{-2}$	$Dep = \frac{1}{H} \int_{-H}^0 (\bar{\rho} - \rho(z)) g z dz ; \bar{\rho} = \frac{1}{H} \int_{-H}^0 \rho(z) dz$
River plume index		
Equivalent fresh water height (Hfw)	m	$Hfw = \int_{-H}^0 \frac{s_0 - s(z)}{s_0} dz ; s_0 = 35.85$
Hydrological indices		
Surface (7m) temperature (Ts)	$^{\circ}\text{C}$	
Bottom temperature (Tb)	$^{\circ}\text{C}$	

564

565

566 Table 2 : Cumulated percent total variance explained by the principal components of the

567 EOF decomposition.

568

PC	1	2	3	4	5	6	7	8	9	10	11	12	13
%	0.30	0.50	0.65	0.77	0.84	0.89	0.93	0.95	0.97	0.98	0.99	1.00	1.00
var													

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574 Table 3 : Selected linear regression models of EOF amplitudes U_m on covariates.
575 Covariates are: SSB: stock biomass as estimated by the survey (tonnes), q25 and q75 the
576 25 and 75 percentiles of the length distribution (cm), Ts and Tb the surface and bottom
577 temperature (°C), Dep the index of stratification, Hfw the index of river plume (see table
578 1). Values tabled are the coefficients estimated for each covariate. R-square is the
579 variance explained by the linear model (1- residual variance/total variance).
580

EOF	<i>EOF1</i>	<i>EOF2</i>	<i>EOF3</i>	<i>EOF4</i>
EOF description	<i>Less at coast off Landes, more off Gironde</i>	<i>Less in southern Biscay, more in North</i>	<i>Less on shelf off Landes, more at coast off Vendée</i>	<i>Less on shelf off Landes, more at shelf edge in North</i>
Amplitudes	U_1	U_2	U_3	U_4
Intercept	97.44	-201.3	196.3	-127.432
SSB	0.0005875	0.0002659	0.0002982	-
q25	-	-	-24.87	-
q75	12.54	-	31.93	-
Ts	-	-	-	8.789
Tb	-29.93	12.98	-	-
Dep	0.4274	0.5136	-	-
Hfw	-	-	-	-
R-square	0.68	0.70	0.43	0.52

581
582
583

583 Table 4: Relative importance weights of covariates over the 127 candidate linear models
 584 for each EOF amplitude Um . Covariates are defined in Table 3.
 585

	U_1	U_2	U_3	U_4
SSB	0.97	0.80	0.47	0.32
q25	0.47	0.40	0.63	0.47
q75	0.55	0.45	0.53	0.40
Ts	0.40	0.44	0.32	0.81
Tb	0.87	0.60	0.36	0.36
Dep	0.43	0.62	0.30	0.42
Hfw	0.38	0.38	0.34	0.48

586

587 Fig. 1: Schematics of the variability in spatial distributions. Environmental and
588 population conditions affecting habitats and behaviour respectively, which influence
589 spatial distribution. In return, the spatial organisation of the population also affects its
590 dynamics and thus feeds back into the loop of drivers affecting population behaviour.

591

592 Fig. 2 : Localization of acoustic transects, CTD stations and polygon of study

593

594 Fig. 3 : Mean distribution map, 2000-2012. The map represents the average percentage
595 (x1000) of population biomass in grid cells of $0.4^{\circ} \times 0.4^{\circ}$.

596

597 Fig. 4: EOFs 1 and 2 (left) and their associated local explained variance (right). EOF1
598 (top) corresponds to the following pattern of variability: when there is less fish at the
599 coast off Landes (negative values), there is more fish off Gironde (positive values) and
600 vice versa. For EOF2 (bottom) the pattern of variability is the following: when there is
601 less fish in southern Biscay (negative values), there is more fish in northern Biscay
602 (positive values) and vice versa.

603

604 Fig. 5: EOFs 3 and 4 (left) and their associated local explained variance (right). EOF3
605 (top) corresponds to the following pattern of variability: when there is less fish on shelf
606 off Landes (negative values), there is more fish at coast off Vendée (positive values) and
607 vice versa. For EOF4 (bottom) the pattern of variability is the following: when there is
608 less fish on shelf off Landes (negative values), there is more fish at the shelf-edge in
609 North (positive values) and vice versa.

610

611 Fig. 6: Typology of maps (hierarchical clustering) based on the first four principal
612 components associated to the EOFs. Three groups were retained.

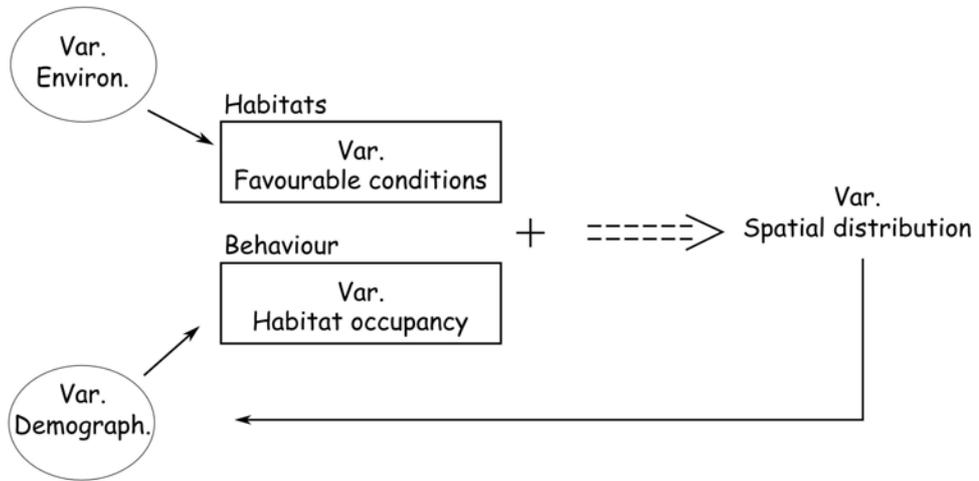
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614 Fig. 7: Mean map in each of the three identified groups of maps: G1 (years 2000, 2001,
615 2008, 2009, 2011, 2012), G2 (years 2002, 2005, 2010), G3 (years 2003, 2004, 2006,
616 2007).

617

618 Fig. 8: Relationship between recruitment in year (t+1), spawning stock biomass and
619 spawning distribution map type (G1-G3) in year (t). At low spawning biomass level
620 maps of type G3 and G2 in year (t) are never followed with a high recruitment in year
621 (t+1). Map of type G3 is observed only at low biomass level.
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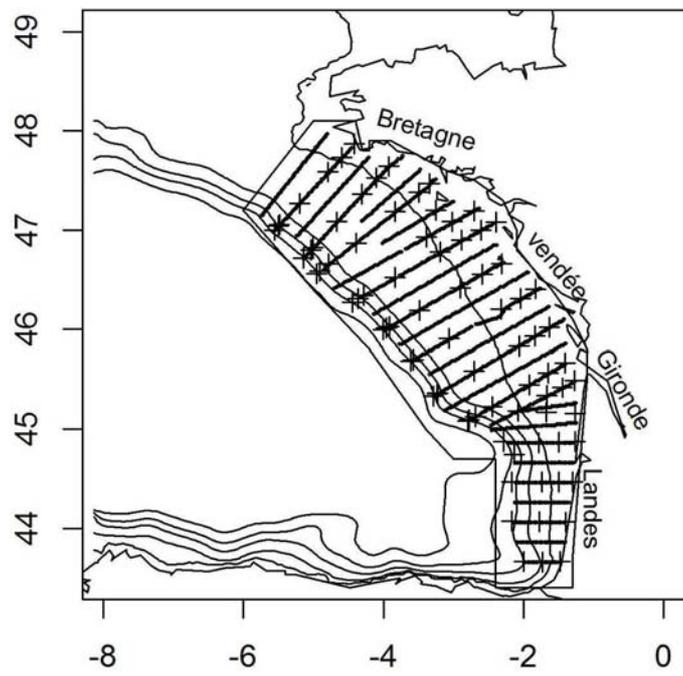
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Figure 1

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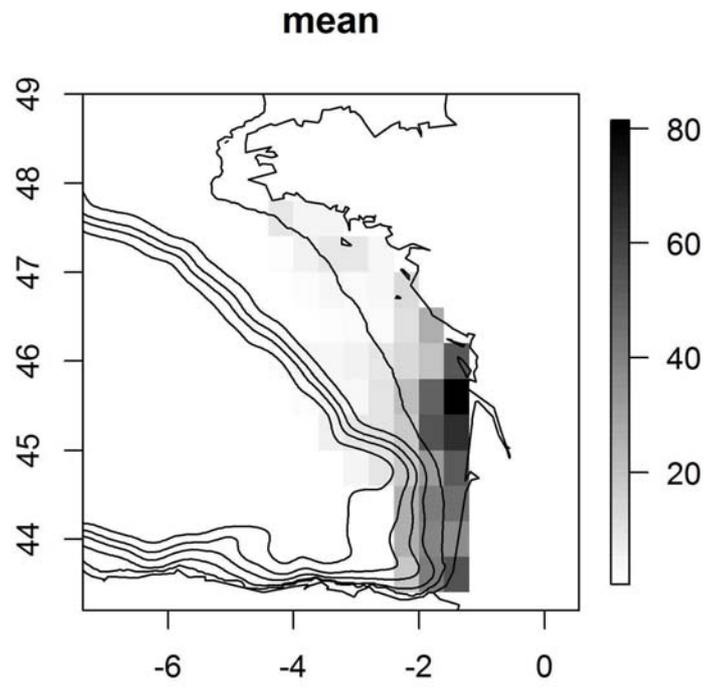
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Figure 2

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Figure 3

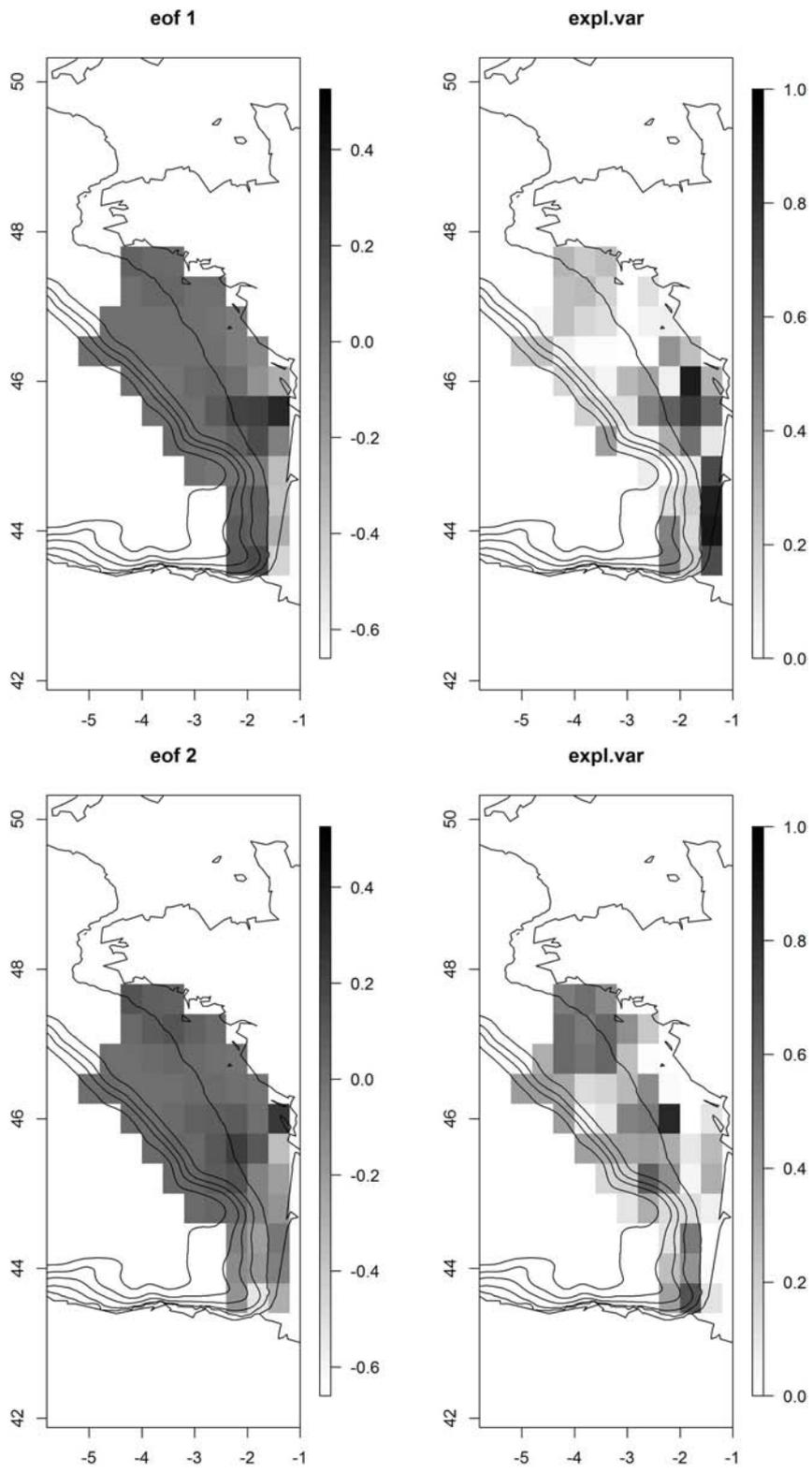
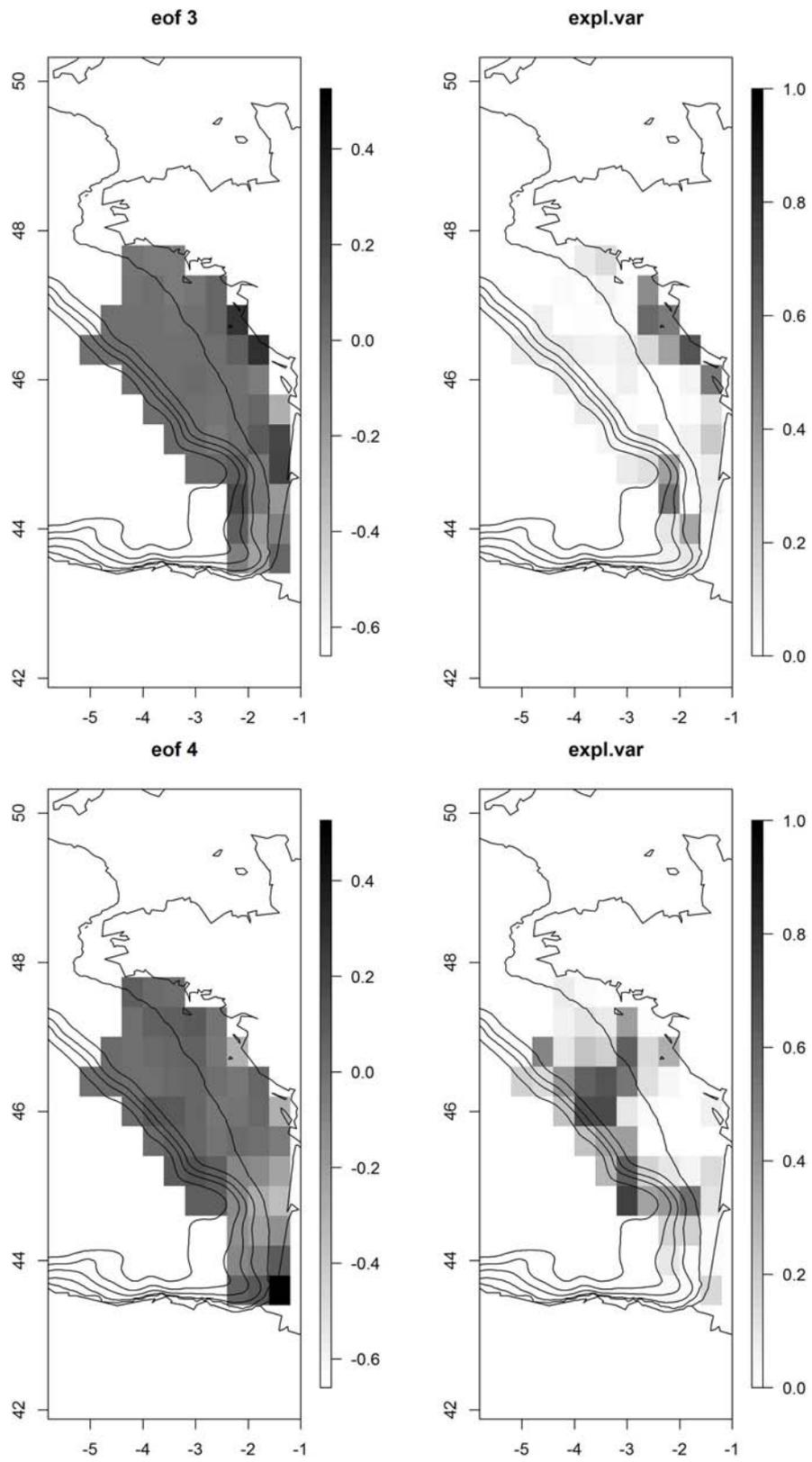


Figure 4

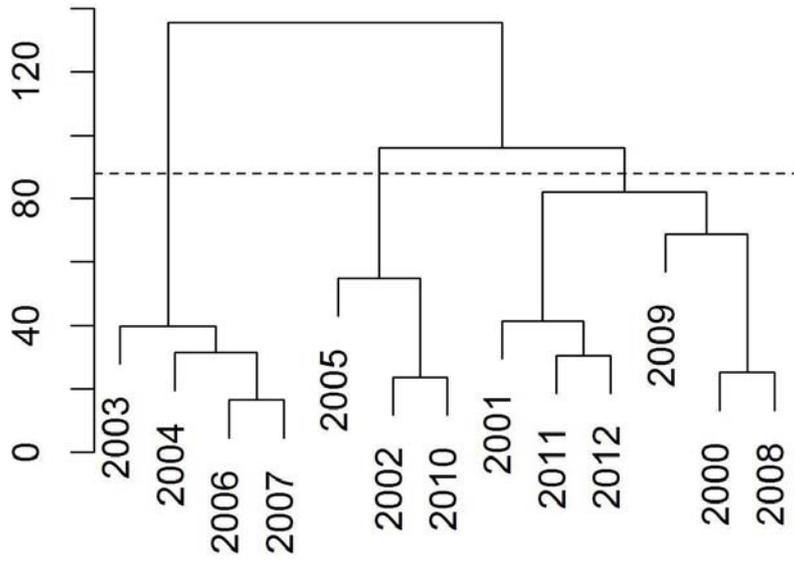


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Figure 5

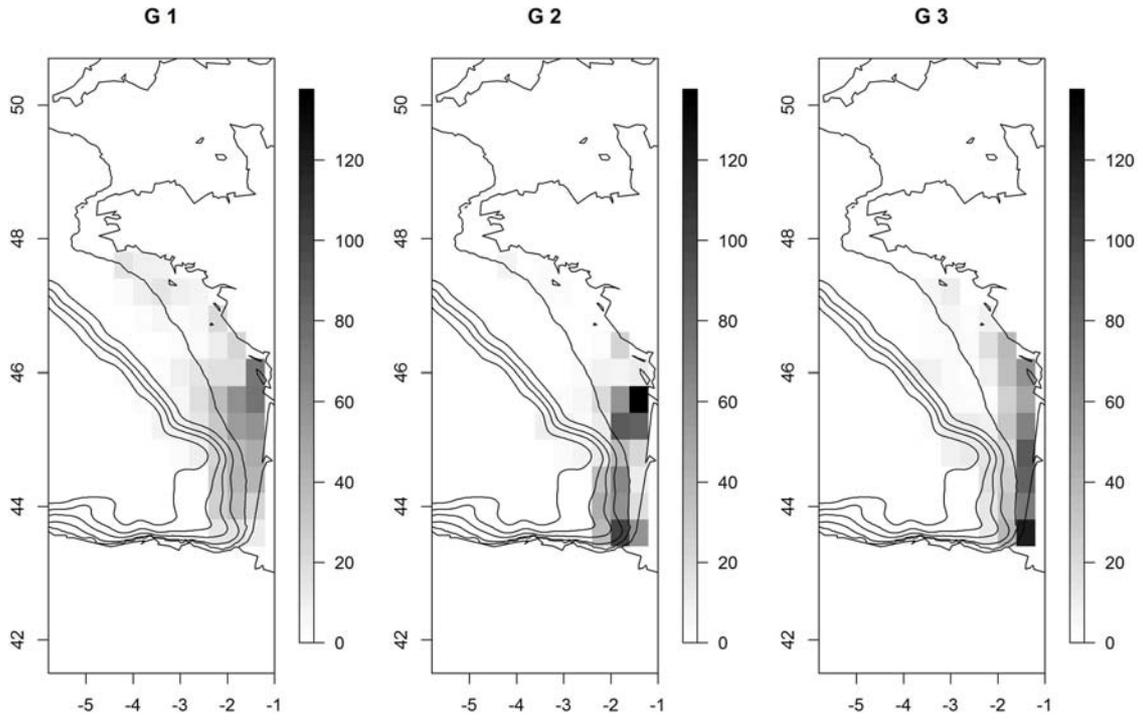
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Figure 6

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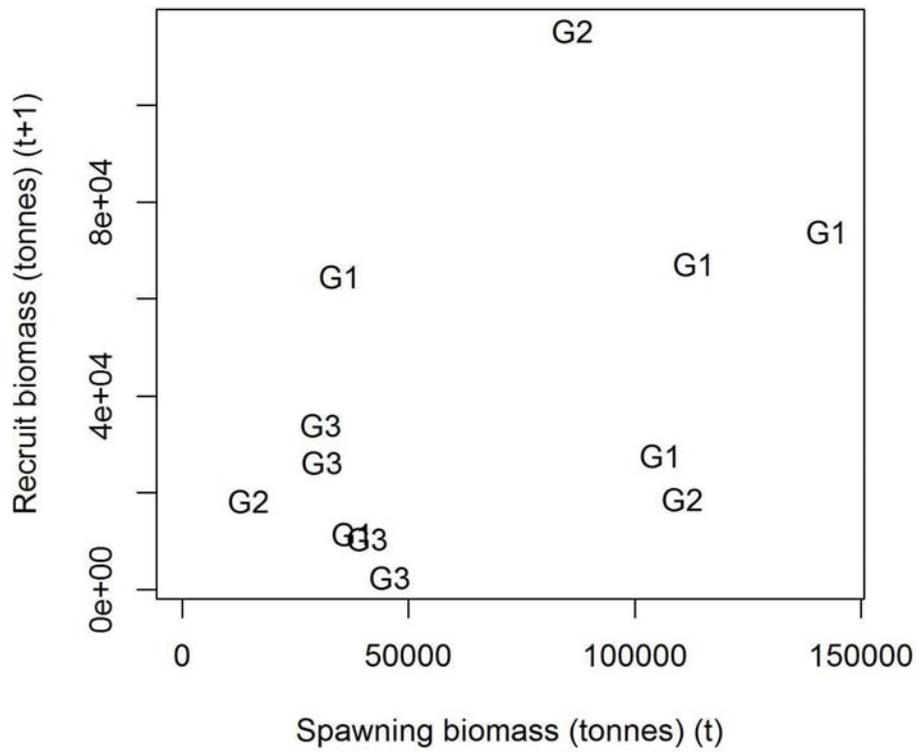
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Figure 7

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Figure 8