

Ecoviability for ecosystem-based fisheries management

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Abstract :

Reconciling food security, economic development and biodiversity conservation is a key challenge, especially in the face of the demographic transition characterizing many countries in the world. Fisheries and marine ecosystems constitute a difficult application of this bio-economic challenge. Many experts and scientists advocate an ecosystem approach to manage marine socio-ecosystems for their sustainability and resilience. However, the ways by which to operationalize ecosystem-based fisheries management (EBFM) remain poorly specified. We propose a specific methodological framework-viability modelling-to do so. We show how viability modelling can be applied using four contrasted case-studies: two small-scale fisheries in South America and Pacific and two larger-scale fisheries in Europe and Australia. The four fisheries are analysed using the same modelling framework, structured around a set of common methods, indicators and scenarios. The calibrated models are dynamic, multispecies and multifleet and account for various sources of uncertainty. A multicriteria evaluation is used to assess the scenarios' outcomes over a long time horizon with different constraints based on ecological, social and economic reference points. Results show to what extent the bio-economic and ecosystem risks associated with the adoption of status quo strategies are relatively high and challenge the implementation of EBFM. In contrast, strategies called ecoviability or co-viability strategies, that aim at satisfying the viability constraints, reduce significantly these ecological and economic risks and promote EBFM. The gains associated with those ecoviability strategies, however, decrease with the intensity of

regulations imposed on these fisheries.

Keywords : biodiversity, ecological economics, ecosystem approach, fisheries, scenario, viability

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1 Introduction and motivations

Reconciling food security with biodiversity conservation is among the greatest challenges of the century, especially in the face of the world demographic transition (Godfray *et al.*, 2010; Rice & Garcia, 2011). The creation of the IPBES (International Panel for Biodiversity and Ecosystem Services) at the interface between decision support and scientific knowledge is in direct line with these concerns. Implementing this bio-economic perspective is especially challenging in the case of fisheries and marine ecosystems. Marine and coastal ecosystems are experiencing accelerating changes affecting species and communities at different biotic scales, sometimes with alarming trends and largely unknown consequences (Butchart *et al.*, 2010; MEA, 2005). These changes are partially due to past and current fishing pressure, thus questioning the sustainability of current fishing activities and food production systems, and raise key questions in terms of food security, especially for developing countries with high demographic growth. Climate change complicates and exacerbates the issues by inducing new, or intensifying existing, risks, uncertainties and vulnerabilities.

As a consequence, ensuring the long-term ecological-economic sustainability of marine fisheries systems, and preserving the marine biodiversity and ecosystems that support them, have become a major issue for national and international agencies (FAO, 2013). In response, an increasing number of marine scientists and experts advocate the use of ecosystem-based fishery management (EBFM) accounting for the various ecological and economic complexities at play. Pikitch *et al.* (2004) for instance claim that EBFM is a new direction for fishery management, essentially reversing the order of management priorities so that management starts with the ecosystem rather than a target species, while FAO (2003) proposes the following definition:

“An ecosystem approach to fisheries strives to balance diverse societal objectives, by taking into account the knowledge and uncertainties about biotic, abiotic and human components of ecosystems and their interactions and applying an integrated approach to fisheries within ecologically meaningful boundaries.”

The way to operationalize this EBFM approach, however, remains challenging (Sanchirico *et al.*, 2008; Doyen *et al.*, 2013), along with the identification of methods, approaches and tools

49 to support its implementation. Hence, there is a need to develop new models, indicators and
50 scenarios in this domain (Plagányi *et al.*, 2007). In particular, the effectiveness of current
51 regulatory instruments including fishing quotas or financial incentives needs to be reconsidered
52 in light of this new multi-functional, cross-sectoral and interdisciplinary context, accounting for
53 the multiple commodities and services provided by marine biodiversity and ecosystems. The
54 aim of this paper is to contribute to this discussion through the use of viability modelling.

55 Viability modeling is now recognized by a growing number of researchers (Jennings, 2005;
56 Cury *et al.*, 2005; Thébaud *et al.*, 2013; Krawczyk *et al.*, 2013) as a relevant framework for
57 EBFM. In the context of dynamic systems, the aim of the viability approach is to explore states
58 and controls that ensure the ‘good health’ and safety of the system (Aubin, 1990; De Lara &
59 Doyen, 2008). By identifying the viability conditions that allow constraints to be fulfilled over
60 time, considering both present and future states of a dynamic system, the viability approach
61 conveys information on sustainability (Baumgartner & Quaas, 2009). It accounts for dynamic
62 complexities, uncertainties, risks and multiple sustainability objectives. Resilience and recovery
63 goals can also be addressed through viability modeling using the notion of minimal time of
64 crisis (Béné *et al.*, 2001; Deffuant & Gilbert, 2011). As reviewed recently by Schuhbauer &
65 Sumaila (2016), the approach has already been successfully applied to fisheries management in
66 several contexts (Eisenack *et al.*, 2006; Martinet *et al.*, 2007; Sanogo *et al.*, 2013; Krawczyk *et*
67 *al.*, 2013) including (eco)-system or biodiversity dynamics (Mullon *et al.*, 2004; Doyen *et al.*,
68 2007; DeLara *et al.*, 2012; Gourguet *et al.*, 2013; Maynou, 2014). In relation to food security,
69 Cissé *et al.* (2013, 2015); Hardy *et al.* (2013) provide useful bio-economic insights in the context
70 of developing countries under important demographic pressure.

71 The main objective of this paper is to show through modeling and scenario analyses how this
72 viability approach can provide a relevant methodological framework to implement EBFM. The
73 work relies especially on four contrasted case studies: the small-scale fishery of French Guiana
74 (South America), the small-scale fishery of Solomon Islands (Pacific), the Bay of Biscay multi-
75 species demersal fishery (Europe) and the Northern prawn fishery of the Gulf of Carpentaria
76 (Australia). All four fisheries are represented as systems of intermediary complexity (Plagányi
77 *et al.*, 2014) and analyzed using the same modeling framework, common methods, indicators

78 and scenarios. The calibrated models are dynamic, multi-species and multi-fleet and account
79 for various sources of uncertainty. A multi-criteria analysis of alternative effort strategies is
80 implemented, with the objective to assess the fulfillment of different constraints and objectives
81 at the 2030-2050 horizon, based on ecological, social and economic reference points. We name
82 such an approach ecoviability as in Cissé *et al.* (2015) to highlight the ecological, economic and
83 ecosystemic ingredients of this viability modeling.

84 The scientific contribution of the paper is twofold. First it demonstrates the advantages
85 of using the ecoviability approach to operationalize EBFM through a series of contrasted case
86 studies. In particular it shows how implementing a viability strategy can lead to ‘win-win’
87 situations in terms of reduction of ecological and economical vulnerabilities and risks. Second,
88 the paper highlights some potentially important differences between more heavily regulated and
89 less regulated fisheries when comparing a viability strategy to the current state (status quo).
90 Ecoviability indeed leads to ‘win-win’ outcomes in terms of both economic expectation and
91 bio-economic risk for less regulated fisheries while, in contrast, heavily regulated fisheries face
92 trade-offs because they perform well in terms of economic expectation and scores.

93 The paper is organized as follows. Section 2 presents the generic ecoviability modeling
94 approach including the controlled uncertain dynamics, viability metrics and scenarios. Section
95 3 is devoted to the application of the general framework to the contrasted case studies and
96 especially to the comparison of scenarios including the viability scenario. Section 4 discusses the
97 results in particular with respect to EBFM while Section 5 concludes. Mathematical details on
98 the models and methods are described in the Appendix.

99 **2 Ecoviability approach, models and scenarios**

100 The viability approach relies on mathematical models derived from the theory of dynamic sys-
101 tems control under constraints. Within this generic framework, the ecoviability framework
102 (also termed co-viability) specifically focuses on the ecological-economic viability of exploited
103 ecosystems including fisheries and marine resources. In this section, the generic framework that
104 underlies ecoviability modeling in the four case studies is presented. The common mathematical

105 framework allows us to consider the problem of integrating multi-species, multi-fleet, dynamic
106 and uncertain socio-ecological systems while taking into account ecological and economic viabil-
107 ity goals or constraints which all constitute major ingredients for EBFM.

108 2.1 A multi-species multi-feet dynamic model

109 Marine social ecological systems are described by a set of n marine stocks exploited by m distinct
110 fleets. A state space formulation (Clark & Mangel, 2000) in discrete time is used to represent
111 the evolution of the ecosystem. Thus the n stocks whose states at time t are denoted by $x_i(t)$
112 are governed by the following controlled and uncertain dynamic equations

$$x_i(t + \Delta t) = g_i(x(t), e(t), \omega(t)), \quad (1)$$

113 from initial time $t = t_0$ to temporal horizon $t = T$ with time step Δt . The states $x_i(t)$ can poten-
114 tially be vectors of abundance or biomass at different ages or sizes or by sex. The global state $x(t)$
115 representing the community or ecosystem state is the vector of states $x(t) = (x_1(t), \dots, x_n(t))$.
116 The vector $e(t) = (e_1(t), \dots, e_m(t))$ is the control of the system through the effort (duration
117 or number of vessels) of the different fleets at time t . Alternatively, output controls through
118 catches could be used based on production functions as described below in equation (2). The
119 variables $\omega(t) = (\omega_1(t), \dots, \omega_p(t))$ represent the uncertainties affecting the dynamics of the sys-
120 tem through random fluctuations on species growth or recruitment, species interactions and
121 catchabilities. The growth functions g_i for each species (or groups of species) may account for
122 inter-specific competition and/or trophic interactions.

123 The catches $h_{ij}(t)$ of stocks $x_i(t)$ by fleet j depend on fishing effort $e_j(t)$ through the production
124 function

$$h_{ij}(t) = h_j(x_i(t), e_j(t), \omega(t)). \quad (2)$$

125 The harvest function $h_j = (h_{1j}, \dots, h_{ij}, \dots, h_{nj})$ of every fleet j accounts for the technical
126 interactions and bycatch which may occur and complexify the control of the system. Catches
127 can also be uncertain (depending on $\omega(t)$) because of random catchability for instance. See

128 appendix, sections A.3, A.4, A.5 and A.6 for more details for each case study.

129 **2.2 The ecoviability objectives**

130 The viability approach focuses on the safety and feasibility of controlled dynamics of the system
131 with respect to constraints or targets representing the good health, safety or sustainability of
132 the socio-ecosystem. These constraints can involve ecological thresholds as in the case of an
133 extinction threshold in population viability analysis (PVA) (Morris & Doak, 2003). Economics
134 constraints (guaranteed rent, food security, ...) can also be integrated as recently reviewed in
135 Schuhbauer & Sumaila (2016), thus allowing for multi-criteria and bio-economic analyses. Such
136 integrated viability objectives generally refer to a mix of the following ecological and economic
137 constraints.

First, an ecological requirement is considered through biological or ecological indicators $\text{Bio}(x(t), \omega(t))$ as follows:

$$\text{Bio}(x(t), \omega(t)) \geq \text{Bio}_{\text{lim}}. \quad (3)$$

138 The ecological indicators $\text{Bio}(x(t), \omega(t))$ correspond to biodiversity or biological metrics which
139 may typically encompass species richness, trophic index or measure of spawning biomass for
140 structured populations. They can also be uncertain because of stock measurement errors or
141 because of uncertainty with regard to ecological thresholds in fish population viability or in fish
142 communities. In that context, the threshold Bio_{lim} can stand for an ecological tipping point.

Second a food security objective is taken into account through the aggregated catch $H(t) = \sum_{i,j} h_{i,j}(t)$ which plays the role of food supply. Maintaining the food supply high enough with respect to the demand reads

$$H(t) \geq H_{\text{lim}}(t), \quad (4)$$

143 where $H_{\text{lim}}(t)$ refers to some basic need threshold which may be time-dependent typically because
144 of demographic growth.

Third, economic viability is captured through profitability of the fleets as follows

$$\text{Profit}_j(t) \geq 0. \quad (5)$$

Here the economic value $\text{Profit}_j(t) = \text{Profit}_j(x(t), e(t), \omega(t))$ relates to the profit of each fleet j computed as the difference between the revenues $\text{Inc}_j(t)$ derived from catches $h_j(t)$ and operating costs $c_j(t)$ associated with the fishing effort $e_j(t)$; namely

$$\text{Profit}_j(t) = \text{Inc}\left(h_j(t), \omega(t)\right) - c_j(e_j(t), \omega(t)).$$

145 Note that these income and cost values are also potentially affected by random uncertainties
 146 $\omega(t)$ because of market price and cost (e.g. fuel) fluctuations.

147 Such an ecoviability framework integrating biodiversity, productive and profitability require-
 148 ments helps overcome the apparent antagonism between ecology, often concerned with survival
 149 and conservation issues, and economic considerations, usually centered around the pursuit of op-
 150 timality and profitability (see below). In the bio-economic context, strong links have been shown
 151 to exist between viability approaches and notable steady states such as Maximum Sustainable
 152 Yield (MSY) or Maximum Economic Yield (MEY) (Béné *et al.*, 2001), the Rawlsian ‘maximin’
 153 approach (Doyen & Martinet, 2012) or precautionary approaches (DeLara *et al.*, 2007). A key
 154 mathematical tool for the analysis of viability is provided by the so-called viability kernel as
 155 illustrated by figure A.4 in the Appendix. The viability kernel corresponds to a safe space within
 156 the initial set of constraints where the system needs to remain to be viable and to remain so in
 157 the future. It exemplifies the need for anticipating viability crisis.

158 In contexts where uncertainties have a probabilistic nature, bio-economic viability can be de-
 159 fined as the fulfillment of constraints with a high enough probability (Doyen & De Lara, 2010);
 160 namely

$$\mathbb{P}(\text{Constraints (3), (4), (5) are fulfilled for } t = t_0, \dots, T) > \beta \tag{6}$$

161 where β corresponds to some prescribed confidence rate (99%, 90%, ...) and where the prob-
 162 ability \mathbb{P} is computed with respect to the uncertainty ω which summarizes stochasticities on
 163 communities dynamics (growth, species interactions), catchabilities or technical interactions,
 164 costs or prices.

165 **2.3 Fishing scenarios**

166 We assume that the historical trajectories of the system are given by a sequence of states $x(t)$
 167 and controls $e(t)$ until a current time denoted by t_0 . By contrast, effort scenarios consist in
 168 sequences $e(t_0), \dots, e(T)$ from current time t_0 to horizon T (typically $T = 2050$).

169 The first scenario of interest for the analysis is the 'baseline' (or status quo) scenario (SQS),
 170 where the control remains fixed at the level it is at t_0 :

$$\text{SQS:} \quad e(t) = e(t_0) \text{ for } t = t_0, \dots, T \quad (7)$$

171 The second scenario considered is the scenario that aims at maximizing the expected net present
 172 value of fishery returns. This scenario, denoted by NPVS is defined as follows:

$$\text{NPVS:} \quad \max_{e(t_0), \dots, e(T)} \text{NPV}(e) \quad (8)$$

where net present value $\text{NPV}(e)$ of a scenario of efforts $e = e(t_0), \dots, e(T)$ is defined by

$$\text{NPV}(e) = \mathbb{E} \left(\sum_{t=t_0}^T \rho^t \sum_{\text{fleets } j} \text{Profit}_j(t) \right). \quad (9)$$

173 Here \mathbb{E} refers to the expected value of returns with respect to uncertainty ω and ρ stands for
 174 the discount factor. The numerical method to compute this expected value and the optimal
 175 controls are detailed in the following section 2.4 devoted to metrics and in the Appendix A.1.
 176 Such a strategy turns out to be close to a dynamic MEY (maximum economic yield) strategy
 177 in the long run (Clark, 1990).

178 The third scenario, denoted hereafter by EVS, is the ecoviability scenario which corresponds
 179 to the strategy that maximizes the probability that the system remains viable from t_0 to horizon
 180 T with respect to the control (the fishing effort $e(t)$); namely

$$\text{EVS:} \quad \max_{e(t_0), \dots, e(T)} \mathbb{P}(\text{Constraints (3), (4), (5) are fulfilled for } t = t_0, \dots, T). \quad (10)$$

181 Such a formulation points to the fact that the viability approach, in a stochastic context, consists

182 in minimizing bio-economic risk or vulnerability. The appropriate effort strategies which ensure
 183 the viability of the system as solutions of the maximal viability problem (10) are given by
 184 feedback controls in the form of $e(t, x)$. This is due to the dynamic programming structure
 185 underlying the probabilistic viability problem, as stressed in Doyen & De Lara (2010). Such
 186 strategies enable adaptive management, accounting for uncertainties affecting the entire social-
 187 ecological system. The numerical method to compute this ecoviability probability value and
 188 the viable controls are detailed in the following section 2.4 devoted to metrics and in Appendix
 189 A.2. The scientific software SCILAB (<http://www.scilab.org/en>) has been used for both
 190 probabilistic simulations and optimization computations.

191 2.4 Ecological and economic metrics

192 This subsection introduces the metrics that will be used for the analysis and the comparison of
 193 the scenarios. The scores especially focus on ecological or economic viability probabilities and
 194 net present values ratio.

Net present value: The normative scenario NPVS defined in (8) is based on the expected net present value defined by

$$\text{NPV}(e, \omega) = \sum_{t=t_0}^T \rho^t \sum_{\text{fleets } j} \text{Profit}_j(t).$$

The numerical approximation of the expected value first relies on the mean over a finite number of replicates of the random variables $\omega(\cdot)$ underlying the uncertainties. In other words, we consider the following K replicates $\omega_k(\cdot)$ of random variables $\omega(\cdot)$ over time t_0, \dots, T

$$\left\{ \begin{array}{l} \omega_1(t_0), \dots, \omega_1(T) \\ \vdots \\ \omega_K(t_0), \dots, \omega_K(T), \end{array} \right.$$

and we approximate the expected value by its mean over the K replicates as follows

$$\mathbb{E}_\omega (\text{NPV}(e, \omega)) \approx \frac{1}{K} \sum_{k=1}^K \text{NPV}(e, \omega_k).$$

In order to compare the different case studies, the net present values are homogenized in the sense that the ratio between the net present value of every scenario and the maximal net present value (related to the NPVS) is computed as follows:

$$\text{INPV}(e) = \frac{\text{NPV}(e)}{\text{NPV}(e^{\text{NPVS}})} \quad (11)$$

195 where net present value is defined in equation (9) and e^{NPVS} stands for the optimal effort of
 196 the net present value scenario NPVS. Thus this ratio INPV is smaller than 1 in every case study.
 197 It takes the value 1 for the NPVS effort strategy.

Viability probability scores: The ecoviability probability underlying scenario EVS defined in (10) is computed in a similar way using the fact that the probability is the expected value of an indicator (boolean) function. More specifically, we rewrite the viability probability as follows

$$\mathbb{P}(\text{Constraints (3), (4), (5) are fulfilled for } t = t_0, \dots, T) = \mathbb{E} \left[\prod_{t=t_0}^T \mathbf{1}_C(x(t), e(t), \omega(t)) \right] \quad (12)$$

with the indicator function

$$\mathbf{1}_C(x, e, \omega) = \begin{cases} 1 & \text{if constraints (3), (4), (5) are satisfied} \\ 0 & \text{otherwise.} \end{cases}$$

198 Ecological viability probability $\mathbb{P}(\text{Constraint (3) are fulfilled for } t = t_0, \dots, T)$ and economic vi-
 199 ability probability $\mathbb{P}(\text{Constraints (5) are fulfilled for } t = t_0, \dots, T)$ that will be used in the com-
 200 parison of scenarios are particular instances of the general viability probability computed in
 201 (12).

Biodiversity metrics The ecological viability probability relies on biological, ecological or biodiversity indicators. The choice of biodiversity metrics remains the subject of numerous debates, with indicators ranging from structural indices, taxonomic or functional indicators to emblematic species. Regarding ecoviability studies for stylized models involving global biomass or abundances of species, the species richness index, the marine trophic index and the Simpson indicator have been used. The species richness denoted by SR is computed as follows:

$$SR(t) = \sum_i \mathbf{1}_i(x_i(t)), \quad (13)$$

with the boolean function

$$\mathbf{1}_i(x) = \begin{cases} 1 & \text{if } x \geq B_{\text{lim},i} \\ 0 & \text{otherwise.} \end{cases}$$

The marine trophic index MTI(t) of an ecosystem is computed as follows

$$MTI(t) = \frac{1}{N(t)} \sum_{i=1} T_i N_i(t) \quad \text{with abundances } N_i(t) = \frac{x_i(t)}{v_i} \quad (14)$$

202 where v_i is a fixed average weight by species and T_i is the trophic level of species i . The Simpson
 203 index SI complements the SR index by estimating the probability that two individuals belong
 204 to the same family or species.

205 For structured models, the use of indicators associated with the ICES precautionary approach
 206 and thresholds for the spawning biomass of fish populations gave important insights into the
 207 risks of stock collapse.

208 **3 Results as a synthesis of different case studies**

209 Ecoviability approach, models and scenarios constitute the original contribution of the paper.
 210 This section shows in particular the interest of such ecoviability modeling to operationalize
 211 EBFM by bringing together and comparing the bio-economic models and viability scenarios of
 212 four contrasted case studies including the small-scale fishery of French Guiana (South America),
 213 the small-scale fishery of Solomon Islands (Pacific), the Bay of Biscay multi-species demersal

214 fishery (Europe) and the Northern prawn fishery of the Gulf of Carpentaria (Australia). In this
215 section, the different case studies and EBFM contexts are first presented. Then the formalization
216 of the viability modeling approach for all case studies is described. The specific features of the
217 systemic and mechanistic models as well as the specific viability constraints related to the
218 four case studies are then listed. Bio-economic performances of viability scenarios for two case
219 studies are then compared graphically. Then it is shown how implementing a viability strategy
220 can lead for the four case studies to ‘win-win’ situations in terms of reduction of ecological and
221 economical risks. The paper also highlights some important differences of ecoviability scenarios
222 between more heavily regulated and less regulated fisheries in terms of economic risk as well
223 as effort reallocation. The viability models, scenarios and performances of these examples are
224 detailed in Doyen *et al.* (2012); Gourguet *et al.* (2013, 2014, 2015); Cissé *et al.* (2013, 2015);
225 Hardy *et al.* (2013).

226 3.1 Case studies

227 The geographical diversity of the four case studies involved in the analysis, ranging from South
228 America, Pacific, Europe to Australia, is useful to obtain generic findings. The following para-
229 graphs briefly describe the major features of these fisheries. Particular emphasis is put on
230 ecosystem challenges for these fisheries following Pitcher *et al.* (2009). While achieving EBFM
231 is a major objective for fisheries worldwide, these case studies exemplify the extent to which
232 the degree of EBFM implementation can significantly vary across countries. In that regard,
233 the description of the main differences and common features between these four case studies is
234 informative (Table 1). In particular, two groups can be distinguished: small scale (and coastal)
235 fisheries in Solomon islands and French Guiana; large scale (and more industrial) fisheries for
236 the Bay of Biscay and the Northern Prawn Fisheries.

237 **French Guiana Fishery:** The small-scale fishery operating along the coast of French Guiana
238 in South America is a multi-species and multi-fleet fishery landing about 3 000 tonnes per
239 year worth €9 million (\approx US\$ 9.78 million). Daily bio-economic data have been recorded by
240 IFREMER since 2006 (Cissé *et al.*, 2013). The fishery, which is highly diverse with about 30

241 exploited species such as weakfish species (*Cynoscion acoupa*, *C. virescens*, *C. steindachneri*, Sci-
242 aenidae), sea catfish species (*Sciades proops*, *S. parkeri*, *Notarius grandicassis*, Ariidae), grunts
243 (*Anisotremus surinamensis*, *Genyatremus luteus*, Haemulidae), snooks (*Centropomus undeci-*
244 *malis*, *C. parallelus*, Centropomidae), Giant grouper (*Epinephelus itajara*, Serranidae) and shark
245 plays a key socio-economic role for the local population, both in terms of livelihood and food
246 security. Recent demographic projections however indicate a likely doubling of the local human
247 population by 2030. Demand for local fish is therefore expected to increase substantially, with
248 some potential risk for the sustainability of the fishery and the local ecosystem's biodiversity.
249 The evaluation based on the Rapfish method proposed in Cissé *et al.* (2014) of the status of
250 this coastal fishery in terms of EBFM rates it a medium score and points to areas of potential
251 improvement among which discarding and capacity building of the supply chain are important.

252 **Bay of Biscay Mixed Fishery:** The Bay of Biscay demersal fishery is a multi-fleet, multi-
253 gear fishery targeting several species including Norway lobster (*Nephrops norvegicus*, Nephropi-
254 dae), European hake (*Merluccius merluccius*, Merlucciidae), Anglerfish and Blackbellied angler-
255 fish (*Lophius piscatorius* and *L. budegassa*, Lophiidae) and Common sole (*Solea solea*, Soleidae)
256 with high commercial values (Gourguet *et al.*, 2013). Its turnover amounted to € 200 million (\approx
257 US\$ 217 million) in 2009. The fishery, however, is under strong pressure, with several stocks al-
258 ready fully exploited. The fishery also operates within a context of high uncertainty with regard
259 to economic costs and biological dynamics. Additional management complexities are induced by
260 the many technical interactions associated with the multi-fleet nature of the activities (trawlers,
261 gillnets). Maintaining the bio-economic sustainability of these different components is thus diffi-
262 cult. A multi-annual management plan based on the recent European Common Fisheries Policy
263 (CFP) reform aims to achieve Maximum Sustainable Yield for all stocks before 2020 subject to
264 economic and social viability constraints. In addition, implementing the recently adopted land-
265 ing obligation (decided at the European scale) is a major challenge for this mixed fishery. The
266 fishery is managed by technical measures, access and quota regulations. Pitcher *et al.* (2009)
267 globally scored France a 'fail grade' in their evaluation of progress in implementing EBFM.

268 **The Australian Northern prawn fishery:** The Northern prawn fishery is one of Aus-
269 tralia's most valuable fisheries in terms of total landed value with AU\$ 91.6 million (\approx US\$ 71
270 million) in 2009-2010 involving 52 trawlers since 2007 (Punt *et al.*, 2010). This multi-species
271 and multi-fishing strategies trawl fishery targets several high-value species of tropical prawns,
272 each with different dynamics and levels of biological variability. The bulk of revenue is obtained
273 from high-valued but rather unpredictable white banana prawns (*Fenneropenaeus merguensis*,
274 Penaeidae) and two species of tiger prawns (Grooved tiger prawn, *Penaeus semisulcatus*, and
275 Brown tiger prawn, *Penaeus esculentus*, Penaeidae). The fishery's management objective is to
276 maximize economic yield, while accounting for biodiversity impacts. According to Pitcher *et al.*
277 (2009), Australian fisheries are well advanced in achieving EBFM. Furthermore, in certifying
278 the Northern prawn fishery in November 2012, the MSC (Marine Stewardship Council) acknowl-
279 edged efforts to limit fishing impacts on the ecosystem, although some concerns remain. Indeed,
280 while the mandatory introduction of Turtle Excluder Devices (TEDs) and By-catch Reduction
281 Devices (BRDs) played a major role in the MSC accreditation by significantly reducing by-catch
282 species such as turtle, syngnathid and sawfish, it only reduced the catches of sea snakes by 5%.

283 **Solomon Islands Fishery:** Solomon Islands are located at the extreme east of the coral tri-
284 angle in the Pacific. This region shelters the highest level of marine biodiversity in the world
285 (Burke *et al.*, 2012). The most recent Solomon Islands biodiversity assessment for instance ac-
286 counted for more than one thousand fish species for these islands (Green *et al.*, 2006). While
287 nearly all coastal dwellers fish for subsistence and self-consumption, an increasing number of
288 them now also engage in income-generating fishing activities. The most recent value of Solomon
289 catches (Brewer, 2011) estimates it at US\$ 21 million. This dual function (subsistence and
290 cash-generation) makes small-scale coastal fisheries a crucial element of the local socio-economic
291 system. Yet, the population of Solomon Islands has doubled in the last 20 years. This demo-
292 graphic trend and the subsequent increase in demand for fish, along with the increased marketing
293 of the output impose a growing pressure on marine resources and on the local ecosystem. The
294 pressure is especially strong on some key species such as groupers (*Serranidae*), parrotfish (*Scari-*
295 *dae*) and particularly on sea-cucumbers' species (*Holothuroidea*). To deal with such issues, a

296 community-based approach (Govan *et al.*, 2009) in line with the implementation of EBFM has
297 been promoted for the last 30 years. In that respect, WorldFish Center (2010) shows several
298 lessons of successful applications of EBFM in the main islands of the country.

299 **3.2 Formalization and calibration of models for the case studies**

300 The formalization of the four different bio-economic models used for the viability analyses has
301 been carried out following the generic modeling framework described in Section 2 and especially
302 the multi-species multi-fleet stochastic dynamics (1). However, beyond this common mathemat-
303 ical framework, two different approaches have been used regarding this formalization: For the
304 case studies of demersal mixed fishery of the Bay of Biscay and the Northern prawn fishery in
305 Australia, models were derived from available structured models (in class or age). In Solomon
306 Islands and French Guiana case studies for which no assessments were available, stylized bio-
307 economic models based on the global biomass of species (or groups of species) were developed.
308 The specific features of the systemic and mechanistic models related to the four case studies
309 are detailed in the four paragraphs below. They are also listed and compared in Table 2. More
310 mathematical details on the models are also provided in Appendices A.3, A.4, A.5 and A.6.

311 The parameterization of the four different models has also been achieved following two dis-
312 tinct approaches. For the case studies of demersal mixed fishery of the Bay of Biscay and the
313 Northern prawn fishery in Australia, calibrations were derived from available stock assessments
314 and economic data. In Solomon Islands and French Guiana case studies for which no assess-
315 ments were available, specific stock and bio-economic models were developed and fitted to the
316 available data. To validate the models and to show to what extent the estimated trajectories fit
317 the observed trajectories, graphs are displayed in the Appendix sections A.3, A.4, A.5 along with
318 figures A.1, A.2, A.3. A comparison of the estimated parameters, their number and underlying
319 data is provided at the bottom of Table 2.

320 **French Guiana:** The fishery population dynamics model used in this case is a multi-species,
321 multi-fleet dynamic model in discrete time (Cissé *et al.*, 2013, 2015). The model accounts for
322 trophic interactions between 13 exploited species and a fourteenth stock aggregating other marine

323 resources. The biomass of the species are assumed to be governed by a complex dynamic system
324 based on Lotka-Volterra trophic relationships and fishing effort of the different fleets. Daily
325 observations of catches and fishing efforts from the landing points all along French Guiana's
326 coast, available from January 2006 to December 2009, were used to calibrate the model. Esti-
327 mations of the parameters were carried out using a least-square method minimizing the distance
328 between observed and estimated catches. Data from the literature (Leopold, 2004) and Fishbase
329 (<http://www.fishbase.ca/>) were used to provide qualitative trophic information concerning
330 the sign of the relationship between species and intrinsic growth rates, and to initiate parameter
331 estimations.

332 **Demersal mixed fishery of Bay of Biscay:** As detailed in Doyen *et al.* (2012) and Gourguet
333 *et al.* (2013), population dynamics of the three species included in the analysis (hake, nephrops
334 and sole) were modeled using an age-structured population model. Parameters were derived
335 from stock assessments carried out by ICES (2009) using a virtual population model (Darby &
336 Flatman, 1994; Shepherd, 1999). The dynamic model was then fitted for each species separately,
337 using data on catch and abundance from surveys or derived from commercial CPUEs.

338 **Northern prawn fishery of Australia:** As described in Gourguet *et al.* (2014) and Gourguet
339 *et al.* (2015), three species of prawns were modeled using a size-structured population model
340 that operates on a weekly time-step. The parameters of this multispecies population model were
341 estimated using data on catches and effort, catch rates, as well as length frequency data from
342 both surveys and commercial landings (Punt *et al.*, 2010).

343 **Solomon Islands:** As in the French Guiana case study, the states of the stock are defined
344 in terms of the global biomass of different groups of species. The model is a multi-group,
345 multi-fleet dynamic model (Hardy *et al.*, 2013) which accounts for trophic interactions between
346 exploited species. The dynamics of the 8 groups included in the model is described through a
347 Lotka-Volterra trophic model accounting for fishing mortality from the several fleets involved in
348 the fishery. Different sources of information were used to parameterize the model. For the sea
349 cucumber and coral fish groups, parameters were calibrated based on data extracted from the

350 literature including Green *et al.* (2006) and FishBase. The parameterization of the model for
351 skipjack was carried out in two steps. First, a Western Pacific assessment (Langley & Hampton,
352 2008) was used to estimate the industrial fishery's parameters. Then, the model including all
353 fleets (industrial and artisanal) was fitted to data on catches from 1982 to 2006.

354 **3.3 Viability constraints of the case studies**

355 The different types of constraints applied to the four case studies presented in section 3.1 are
356 also compared (Table 3). Some of the viability constraints such as profitability constraints
357 are common to the four case studies, while others such as food security are specific to French
358 Guiana and Solomon Islands. The ecological constraints also differ between structured models
359 in Bay of Biscay or Northern prawn fishery where viability relies on precautionary thresholds
360 for stock biomass while more stylized models in French Guiana or Solomon Islands are based on
361 biodiversity metrics. Mathematical details regarding these viability constraints are also provided
362 in Appendices A.3, A.4, A.5 and A.6.

363 **3.4 Ecoviability scenarios**

364 As illustrated in figure 1 for the example of the Bay of Biscay and in figure 2 for French Guiana
365 case, eco-viable strategies satisfying dynamics in equation (1) and objectives specified in equation
366 (10) were identified for the four case studies. The blue diamond lines represent the estimated
367 historical paths while the viability thresholds are indicated in red triangle lines. The envelop
368 of all possible simulated trajectories accounting for the uncertainties is represented by the dark
369 dotted lines and the grey areas include 95% of the trajectories. The green (full) line within
370 the grey zone is one particular trajectory associated with one specific random selection. The
371 shocks underlying figures 1 and 2 are due to the change of fishing efforts induced by ecoviability
372 strategies: for the Bay of Biscay, the change occurs at the beginning of the scenario namely
373 2009 while, in French Guiana, the efforts are modified in 2011 and then in 2026 as a revision of
374 decisions is applied after 15 years. The figures illustrate how every ecological-economic constraint
375 is satisfied with a very high probability over time despite the complexities and uncertainties
376 affecting the social-ecological system.

377 **3.5 Viability performances of scenarios**

378 The ecological and economic viability probabilities of the status quo (SQS), net present value
379 (NPVS) and ecoviability (EVS) scenarios are displayed and compared for the four case studies
380 in figure 3. The graph shows that the status quo strategies SQS (grey granite dots) as defined in
381 equation (7) do not adequately cope with bio-economic risks in general in the sense that these
382 SQS offer only a low probability of meeting either the socio-economic viability constraint for Bay
383 of Biscay and French Guiana or both ecological and economic constraints for Solomon Islands.
384 The Northern prawn fishery is the only case displaying good scores from the viewpoint of both
385 ecological and economic risks since viability probabilities are close to 100%.

386 We also note that, in all case studies, ecoviability strategies EVS (blue degraded dots)
387 reduce ecological and economic risks, as compared to the SQS. The mitigation of ecological
388 and economic risks through ecoviability strategies EVS is not surprising since this EVS relies
389 on the maximization of the ecoviability probability. However, the magnitude of the viability
390 gains between EVS and SQS is not straightforward and varies according to the case study. In
391 the example of the Bay of Biscay fishery, the EVS leads to a strong increase in the probability
392 that socio-economic constraints will be complied with. This improvement is slightly smaller
393 for the French Guiana fishery. In Solomon Islands, the EVS leads to the strongest gain in the
394 management of both ecological and socio-economic risks. In the Northern prawn fishery, the
395 viability benefits are limited because the SQS already performs well as already pointed out. The
396 viability probability metrics thus provide informative and synthetic multi-attribute criteria to
397 grade the case studies in terms of EBFM. Moreover, the improvement associated with lowering
398 bio-economic and ecosystem risks decreases with the level of regulations already in place in
399 these fisheries: the Northern Prawn and the Bay of Biscay fisheries which are characterized by
400 higher levels of regulation than the French Guiana and Solomons Islands fisheries show lower
401 bio-economic and ecosystem risk reductions than those two other fisheries. This finding is likely
402 due to the fact that the regulatory frameworks already in place have been successful at reducing
403 some elements of these economic and/or ecological risks. For instance, fisheries in the Bay of
404 Biscay are managed by targeting MSY (Maximum Sustainable Yield) (ICES, 2009), while the
405 Gulf of Carpenteria prawn fishery is managed with a MEY (Maximum Economic Yield) goal

406 (Gourguet *et al.*, 2014).

407 **3.6 Synergy or tradeoff between risk and economic expectations**

408 The trade-offs between ecoviability and expected economic scores are investigated in figure
409 4. More specifically, the figure compares the scenarios according to both their ecoviability
410 probability and their mean economic performance in terms of net present values. From its very
411 definition, the ecoviability strategies EVS provide the largest probability for the fisheries to be
412 eco-viable. More interestingly, we note in figure 4 a) focusing on the two cases of small-scale
413 fisheries (French Guiana and Solomon Islands) that these EVS strategies also involve an increase
414 in mean annual economic performance of the fishery as compared to the status quo SQS. French
415 Guiana and Solomon Islands therefore appear to offer potential win-win strategies compared to
416 the current situations. In contrast, as displayed in figure 4 b) focusing on large scale fisheries,
417 the pursuit of ecoviability strategies in the Northern prawn fishery entails a trade-off between
418 co-viability and expected economic performance: meeting the inter-annual economic constraint
419 of positive profits in the Northern prawn fishery can only be achieved through a reduction in the
420 net present value. The case of Bay of Biscay is intermediary in the sense that adopting an EVS
421 strategy is a ‘win-no-loss’ situation as compared to the SQS because enhancing the bio-economic
422 viability is not detrimental to net present value. The global trade-off is even more apparent
423 when comparing the ecoviability strategies with the strategy aimed at maximizing the Net
424 Present Value of profits in the fishery (NPVS, red circle): in all four case studies, the pursuit of
425 ecoviability objectives entails lower mean returns than those which would be achieved by NPVS
426 strategies. Such a trade-off strongly relates to the mean-variance analysis, intensively used in
427 portfolio theory and finance, stressing the antagonism between mitigating risks and promoting
428 the mean (or expected) performances. Such a result exemplifies the idea that an EBFM relying
429 on viability probability criteria and on the mitigation of ecological-economical risks significantly
430 differs from bio-economic maximizing strategies underlying the net present value (NPVS), or
431 economic yield (MEY).

432 **3.7 Viable effort or vessels reallocation**

433 Ecoviability conditions were achieved in each case by adjusting the fleet fishing effort. The
434 control in the Bay of Biscay and the Australian case studies correspond to capacity adjustments
435 in the number of vessels, assuming that the fishing time per vessel remains constant. In both the
436 Solomon and the Guiana case studies, the adjustment takes place at the level of fishing time per
437 vessel or per fisher, assuming that the numbers of vessels/fishers in the fisheries remain stable.

438 Results differ according to the case studies and constraints. The efforts associated with the
439 ecoviability scenarios for the four case studies are detailed in Doyen *et al.* (2012); Gourguet *et*
440 *al.* (2013, 2014, 2015); Cissé *et al.* (2013, 2015); Hardy *et al.* (2013) and summarized in Table
441 4. It turns out that, in the Bay of Biscay and the Australian cases, ecoviability was achieved
442 by decreasing the capacity of the fleets (decrease in the number of vessels) while in both the
443 Guiana and Solomon examples, bio-economic viability was obtained by both increasing global
444 fishing effort and reallocating it between the different métiers. For instance, in Solomon islands,
445 the viability scenario relies on an important increase of the small-scale (inshore) tuna fishery
446 combined with reductions in sea-cucumber and reef fish fisheries. The global growth of efforts
447 obtained for the ecoviability of the two small-scale fisheries is mainly due to the food security
448 constraint implying increased global fishing intensities in the future. In Solomon Islands, the use
449 of FADs (fish aggregating devices) for skipjack tuna is also favorable to sustainability, stressing
450 the importance of technological innovation in enabling a re-allocation of effort towards more
451 sustainable levels per fish stock (Hardy *et al.*, 2013). More globally, ecoviability induces global
452 reallocations of fishing efforts due to an integrated, multi-species multi-fleet framework well
453 aligned with the holistic objectives of EBFM.

454 **4 Discussion**

455 **4.1 Ecoviability is globally well suited to EBFM.**

456 The central contribution of the paper is to synthesize the potential of the ecoviability modeling
457 approach to operationalize EBFM through different and contrasted case studies. We discuss

458 this assertion with respect to the three items proposed in Pitcher *et al.* (2009); Ward *et al.*
459 (2002), namely EBFM principles, EBFM criteria and EBFM implementation, to assess the per-
460 formances of fisheries with respect to the ecosystem approach.

461 In terms of EBFM principles, the ecoviability approach globally performs very well. A central
462 feature of the approach is indeed to suppose that ecosystems are complex, dynamic, that their
463 attributes and boundaries are constantly changing, in particular as they relate to the interac-
464 tions with human uses. Consequently a central aim of ecoviability is to maintain the structure
465 and function of ecosystems, including the biodiversity and productivity of natural systems.
466 Thus it clearly reverses the order of management priorities so that management starts with the
467 ecosystem rather than one target species. We discuss these EBFM principles and issues in a
468 more detailed way in the following subsection 4.2 devoted to models of intermediate complex-
469 ity. Another principle for EBFM requires human use and values of ecosystems to be central to
470 establishing objectives for the use and management of natural resources. In that respect, the
471 ecoviability approach considers that natural resources are best managed within a system based
472 on a shared vision and a set of ecological and socio-economic targets or constraints developed
473 amongst stakeholders. These multi-attribute and bio-economic principles of EBFM are exam-
474 ined in more detail in the following subsection 4.3 dedicated to sustainability and the triple
475 bottom line. Furthermore, viability management is adaptive through feedback controls espe-
476 cially accounting for uncertainties. This EBFM principle is discussed in the subsection below
477 4.4 focusing on adaptive management.

478 In terms of EBFM criteria, the ecoviability approach also performs well. First viability sce-
479 narios account for the policy and societal framework at play in every case studies in the sense
480 that management reflects national and international goals, objectives and constraints relating
481 to both conservation and sustainable use. Second, the social, economic and cultural context of
482 the fishery is incorporated by relying on acceptable bio-economic thresholds, tipping points and
483 precautionary boundaries. These dimensions are investigated in the following subsection 4.6
484 devoted to decision making for fisheries management. In particular ecological values are incor-
485 porated through biodiversity or biological viability constraints. This last issue is examined in
486 subsection below 4.5 related to the choice of biodiversity metrics. Furthermore, viable manage-

487 ment relies on the knowledge of utilized species through calibrated and dynamic models. Thus
488 the resource management system is comprehensive and inclusive, based on reliable data and
489 scientific knowledge. Again this is explained in 4.2 dealing with models and complexity. Finally
490 environmental and economic externalities are incorporated especially through stochasticities as
491 elaborated in the subsection 4.4.

492 Lastly, regarding EBFM implementation, we cannot assess this meaningfully in the case studies
493 as ecoviability management strategies are not currently in place. French Guiana could provide
494 however a good test-case in that regard in the future, as the implementation of such a strategy
495 is in progress with stakeholders. In the Bay of Biscay, ingredients of ecoviability are also in-
496 tegrated in current management since socio-economic viability constraints are indeed balanced
497 with MSY targets in practical management decision-making (Gourguet *et al.*, 2013). More glob-
498 ally, we discuss possible improvements of the approach in terms of implementation in subsection
499 4.7 regarding the need to integrate more clearly technical change within the models and sce-
500 narios. In subsection 4.8, we highlight the need to account for other management tools such as
501 quotas or protected areas.

502 **4.2 Ecoviability allows models of intermediate complexity adapted to EBFM**

503 The need to take into account the complexity of fisheries management problems especially in the
504 context of EBFM is now broadly recognized (Pahl-Wostl, 2007). Research and the case studies
505 presented here show that this can be done using an integrated, systemic modeling approach
506 that seeks to capture realistic features of marine social-ecological systems, but including only
507 the strictly necessary level of complexity. Such an approach based on multi-species, multi-fleets
508 dynamic models is in line with ‘models of intermediate complexity’ (MICE) as discussed in
509 Plagányi *et al.* (2014). MICE models such as those examined here make it possible to address
510 the ecosystem approach at intermediate scales between analytically tractable models used to
511 identify MEY-MSY approaches for single stocks, and higher dimensional and numerical models
512 attempting to capture the ‘end-to-end’ complexity of the social-ecological system at play. The
513 latter models are usually characterized by a more limited ability to derive the mathematical
514 properties of the system under consideration and may appear as ‘black boxes’. MICE being

515 ‘question-driven’, these models will tend to limit the complexity to only account for those com-
516 ponents of the social-ecological system required to address specific management issues. The
517 viability approach applied has hitherto largely been focused on stylized/simplified models, to
518 allow for analytical solutions. The applied work presented here demonstrates however the ap-
519 plicability of the viability approach to more realistic representations of fisheries systems, taking
520 account of their complexities and dynamics, notably via numerical simulations.

521 **4.3 Ecoviability directly deals with sustainability**

522 The ecoviability modeling framework used here involves an integrated, multi-functional and
523 multi-criteria approach in line with EBFM as in Béné *et al.* (2001); Doyen *et al.* (2012); Pereau
524 *et al.* (2012); Thébaud *et al.* (2014); Krawczyk *et al.* (2013); Maynou (2014). A wide range
525 of stakeholders are involved in fisheries and their management, including industrial, artisanal,
526 subsistence and recreational operators, suppliers and workers in related industries, managers,
527 environmentalists, biologists, economists, public decision makers and the general public. Each
528 of these groups has an interest in particular outcomes from fisheries and marine ecosystems, and
529 the performances that are considered desirable by one stakeholder may sound less desirable for
530 another (Hilborn, 2007). Considering this multi-attribute nature of marine fisheries management
531 is a way to guarantee a feasible and acceptable exploitation of aquatic resources, enabling the
532 conditions for sustainability from economic, environmental and social viewpoints as stressed by
533 Pope (1983). The present work is fully aligned with these considerations and the triple bottom
534 line nature (Brooks *et al.*, 2015) of sustainable development, as well as the multi-objective
535 principles stressed in EBFM. Moreover the use of thresholds, precautionary limits, reference or
536 tipping points underlying viability goals results in a simple and operational way to characterize
537 the safety and sustainability of marine ecosystems and fisheries.

538 Furthermore, by focusing on viability, the models presented in this paper exhibit manage-
539 ment strategies and scenarios that account for intergenerational equity. This is another impor-
540 tant ingredient of sustainability and sustainable uses of ecosystems underpinning EBFM. As
541 emphasized in Doyen & Martinet (2012), viability is closely related to the maximin (Rawlsian)
542 approach which gives key insights into intergenerational equity (Heal, 1998). In this respect,

543 the ecoviability strategies and scenarios link present and future performances, the various bio-
544 economic constraints being equally binding through time. This offers a substantial progress
545 compared to purely economic-oriented strategies such as the NPVS approach, which involves
546 discount factors and generally favor present or short-term performances. This result is particu-
547 larly illustrated in Gourguet *et al.* (2013); Cissé *et al.* (2013); Hardy *et al.* (2013) related to the
548 case studies examined in this paper.

549 **4.4 Ecoviability provides an adaptive management with respect to uncer-** 550 **tainties**

551 Accounting for uncertainties is a major challenge in ecosystem management. Uncertainties may
552 concern data measurements, ecological dynamics (climate variability, environmental stochastic-
553 ities) and anthropogenic dynamics (price variability, compliance, etc.). The use of stochastic or
554 probabilistic viability (Doyen & De Lara, 2010) as detailed in equation (10) provides a solid and
555 rigorous framework for detailed analyses of bio-economic risks, vulnerabilities and ecosystem
556 sustainability. In that vein, Gourguet *et al.* (2013); Mouysset *et al.* (2014) stand as important
557 illustrations. In addition, as stochastic viability is based on dynamic programming, it provides
558 closed loop (feedback) controls which enable adaptive strategies and scenarios with respect to
559 possible future states. Adaptability is also possible due to the multi-valued nature of viable
560 management strategies that focus on sets of possible strategies in contrast to optimal control or
561 equilibrium approaches which are usually unique or deterministic, and therefore less flexible.

562 **4.5 Ecoviability can capture the dynamics of biodiversity**

563 The ecosystem approach requires the use of biodiversity indicators to assess the ecological states
564 of communities and ecosystems, to track their temporal or spatial changes and finally to identify
565 drivers of changes. Unfortunately the choice of biodiversity metrics remains the subject of
566 numerous debates, with indicators ranging from structural indices, taxonomic or functional
567 indicators to emblematic species. For instance, analyzing the ecological state of lakes, Allen *et*
568 *al.* (1999) concluded that the taxonomic diversity index was an ambiguous indicator of biological
569 integrity when used alone. This conclusion may be broadened to structural indicators in the case

570 of marine fish communities (Blanchard *et al.*, 2001). In the case of marine fisheries, the relevance
571 of functional indicators such as the marine trophic level index and the average maximal size in
572 the community to detect some ecosystem effects of fishing can also be questioned (Blanchard *et*
573 *al.*, 2005).

574 Regarding ecoviability studies, the species richness index, the marine trophic index and the
575 Simpson indicator have been used, especially in the Guiana (Cissé *et al.*, 2013) and Solomon
576 Islands (Hardy *et al.*, 2013) case studies. For the Bay of Biscay and the Gulf of Carpenteria,
577 the use of indicators associated with the ICES precautionary approach and thresholds for the
578 spawning biomass of fish populations gave important insights into the risks of stock collapse.
579 More generally, it turns out that it is the combination of several ecological indicators, structural
580 and functional, instead of one unique universal biodiversity criterion that seems relevant to
581 evaluate the state of fish megafauna. In this respect, the multi-attribute nature underlying the
582 ecoviability approach has led to major advances strongly connected with criteria requirements
583 for EBFM. Indeed, this multi-criteria approach has been shown to facilitate the comparison of
584 alternative management options in cases where there may be uncertainty, and even disagreement,
585 regarding the selection of not only the indicators of system viability, but also of the thresholds
586 that define the viability space (Thébaud *et al.*, 2014).

587 **4.6 Ecoviability can represent the short term vs. long term choices**

588 As demonstrated on figures 1 and 2, the viability approach has allowed the identification of
589 strategies, through reallocation of fishing effort, that create or increase the social-ecological
590 systems viability over a certain period of time. French Guiana and Solomon Islands case studies
591 however also suggest that this viability can be maintained only for a limited number of years:
592 25 years in French Guiana (Cissé *et al.*, 2015), 35 years in Solomon Islands (Hardy *et al.*, 2013).
593 The two case studies therefore underline the long-term serious problem faced by these territories
594 which are already under intense demographic pressure. Based on the results of these analyses, it
595 appears that the mid-century population will be too high for the resource available, and that even
596 the options/innovations envisaged (e.g. the reallocation of a greater share of the fishing effort
597 toward the tuna resource through the introduction of FADs in Solomon Islands) will eventually

598 reach their limits. The 2050 decade is therefore likely to constitute a tipping point for these
599 islands under the assumption of constant demographic growth and current consumption habits.

600 Solomon Islands and French Guiana will therefore face important challenges -for which (even)
601 the viability approach seems challenged to find endogenous solutions. The marine resources of
602 these territories have a natural productivity limit which will eventually be reached unless an
603 overall dynamics shift occurs toward another regime. In our case, one possible shift is related to
604 demographics. In Solomon Islands, the hypothesis that such a shift might occur is not totally
605 unrealistic as data indicates that the local demography seems to decrease by 15% every decade.
606 In French Guiana, however, the recent Census suggests that such a change is not yet happening
607 (Cissé *et al.*, 2013). Such structural constraints, including demographic or technological, stress
608 the need for the ecoviability approach to adopt a more adaptive framework in line with MSE
609 (management strategy evaluation) accounting.

610 **4.7 Ecoviability can allow underlining the role of technical change**

611 As noted in Squires & Vestergaard (2013a,b), technical change in fisheries is a major driver of
612 the sustainability and viability of both fisheries and marine ecosystems and has to be integrated
613 into models aiming at operationalizing EBFM. Technological innovation in the long term will
614 affect not only the dynamics of the system but also alter and modify the ecoviability constraints.
615 These changes will possibly create more viability space in the way it has occurred with the in-
616 troduction of FADs in Solomon Islands (Hardy *et al.*, 2013). In other cases, however, economic
617 and technological changes may restrict this viability space. Gourguet *et al.* (2013) for instance
618 show how in the case of the Bay of Biscay, the projected increase in fuel price leads to a decrease
619 in the general viability of the fisheries.

620 More generally, the very general systemic, mechanistic and dynamic framework underlying equa-
621 tion (1) potentially allows for the introduction of capital dynamics and accounting for techno-
622 logical changes. In that respect, viability works proposed in Doyen & Martinet (2012) already
623 stress the role played by technical change and substitution between capital and natural resources
624 through the analysis of the Dasgupta-Heal-Solow model. One can also argue that the stochas-
625 ticity introduced in the models for the economic parameters (prices, costs) is a way to partially

626 capture the technical uncertainties.

627 **4.8 Ecoviability can rely on many fisheries management tools**

628 At this stage, it is worth stressing that other management controls should be investigated to
629 address and operationalize EBFM. To keep models simple, the emphasis in this paper has
630 been on fishing effort controls. However, the disadvantages of regulations relying on effort and
631 especially situations of technological creep on fishing effort and fishing mortality are well-known
632 (Wilén, 1979). Consequently, alternative managements based for instance on catch quotas,
633 transferable quotas (Chu, 2009) or marine reserve should be taken into account and examined
634 in the viability, co-viability or ecoviability framework. This has been done in others papers
635 and for other case studies showing that the viability modeling framework is flexible enough to
636 cope with such important management issues for the ecosystem approach. For instance DeLara
637 *et al.* (2012) deal with harvesting quotas while Pereau *et al.* (2012) address ITQ management
638 systems. Marine Protected Areas are investigated in Doyen *et al.* (2007). A simple change
639 enabling the movement from effort and input controls to catch and output controls consists
640 of using Schaeffer or Cobb-Douglas production functions. But this can be more complicated
641 in multi-species and multi-fleet contexts and in situations with non-compliance. In Pereau *et al.*
642 *et al.* (2012), the modeling principle is that the effort of agents (fishers or fleets) is adjusted in
643 a rational way (through optimization of rents) to comply with the level of harvesting quotas
644 supply. For the Bay of Biscay and French Guiana case studies, the implementation of such
645 ecoviability goals and approach associated with catch quota regulation strategies is an ongoing
646 work.

647 **5 Conclusions**

648 This paper has shown the extent to which the operationalization of EBFM via ecoviability mod-
649 eling of management strategies and scenarios can be relevant. From a methodological point of
650 view, major advances have recently been made regarding the use of this approach to sustain-
651 ability issues, in the contexts of multiple dimensional states (multi-species), controls (multi-fleet

652 fishing) and criteria (ecological, social and economic scores). The use of stochastic viability
653 modeling has also promoted a more realistic analysis of ecological-economic risks, vulnerabilities
654 and social-ecological system sustainability. From the decision support viewpoint, identification
655 of eco-viable scenarios in each case study provides important insights in terms of redistribution
656 of fishing effort and conservation measures.

657 The paper especially highlights that adopting an ecoviability strategy can lead to ‘win-win’
658 situations in terms of mitigation of ecological and economical vulnerabilities as compared to the
659 current situation. The paper also stresses some significant differences between more regulated
660 and less regulated fisheries when comparing a viability strategy to the current state (status
661 quo) in terms of economic expectation (mean) and risk (variance). For small scale fisheries,
662 ecoviability turns out also to be a ‘win-win’ option as compared to the current situation. By
663 contrast, a trade-off between economic expected value and risks is identified for large scale and
664 regulated fisheries. In other words, implementing an ecoviability strategy for large scale and
665 already regulated fisheries could be more difficult because some stakeholders could be reluctant
666 to adopt such a strategy based on bio-economic risk mitigation.

667 Many stimulating challenges remain. The study of social-ecological system resilience using
668 the tools of viability analysis appears particularly fruitful (Béné *et al.*, 2001; Deffuant & Gilbert,
669 2011) due to the insights it brings into recovery and restoration issues, and the ability of fish-
670 eries to cope with shocks. Moreover, a refined account of governance (Gutierrez *et al.*, 2011) and
671 EBFM implementation issues through game theory in the context of multi-agent viability also
672 appears very promising. Doyen & Pereau (2012); Pereau *et al.* (2012); Hardy *et al.* (2016) for
673 instance show that coordination strategies or structures (cooperative, community-based man-
674 agement or transferable quota market for large scale fisheries) between agents may improve the
675 bio-economic viability by inducing relevant changes in fishing efforts of different fleets. Although
676 the models in the current examples focus on ecological and economic objectives, the viability
677 models can also accommodate more social indicators as for instance in Pereau *et al.* (2012) where
678 a participation goal for the agents is imposed. Moving from modeling and management based on
679 input control (effort) to a management based on output control (catch) seems appropriate given
680 the current issues in fisheries governance. At this stage, the comparison of ecoviability strategies

681 with the MSY- MEY strategies that are commonly put forward at the international level should
682 be strengthened. The development of spatially explicit models, as initiated in Thébaud *et al.*
683 (2014), which integrate spatial controls of fishing pressure, including e.g. protected areas, is also
684 an important goal for ecoviability modelers with respect to the operationalization of EBFM.

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<http://www.worldfishcenter.org/content/community-based-adaptive-resource-management-solomon-islands-lessons-learned>

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- 1 Main common features and differences of the four fisheries. SSF: Small Scale fishery; IF: Industrial fishery; NPF: Northern prawn fishery. Notation ++ means a high level. Notation + means a weak level. Notation 0 means a nil level.
- 2 State space formulation: model features in terms of state, control, mechanisms and number of parameters for the four fisheries. FG: French Guiana, BoB: Bay of Biscay, NPF: Northern Prawn Fishery, SI: Solomon Islands.
- 3 Viability constraints and number of parameters taken into account in the viability metrics for the four case studies. Notation x means yes. Source for ICES precautionary limits <http://standardgraphs.ices.dk/stockList.aspx> and FAO
- 4 Ecoviability efforts changes as compared to status quo at the end of the scenario period for the four case studies. Notation ↗ means an increase and ↗↗ means a strong increase. Notation ↘ means a decrease and ↘↘ means a strong decrease.

Ecoviability

Case study	French Guiana	Bay of Biscay	Gulf Carpenteria	Solomon Islands
Notation	FG	BoB	NPF	SI
Scale	SSF	IF	IF	SSF
Data	++	++	++	+
Targeted biodiversity	++	++	+	++
	(≈ 30 species)	(≈ 10 species)	(4 prawn species)	(≈ 100 species)
Trophic Interactions	++	+	0	++
Metier diversity	+	+	0	+
Technical Interactions	++	+	+	+
Bycatch	+	+	++	0
Regulation	Limited entry	TAC (MSY) selectivity	Limited entry (MEY) Closure	
Food security issue	+	0	0	++

Table 1

Source	FG	BoB	NPF	SI
States $x(t)$	Cissé <i>et al.</i> (2015)	Gourguet <i>et al.</i> (2013)	Gourguet <i>et al.</i> (2015)	Hardy <i>et al.</i> (2013)
Control (effort) $e(t)$	14 fish species	3 fish species	4 fish species	8 fish groups
	4	16	1	3
	(fishing duration)	(number of vessels)	(number of vessels)	(fishing duration)
Maximum age or size structured A		9	41	
Time step Δt	month	year	week	week
Trophic interactions	+	0	0	+
Biological uncertainties	+	+	+	
Economic uncertainties	0	+	+	0
Species growth rates r_i	14			8
Species recruitment parameters		3	3x4	
Species mean weight v	13	3x9	3 + 4*41	8
Species proportions of mature individuals		3x9	4 x41	
Species interactions s_{ij}	14x14	0	0	6x6 + 2
Species mortality rates M_i		3x9	3	
Catchability $q_{i,k,a}$	13x4	3x16x9	1+3x2x41x52	3x8
Species discards $d_{i,k}$	0	3x16x9	0	0
Initial states $x(t_0)$	14	3x9	3 + 2*41	8
Initial effort $e(t_0)$	4	16	1	3

Table 2

		FG	BoB	NPF	SI	
Constraints	{	ICES precautionary limits B_{pa}		x	x	
		Targeted species richness	x			x
		Non valuable by-catch species			x	
		Food security	x			x
		Profitability	x	x	x	x
Number of parameters	{	Species trophic levels T_i	13	0	0	8
		Species prices p_i	13	3x9	2+ 2*41	8
		Fleet variable costs c_k^v	4	16	3	3
		Fleet fixed costs c_k^f	4	16	1	3
		Human demographic growth	1	0	0	1
		Replicates for stochasticity	100	1000	1000	1

Table 3

	FG	BoB	NPF	SI
Effort 1	(canot créole)	(nephrops trawlers)	(prawn trawlers)	(sea cucumber)
	↗↘	↘↘	↘	↘↘
Effort 2	(canot amélioré)	(fish trawlers)		(coral fish)
	↗	↘↘		↘↘
Effort 3	(pirogue)	(sole netters)		(inshore tuna)
	↗↗	↘		↗↗
Effort 4	(tapouille)	(fish netters)		
	↗	↘		
Total effort	↗↗	↘	↘	↗↗

Table 4

List of Figures

- 1 Bio-economic viability scenarios at the horizon $T = 2030$ of the Bay of Biscay demersal mixed fishery. Top: Spawning stock biomass of Norway lobster, European hake and Common sole; Bottom; Rents of two specific fleets (in €): nephrops trawlers (12-16 m) and various fish gill netters (> 24 m) fleets. The dark dotted lines and the grey field include 100% and 95 % of the trajectories, respectively. In red (triangle), the viability constraints; in blue (diamonds), historical data; in green (dark grey) a random trajectory. Source: Gourguet *et al.* (2013).
- 2 Bio-economic viability scenarios at the horizon $T = 2045$ of the French Guiana small-scale fishery for different bio-economic indicators. The dark dotted lines and the grey field include 100% and 95 % of the trajectories, respectively. In red (triangle), the viability constraints; in blue (diamonds), historical data; in green (dark grey) a random trajectory. On top: left: Species Richness; right: Marine Trophic index. Second row: Seafood Production. Third and fourth rows: profit of the four fleets. Source: Cissé *et al.* (2015).
- 3 Ecological viability probability $\mathbb{P}(\text{Constraint (3) are fulfilled for } t = t_0, \dots, T)$ versus economic viability probability $\mathbb{P}(\text{Constraints (5) are fulfilled for } t = t_0, \dots, T)$ for the four case-studies (BoB, FG, NPF, SI) and the three scenarios SQS (disk grey striped), NPVS (red circle with an empty disk), EVS (full disk degraded blue). In every case, the ecoviability scenario EVS performs better, reducing both ecological and economic vulnerabilities. The arrows point to the bio-economic gains in terms of viability, when moving from the status quo to ecoviability strategies.

- 4 Ratio of expected economic performance (Y-axis) INPV as in equation (11) and ecoviability probability (X-axis) $\mathbb{P}(\text{Constraints (3), (5), (4) are fulfilled for } t = t_0, \dots, T)$ as in equation (10) under the three scenarios SQS (full disk grey granite), NPVS (red empty circle), EVS (full disk degraded blue). By definition, the ecoviability scenario EVS performs better with respect to the co-viability probability. Symmetrically, as expected, the NPVS scenario performs better with respect to economic performance. The arrows in a) comparing the status quo and EVS strategies for small scale fisheries (FG, SI) show the bio-economic win-win situation between economic gain and probability of viability. By contrast, the arrows in b) focusing on large scale fisheries show the bio-economic trade-offs between economic gain and probability of viability, comparing the SQS and EVS strategies.

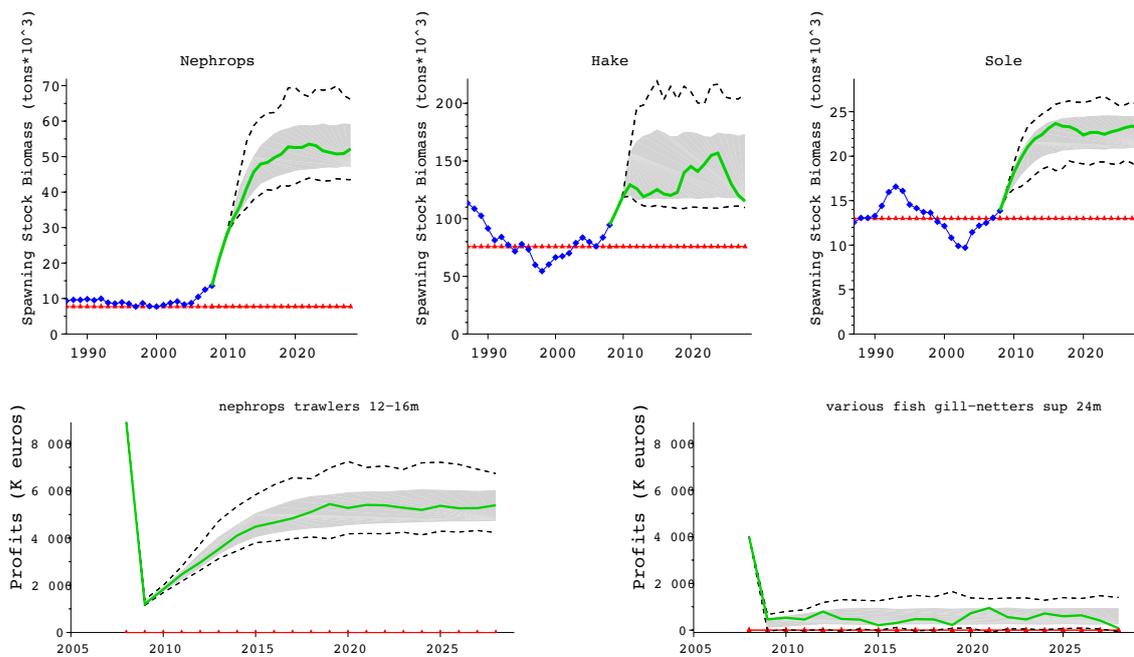


Figure 1

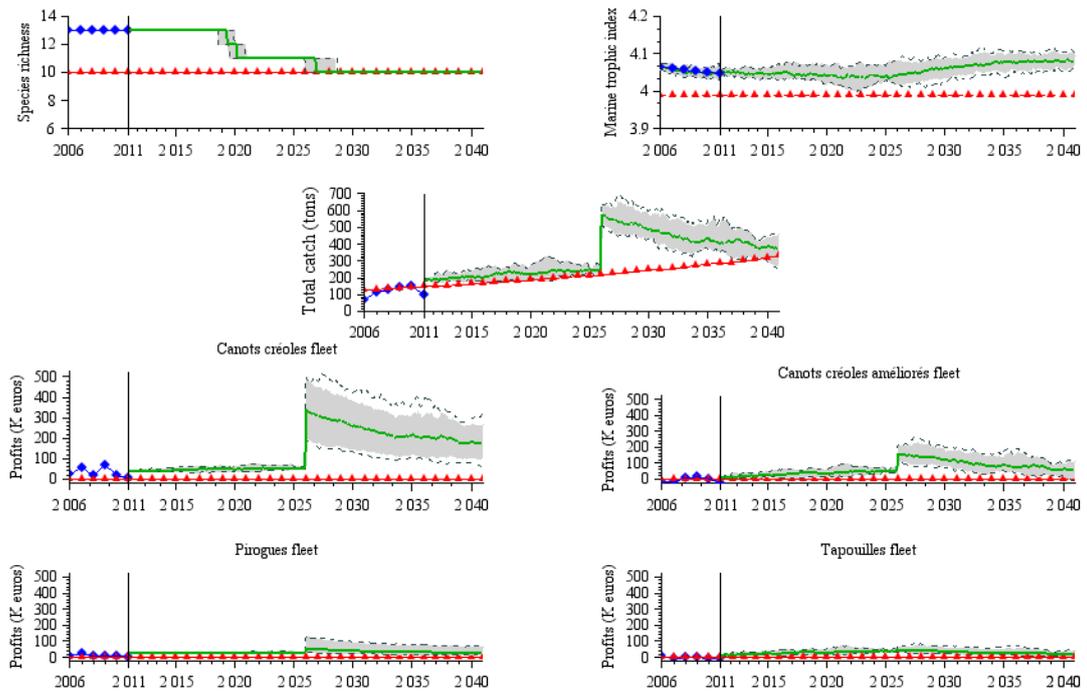


Figure 2

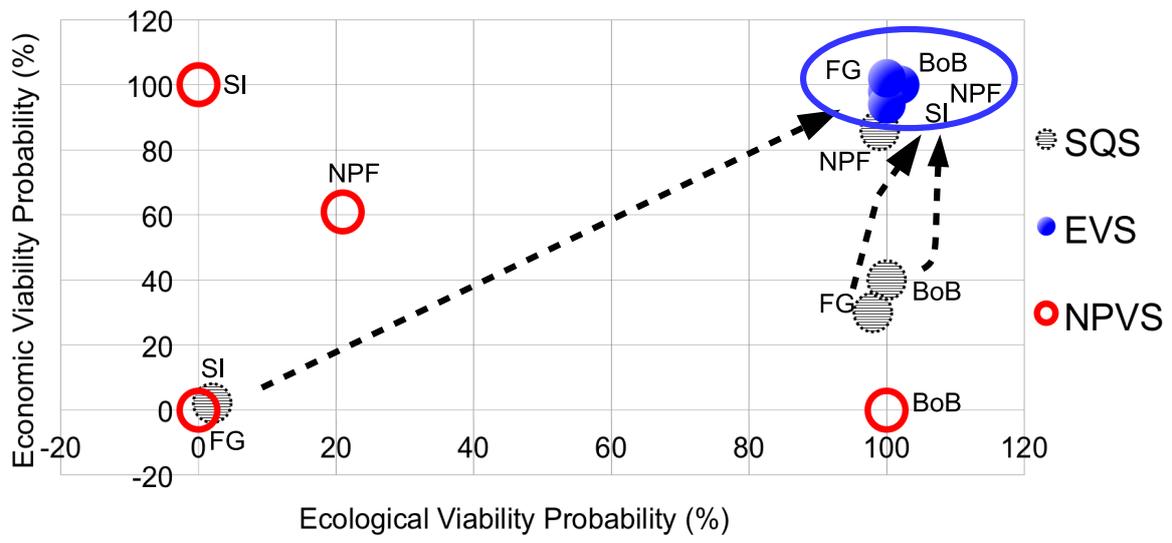
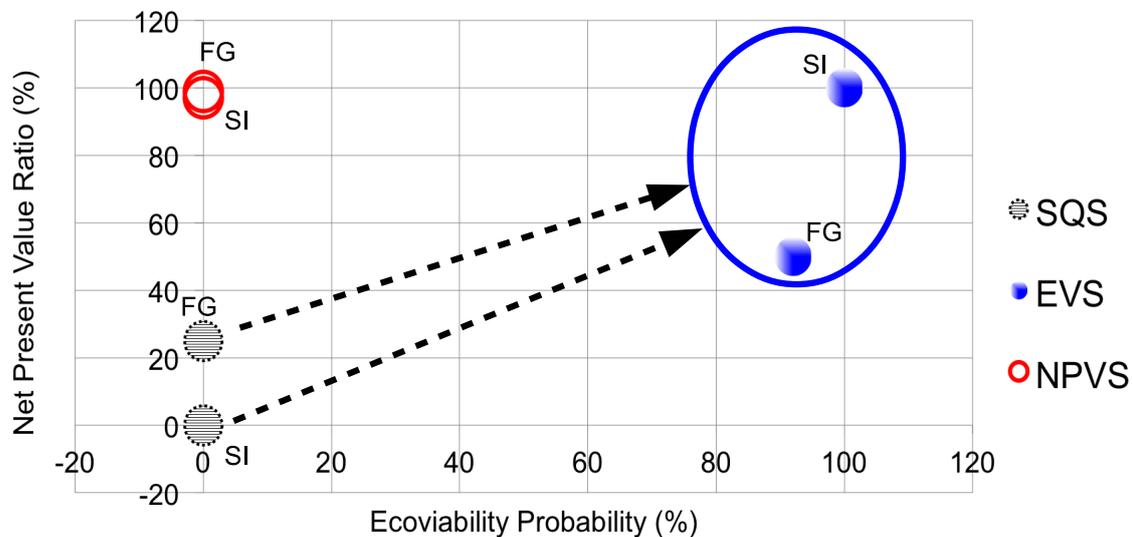
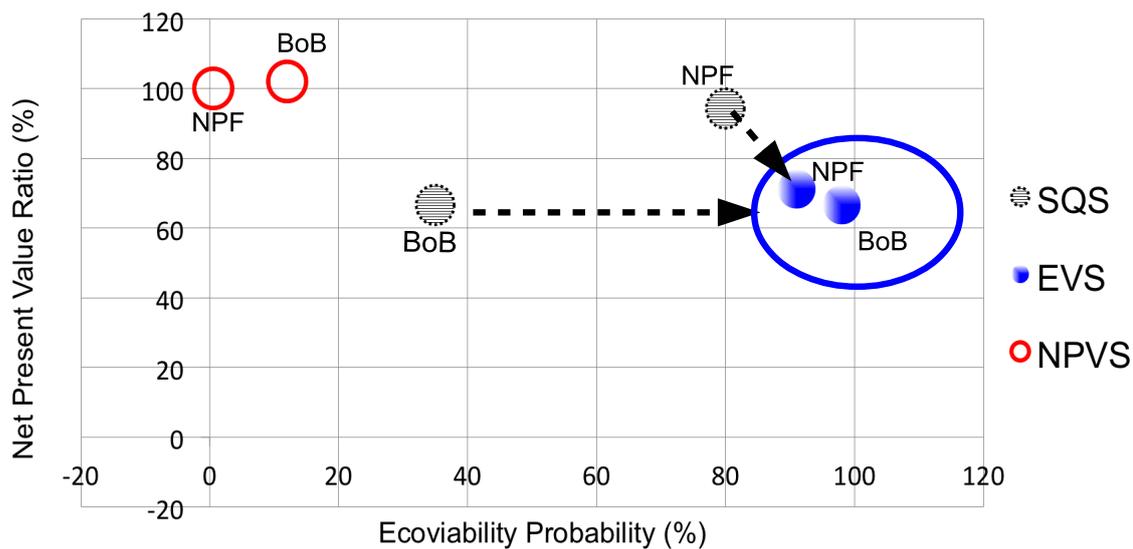


Figure 3



a) Small scale fisheries



b) Large scale fisheries

Figure 4

S Appendix

S.1 Computation of optimal expected value for scenario NPVS

The normative scenario NPVS defined in (8) based on the maximization of the expected net present value is defined as follows:

$$\max_{e(t_0), \dots, e(T)} \mathbb{E}_\omega (\text{NPV}(e, \omega)) \quad (15)$$

with the net present value

$$\text{NPV}(e, \omega) = \sum_{t=t_0}^T \rho^t \sum_{\text{fleets } j} \text{Profit}_j(x(t), e_j(t), \omega(t))$$

and where \mathbb{E} refers to the expected value of returns with respect to random variables ω and ρ stands for the discount factor. The numerical approximation of the expected value first relies on the mean over a finite number of replicates of the random variables $\omega(\cdot)$ underlying the uncertainties. In other words, we consider the following K replicates $\omega_k(\cdot)$ over time t_0, \dots, T

$$\left\{ \begin{array}{l} \omega_1(t_0), \dots, \omega_1(T) \\ \vdots \\ \omega_K(t_0), \dots, \omega_K(T), \end{array} \right.$$

and we approximate the expected value by the mean over the K replicates as follows

$$\mathbb{E}_\omega (\text{NPV}(e, \omega)) \approx \frac{1}{K} \sum_{k=1}^K \text{NPV}(e, \omega_k)$$

Using the scientific software SCILAB available online <http://www.scilab.org/en>, the replicates are obtained from the function entitled GRAND.

Regarding the way to compute the optimal control e , we have to distinguish between the case studies. For Bay of Biscay and NPF case studies, the control is kept fixed during the whole period $t_0, ..T$. But for French Guiana and Solomon Islands, the control can change and adapt to the uncertainty at several periods using optimal feedback controls and non anticipative strate-

gies. For two periods of decision, as explained in the Cissé *et al.* (2015), closed-loop efforts are solution of the following optimization problem

$$\max_{e(t_0)} \mathbb{E}_{\omega_0} \left[\sum_{t=t_0}^{t_1-1} \rho^{t-t_0} \text{Profit}(x(t), e(t_0), \omega_0) + \max_{e(t_1, \omega_0)} \mathbb{E}_{\omega_1} \sum_{t=t_1}^{T-1} \rho^{t-t_1} \text{Profit}(x(t), e(t_1, \omega_0), \omega_1) \right]$$

From a numerical point of view approximating the expected value by the average with respect to the $K = K_0 * K_1$ (K_0 in first period; K_1 in second period) replicates of ω gives

$$\max_{e(t_0)} \left\{ \begin{array}{l} \max_{e(t_1, \omega_{0,1})} \\ \vdots \\ \max_{e(t_1, \omega_{0, K_0})} \end{array} \frac{1}{K_0} \sum_{\omega_0 = \omega_{0,1}}^{\omega_{0, K_0}} \left[\sum_{t=t_0}^{t_1-1} \rho^{t-t_0} \text{Profit}(x(t), e(t_0), \omega_0) + \frac{1}{K_1} \sum_{\omega_1 = \omega_{1,1}}^{\omega_{1, K_1}} \sum_{t=t_1}^{T-1} \rho^{t-t_1} \text{Profit}(x(t), e(t_1, \omega_0), \omega_1) \right] \right.$$

The optimal control problem above then becomes a more usual mathematical optimization problem where the number of unknown variables is the number of efforts e multiplied by $(K_0 + 1)$. The feedback (adaptive) fishing effort controls at time t_1 are given by the different optimal $e(t_1, \omega_0)$ associated with the K_0 replicates of random variables ω_0 . To approximate this optimal value and identify optimal efforts with the scientific software SCILAB we used the optimizing function entitled OPTIM_GA.

S.2 Computation of optimal viability probability value for scenario EVS

Efforts in the Ecoviability EVS scenario defined in (10) are computed in a similar way using the fact that the probability is the expected value of an indicator (boolean) function. More specifically, we rewrite the viability probability as follows

$$\mathbb{P}(\text{Constraints are fulfilled for } t = t_0, \dots, T) = \mathbb{E} \left[\prod_{t=t_0}^T \mathbf{1}_C(x(t), e(t), \omega(t)) \right]$$

with the indicator function

$$\mathbf{1}_C(x, e, \omega) = \begin{cases} 1 & \text{if constraints are satisfied} \\ 0 & \text{otherwise.} \end{cases}$$

We compute the maximal viability probability as well as optimal controls associated with viability scenario using again the optimizing function in scilab entitled OPTIM_GA

S.3 Details of the model and data in French Guiana

Dynamic model: The fishery population dynamics model used in this case is a multi-species, multi-fleet dynamic model in discrete time as in Cissé *et al.* (2013, 2015). The model accounts for trophic interactions between 13 exploited species and a fourteenth stock aggregating other marine resources. The biomass $x_i(t)$ of the species i is assumed to be governed by a dynamic system based on Lotka-Volterra trophic relationships and fishing effort of the different fleets:

$$x_i(t+1) = g_i(x(t) - h(t), \omega_i(t)), \quad (16)$$

with growths and catches by species defined respectively by

$$g_i(x_1, \dots, x_n, \omega_i) = x_i \left(1 + r_i - \frac{r_i}{K_i} x_i + \sum_{j \neq i} s_{i,j} x_j + \omega_i \right), \quad (17)$$

$$h_i(t) = \sum_{k=1}^m h_{i,k}(t) = \sum_{k=1}^m q_{i,k} e_k(t) x_i(t). \quad (18)$$

In equation (17), r_i and K_i stand respectively for the intrinsic growth rate and the carrying capacity of the species i . $s_{i,j}$ is the trophic effect of species j on species i . The noise ω_i captures the environmental stochasticities affecting the growth of each species i at each step t . It is assumed that the random variables $\omega_i(t)$ follow a Gaussian law, independent and identically distributed : $\omega \rightsquigarrow \mathcal{N}(0, \sigma)$. The control $e_k(t)$ in equation (18) represents the fishing effort of fleet k (time spent at sea, in hour) and $q_{i,k}$ measures the catchability of species i by fleet k . The number of the fleet k (from $k = 1$ to $k = 4$) corresponds respectively to Canot Créoles, Canot Créoles Améliorés, Pirogues and Tapouille.

Calibration: The model calibration relies on monthly observations of catches and fishing efforts from the landing points all along the coast available from January 2006 to December 2010. Initial stocks, catchabilities, trophic intensities values of the ecosystem as well as the standard deviation of growth were estimated through a least square method. This method involved minimizing the mean square error between the monthly observed catches $h_{i,k}^{\text{data}}$ and the

catches $h_{i,k}$ simulated by the model as defined by equation (18):

$$\min_{x_0, s, q, \sigma} \mathbb{E}_\omega \left[\sum_{t=\text{January 2006}}^{\text{December 2010}} \sum_{i=1}^{13} \sum_k^4 \left(h_{i,k}^{\text{data}}(t) - h_{i,k}(t) \right)^2 \right]. \quad (19)$$

Figure (S.1) shows how catches generated by the calibrated model fit the historical catches by fleet.

Indicators: Regarding biodiversity metrics, the species richness and marine trophic indicators were selected. Species richness $\text{SR}(t)$ indicates the estimated number of species represented in the ecosystem. In our model, it is assumed that a species disappears whenever its biomass falls under a predetermined viability limit B_{lim} . This threshold B_{lim} which corresponds to a proxy of the ICES precautionary reference points is here set to 1/1000 of the initial biomass B_0 . The indicator SR is computed as follows:

$$\text{SR}(t) = \sum_i \mathbf{1}_i(x_i(t)), \quad (20)$$

with the boolean function

$$\mathbf{1}_i(x) = \begin{cases} 1 & \text{if } x \geq B_{\text{lim},i} \\ 0 & \text{otherwise.} \end{cases}$$

The marine trophic index $\text{MTI}(t)$ of an ecosystem is computed as follows

$$\text{MTI}(t) = \frac{1}{N(t)} \sum_{i=1}^{13} T_i N_i(t) \quad \text{with abundances } N_i(t) = \frac{x_i(t)}{v_i} \quad (21)$$

where v_i is a fixed average weight by species.

The total catches $H(t)$ within the fishery plays the role of food supply:

$$H(t) = \sum_k \sum_i h_{i,k}(t). \quad (22)$$

The profit $\text{Profit}_k(t)$ of each fleet k is derived from the landings of each species $h_{i,k}$, the landing prices $p_{i,k}$, fixed costs c_k^f , variable costs c_k^v and the crew share earnings c_k^L as follows:

$$\text{Profit}_k(t) = (1 - c_k^L) \left(\sum_i p_{i,k} h_{i,k}(t) - c_k^v e_k(t) \right) - c_k^f. \quad (23)$$

Prices, variable costs and fixed costs are those collected for year 2010. They are assumed to remain unchanged throughout the simulations. Variable costs c_k^v include fuel consumption, ice, food and lubricants. Equipment depreciation, maintenance and repairs are incorporated in the fixed costs c_k^f .

Ecoviability constraints: This ecological constraint is about maintaining both the SR index and the MTI above the minimum observed for the status quo scenario SQS defined in equation (7):

$$\text{SR}(t) \geq \min_{t=t_1, \dots, T} \text{SR}^{SQS}(t), \quad \text{MTI}(t) \geq \min_{t=t_1, \dots, T} \text{MTI}^{SQS}(t). \quad (24)$$

The food security constraint is linked to the ability of the fishery to satisfy the local food consumption. Consequently the food security reads

$$H(t) \geq H(2010) \cdot (1 + d)^t, \quad \text{for } t = t_1, \dots, T, \quad (25)$$

where d stands for the growth rate of the population and 2010 catches stand for the baseline. To analyze the economic risks, we define the profit constraint for every fleet at any time:

$$\text{Profit}_k(t) \geq 0, \quad \text{for } t = t_1, \dots, T, \quad \text{for every } k = 1, \dots, 4. \quad (26)$$

S.4 Details of the model and data in Bay of Biscay

Dynamic Models: As detailed in Gourguet *et al.* (2013), population dynamics of the three species included in the analysis (hake, nephrops and sole) were modeled using an age-structured population model. Parameters were derived from stock assessments carried out by ICES (2009) using a virtual population model. The model was then fitted for each species separately, using data on catch and abundance from surveys or derived from commercial cpues. Fish population dynamics are modeled using an age-structured population model derived from the standard fish stock assessment approach. Population dynamics are described on a yearly basis and integrate uncertainties regarding recruitment. The age-structured dynamics of the three species are governed by :

$$x_{i,a}(t+1) = x_{i,a-1}(t) \exp(-M_{i,a-1} - F_{i,a-1}(t)), \quad a = 2, \dots, A_i - 1 \quad (27)$$

where $x_{i,a}(t)$ stands for the abundance of the exploited species $i = 1, 2, 3$ (Nephrops, Hake and Sole, respectively) at age $a = 1, \dots, A_i$. Thus the state evolves according to both natural $M_{i,a}$ and total fishing $F_{i,a}(t)$ mortality rates of the species i at age a . Total fishing mortality of species i at age a $F_{i,a}$ is derived from the sum of fishing mortality from all 17 sub-fleets:

$$F_{i,a}(t) = \sum_{k=1}^{17} F_{i,a,k}(t) = \sum_{k=1}^{17} q_{i,a,k} e_k(t_0) K_k(t) \quad (28)$$

where $e_k(t_0)$ is the mean value of fishing effort by vessel of sub-fleet k expressed in number of days at sea and $K_k(t)$ is the number of vessels by sub-fleet k . The reference year is set at $t_0 = 2008$. The catchability $q_{i,a,k}$ corresponds to the fishing mortality of species i at age a associated with one unit of effort from a vessel of sub-fleet k . The parameter values are derived from the ICES databases.

The recruits $x_{i,1}(t+1)$ for each species are assumed to be uncertain functions of the Spawning Stock index (biomass here) $SSI_i(t)$ at time t :

$$x_{i,1}(t+1) = \phi_i \left(SSI_i(t), \omega_i(t) \right). \quad (29)$$

The Spawning Stock biomass $SSI_i(t)$ of the species i is given by:

$$SSI_i(t) = \sum_{a=1}^{A_i} \gamma_{i,a} v_{i,a} x_{i,a}(t), \quad (30)$$

with $(\gamma_{i,a})_{a=1,\dots,A_i}$ the proportions of mature individuals of species i at age a and $(v_{i,a})_{a=1,\dots,A_i}$ the weights of individuals of species i at age a . In the present case-study, the recruitment relationship of the species is set using an Ockham-Razor function:

$$\phi_i(SS I_i, \omega_i) = \begin{cases} \omega_i \rightsquigarrow \mathcal{U}_i & \text{if } SS I_i \geq B_i^{\text{lim}}, \\ SS I_i \frac{\bar{R}_i}{B_i^{\text{lim}}} & \text{if } SS I_i \leq B_i^{\text{lim}}. \end{cases} \quad (31)$$

Here \mathcal{U}_i stands for the uniform distribution relying on the historical time series of recruitment R_i^t of species i and the notation $\omega_i \rightsquigarrow \mathcal{U}_i$ means that the random variable ω_i is governed by the uniform probability distribution \mathcal{U}_i . Threshold B_i^{lim} is the ICES limit reference biomass and \bar{R}_i the mean historical recruitment values by species. The three species have different biology and life cycles, therefore their recruitments are assumed to be uncorrelated.

Calibration: Parameters underlying the dynamics (27) and (29) were derived from stock assessments carried out by ICES (2009) using a virtual population model. The model was then fitted for each species separately, using data on catch and abundance from surveys or derived from commercial CPUEs. Figure S.2 displays the comparison between the historical and simulated spawning biomass $SSI_i(t)$ for the three species at play.

Indicators: For each period t , the exploitation of the three species is described by the catches $h_{i,a,k}(t)$. These catches depend on initial fishing mortalities $F_{i,a,k}(t_0)$ and abundances $x_{i,a}(t)$ through the Baranov catch equation:

$$h_{i,a,k}(t) = x_{i,a}(t) F_{i,a,k}(t) \frac{1 - \exp\left(-M_{i,a} - \sum_{k=1}^m F_{i,a,k}(t)\right)}{M_{i,a} + \sum_{k=1}^m F_{i,a,k}(t)}. \quad (32)$$

The gross income from catches of each sub-fleet denoted by $\text{Inc}_k(t)$ is then estimated by introducing the market price of the species along with the estimates of discard rates, such that:

$$\text{Inc}_k(t) = \sum_i \sum_{a=1}^{A_i} p_{i,a}(t) v_{i,a} h_{i,a,k}(t) (1 - d_{i,a,k}). \quad (33)$$

where $v_{i,a}$ is the mean weight of landed individuals of species i at age a and $d_{i,a,k}$ represents the discard rate of individuals of age a by the sub-fleet k . Discard ratios were calibrated on the data available from the ICES working group WGHMM. Prices $p_{i,a}(t)$ correspond to the market value (euros by kg) of species i at age a for year t and are assumed to be uncertain. Uncertainties on annual market price by species are introduced through a random price by species following a Gaussian law as:

$$p_i(t) \rightsquigarrow \mathcal{N}(\mu_i^P, \sigma_i^P). \quad (34)$$

Gaussian laws are calibrated from ex-vessel prices for the three species for the 2000-2009 period, recorded in French harbours (data from Ifremer, SIH, DPMA). Prices by species $p_i(t)$ are assumed to be independent by species and by year. The profit Profit_k of a sub-fleet k is estimated as follows:

$$\text{Profit}_k(t) = \left(\text{Inc}_k(t) + \alpha_k K_k(t) e_k(t) \right) (1 - \tau_k) - \left(V_k^{\text{fuel}} p_{\text{fuel}}(t) e_k(t) + c_k^v e_k(t) + c_k^f \right) K_k(t). \quad (35)$$

Here the parameter α_k corresponds to the income per unit of effort of sub-fleet k derived from catches of species not explicitly modelled. We assume that biomass and price of other species are constant, and that the impacts of modelled fleets on these species are relatively negligible. Rate τ_k is the landing cost by sub-fleet as a proportion of the gross income. V_k^{fuel} corresponds to the volume of fuel (in litres) used by fishing effort unit (i.e. days at sea) for one vessel of sub-fleet k and $p_{\text{fuel}}(t)$ is the fuel price by litre of the year t that can be subjected to projection scenarios. The other variable cost c_k^v of a fishing effort unit by a vessel of sub-fleet k includes oil, supplies, ice, bait, gear and equipment costs while c_k^f corresponds to the annual costs associated with vessel of the sub-fleet k , including maintenance, repair, management and crew costs, fishing firms, licenses, insurance premiums and producer organisation charges. Cost parameter values

in the model are based on the economic data available for 2008 (Ifremer, SIH, DPMA) and are assumed to be constant over the simulation period.

Ecoviability constraints: Ecological viability is defined as the requirement that the Spawning Stock Biomass of each individual species is maintained above a threshold value. In this study, the thresholds correspond to B_i^{pa} , the biomass of precaution of the species i estimated by the International Council for the Exploration of the Sea. The constraint is specified as:

$$SSI_i(t) \geq B_i^{\text{pa}}, \quad i = 1, 2, 3. \quad (36)$$

We also consider the economic objective of maintaining positive profits for the sub-fleets over time as follows

$$\text{Profit}_k(t) > 0, \quad k = 1, \dots, 16. \quad (37)$$

S.5 Details of the model and data in the Northern prawn fishery

Dynamic Model: As described in Gourguet *et al.* (2014) and Gourguet *et al.* (2015), three prawn species in Australia’s Northern prawn fishery were modeled explicitly using a size and sex-structured population model (with Ricker stock-recruitment relationship and environmental uncertainties) that operates on a weekly time-step. The parameters of this multi-species population model were estimated using data on catches and effort, catch rates, as well as length frequency data from both surveys and commercial landings (Punt *et al.*, 2010). The dynamics of the three species are governed by:

$$x_i(t+1) = g_i\left(x_i(t), F_i(t), \omega(t)\right), \quad i = 1, 2, 3 \quad (38)$$

where $x_i(t)$ is the matrix of abundance $x_{i,sex,l}(t)$ of the exploited prawn species $i = 1, 2, 3$ (grooved and brown tiger and blue endeavour prawns, respectively) of sex female or male in size-class l alive at the start of time t which corresponds to one time step, i.e. one week. The dynamic function g_i accounts for species recruitment and mortality mechanisms of species i as detailed in Punt *et al.* (2010). $F_i(t)$ is the matrix of fishing mortality $F_{i,l}(t)$ of animals of species i and size-class l at time t and is derived from the sum of fishing mortality from the two tiger prawn fishing strategies:

$$F_{i,l}(t) = \sum_{k=1}^2 F_{i,l,k}(t) = \sum_{k=1}^2 q_{i,l,k}(t) e_k(t) K(y(t)), \quad (39)$$

where $e_k(t)$ is the mean value of fishing effort (in days at sea) by vessel associated with tiger prawn fishing strategy $k = 1, 2$ at time t , and $K(y(t))$ is the number of vessels involved in the fishery during the year $y(t)$ (which is the year¹ corresponding to the time t). Catchability $q_{i,l,k}(t)$ corresponds to the fishing rate of species i in size-class l associated with one unit of fishing effort of fishing strategy k (as in 2010) which depends on week t because the relative availability of species i varies with time. Recruits in the fishery for species $i = 1, 2, 3$ during a ‘biological’ year are assumed to be related to the spawning stock size index of species i for the previous

¹Year $y(t)$ is a function of week t , where weeks are numbered 1, . . . , 52, 53, . . . , 102, 103, . . .

year, according to a Ricker stock-recruitment relationship fitted assuming temporally correlated environmental variability and down-weighting recruitments, as described in Punt *et al.* (2010). The annual spawning stock size indices $SSI_i(y(t))$ of the three species i for the year $y(t)$ are calculated as in Punt *et al.* (2010) and are described by

$$SSI_i(y(t)) = \frac{1}{52} \sum_{t=52(y(t)-1)+1}^{52y(t)} \beta_i(t) \sum_l \gamma_{i,l} \frac{1 - \exp(-(M_i + F_{i,l}(t)))}{M_i + F_{i,l}(t)} x_{i,female,l}(t). \quad (40)$$

where $x_{i,female,l}(t)$ is the abundance of prawns of species i of sex *female* in size-class l alive at the start of time t , and M_i is the natural mortality of animals of species i . $\beta_i(t)$ measures the relative amount of spawning of species i during the time t , and $\gamma_{i,l}$ corresponds to the proportion of females of species i in size-class l that are mature.

A fourth prawn species, the white banana prawn is represented without an explicit density-dependence mechanism, due to its highly variable recruitment and in the absence of a defined stock-recruitment relationship. The biomass of this species is thus modeled as a uniform i.i.d. random variable, described by equation (41).

$$x_4(y(t)) \rightsquigarrow \mathcal{U}(B_4^-, B_4^+), \quad (41)$$

with $x_4(y(t))$ the stochastic biomass of white banana prawn for the year $y(t)$, and B_4^- and B_4^+ the uniform law bounds. Numerical values are given in Gourguet *et al.* (2014).

Indicators: Weekly catches $h_{i,l,k}(t)$ of species $i = 1, 2, 3$ in length-class l by tiger prawn fishing strategies ($k = 1, 2$); and annual catches $h_{i=4,k=3}(y(t))$ of prawn species $i = 4$ by banana prawn fishing strategy ($k = 3$) for the year $y(t)$ are defined by

$$h_{i,l,k}(t) = \sum_{sex=male}^{female} v_{i,sex,l} x_{i,sex,l}(t) F_{i,l,k}(t) \frac{1 - \exp\left(-M_i - \sum_{k=1,2} F_{i,l,k}(t)\right)}{M_i + \sum_{k=1,2} F_{i,l,k}(t)} \quad i = 1, 2, 3; \quad k = 1, 2$$

$$h_{i,k}(y(t)) = q_{i,k} x_i(y(t)) e_k(y(t)) K(y(t)) \quad i = 4; \quad k = 3 \quad (42)$$

with $v_{i,sex,l}$ the mass of an animal of species $i = 1, 2, 3$ and sex sex in size-class l . The annual gross income by fishing strategy $k = 1, 2, 3$ is calculated such that:

$$\begin{aligned} \text{Inc}_k(y(t)) &= \sum_{t=52(y(t)-1)+1}^{52y(t)} \left(\sum_{i=1}^3 \sum_l p_{i,l} h_{i,l,k}(t) \right), \quad i = 1, 2, 3; \quad k = 1, 2 \\ \text{Inc}_k(y(t)) &= p_i h_{i,k}(y(t)), \quad i = 4; \quad k = 3 \end{aligned} \quad (43)$$

where $p_{i,l}$ is the average market price per kilogram for animals of species $i = 1, 2$ and 3 in size-class l . The average price per kilogram of prawn species $i = 4$ is denoted by $p_{i=4}$. Total annual profit of the whole fishery $\text{Profit}(y(t))$ for year $y(t)$ is then formulated as follows:

$$\text{Profit}(y(t)) = \left(\sum_{k=1}^3 \text{Inc}_k(y(t)) \right) (1 - c^L) - \left(c^M \sum_{k=1}^3 \sum_{i=1}^4 h_{i,k}(t) \right) - \left(\sum_{k=1}^3 (c_k^v e_k(y(t))) + c^f \right) K(y(t)) \quad (44)$$

where c^L is the share cost of labour (crew are paid a share of the income) and c^M is the cost of packaging and gear maintenance (assumed to be proportional to the fishery catch in weight). The other variable cost c_k^v includes the costs of repair, maintenance, fuel and oil per unit of effort of fishing strategy k ; while c^f is the annual fixed cost by vessel (i.e. those costs that are not related to the level of fishing effort). More details are given in Punt *et al.* (2010) and Gourguet *et al.* (2014).

Total annual sea snake catch $h_{seasnake}(y(t))$ is considered as an indicator of the impacts of fishing on sea snakes. Annual sea snake catches are estimated based on data available in Banks *et al.* (2012) from linear regressions. To model a progressive adoption over time of more effective Bycatch Reduction Devices (Milton *et al.*, 2008), the coefficient values from the linear regressions are reduced progressively by 8.7% each year to have a total reduction of 87% (compared to the initial year) after a period of 10 years. More details are given in Gourguet *et al.* (2015).

Ecoviability constraints: Ecological viability is defined as the requirement that the spawning stock index of each individual species $i = 1, 2, 3$ is maintained above a threshold value. In this study the thresholds SSI_i^{lim} correspond to 50% of the 2010 spawning stock size indices, based

on a precautionary approach. The constraint is specified as:

$$SSI_i(y(t)) \geq S_i^{\text{lim}}, \quad i = 1, 2, 3. \quad (45)$$

We also consider a sea snake conservation objective which requires maintaining the catch of sea snakes below or equal to a maximum ‘allowed’ level:

$$h_{seasnake}(y(t)) \leq h_{seasnake}^{\text{lim}} \quad (46)$$

with $h_{seasnake}^{\text{lim}}$ the maximum allowed total catch of sea snakes set to the sea snake catch estimated with 2010 (i.e. reference year) effort levels.

The economic objective in this study requires maintaining a minimum total annual profit for the NPF such that:

$$\text{Profit}(y(t)) \geq \text{Profit}^{\text{lim}} \quad (47)$$

where $\text{Profit}^{\text{lim}}$ is set to 50% of the 2010 annual profit.

S.6 Details of the model and data in Solomon Islands

Dynamic Models: Following Hardy *et al.* (2013), the state of the socio-ecosystem corresponds to the biomass of eight fish families including the Holothurian $i = 1$, Serranidae $i = 2$, Lutjanidae $i = 3$, Lethrinidae $i = 4$, Acanthuridae $i = 5$, the Scaridae $i = 6$ and others coral-reef fishes $i = 7$ while the pelagic family $i = 8$ relates to the skipjack tuna and the Scombridae family. The dynamics of the eight fish groups are assumed to be governed by Lotka-Volterra type interactions and by fishing efforts associated with 3 fleets k including the fleet $k = 1$ associated with sea cucumber fishing, the fishing of the coral-reef fishes $k = 2$ and tuna fishing $k = 3$. Thus, the biomass $x_i(t + 1)$ of family i at time $t + 1$ depends on previous stocks' biomasses $x_i(t)$, fishing efforts $e_k(t)$ and labour intensity $L_k(t)$ of fleet k through the relation :

$$x_i(t + 1) = x_i(t) \cdot \left(1 + r_i + \sum_{j=1}^8 s_{i,j} \cdot x_j(t) - \sum_{k=1}^3 q_{i,k} \cdot e_k(t) \cdot L_k(t) \right) \quad (48)$$

with $x(t)$ in kg/m², $e_k(t)$ in hours/fishers, $L_k(t)$ in number of fishers. Parameter r_i stands for the intrinsic growth rate of the population i while $s_{i,j}$ is the trophic effect of family j on family i . The parameter $q_{i,k}$ measures the catchability on family i of fleet k .

The catch $h_{i,k}$ of stock i by fleet k at time t is given by:

$$h_{i,k}(t) = q_{i,k} \cdot e_k(t) \cdot L_k(t) \cdot x_i(t) \cdot \quad k = 1, 2, 3 \quad (49)$$

The total fishing effort is assumed to grow linearly since 2004 in proportion with the total population of the islands following a yearly demographic rate of $d = 2.14\%$ by year.

$$L_k(t) = L_k(2004)(1 + d)^t \quad (50)$$

Calibration: For the sea cucumber and coral fish groups, parameters were calibrated based on data extracted from the literature including Green *et al.* (2006) and FishBase. The parameterization of the model for skipjack was carried out in two steps. First, a Western Pacific assessment (Langley & Hampton, 2008) was used to estimate the industrial fishery's parameters.

Then, the model including all fleets (industrial and artisanal) was fitted to data on catches from 1982 to 2006 using a least square method. The free access Scilab software was used for the code and computation of the simulations. The figure S.3 displays the fitness between simulated and historical catches for the tuna.

Indicators: Species (family) richness SR and the Simpson index SI are used to depict structural aspects of the marine ecosystem. A family is here assumed to become extinct whenever its abundance falls below a minimum threshold set at a certain proportion of its initial biomass $x_i(0)$. The Simpson index SI complements the SR index by estimating the probability that two individuals belong to the same family.

The choice of economic indicators, a subsistence index and a cash index, reflects the dual function of fishing in the case study. The subsistence index computed per capita corresponds to the quantity of fish kept by households for self-consumption:

$$h_{\text{sub}}(t) = \sum_k \alpha_k \sum_i \frac{h_{i,k}(t)}{L_k(t)} \quad (51)$$

where α_k represents the shares of the catch kept for self-consumption. The other shares $(1 - \alpha_k)$ correspond to the share of fish sold on local or regional markets. Like the subsistence index, the cash index remains per capita:

$$\text{Profit}(t) = (1 - \alpha_k) \cdot \sum_i p_i \cdot \sum_k \frac{h_{i,k}(t)}{L_k(t)}. \quad (52)$$

with the prices p_i assumed to be fixed and the costs to be null. The proportion of fish retained by households for self-consumption averaged around 60% (i.e. 40% sold for cash). We therefore used this value for households' self-consumption of reef fish and tuna, i.e. $\alpha_3 = \alpha_2 = 60\%$. In contrast, $\alpha_1 = 0\%$ as sea cucumber is not consumed but only harvested for cash.

Ecoviability constraints: In this study the ecological constraint relates to the attempt to maintain the various fish families above their respective extinction thresholds (using the Simpson and Species Richness Indexes as indicators), while the economic and social constraints attempt

to ensure households food and cash security.

The ecological constraints are:

$$\left\{ \begin{array}{l} \text{SR}(t) \geq 0.9 \text{ SR}(2004) \\ \text{SI}(t) \geq 0.9 \text{ SI}(2004) \end{array} \right. \quad (53)$$

The levels of the two economic constraints (food and cash security) were defined by international standards. The food security constraint relies on a weekly amount of 0.8 g/kg protein per person and reads here

$$h_{\text{sub}}(t) \geq h_{\text{sub}}^{\text{lim}} = 2.1 \quad \text{kg/hh/week}$$

while the second economic constraint relies on the weekly basic need poverty line estimated at 47\$SB per household

$$\text{Profit}(t) \geq \text{Profit}^{\text{lim}} = 47 \quad \text{\$SB/hh/week}.$$

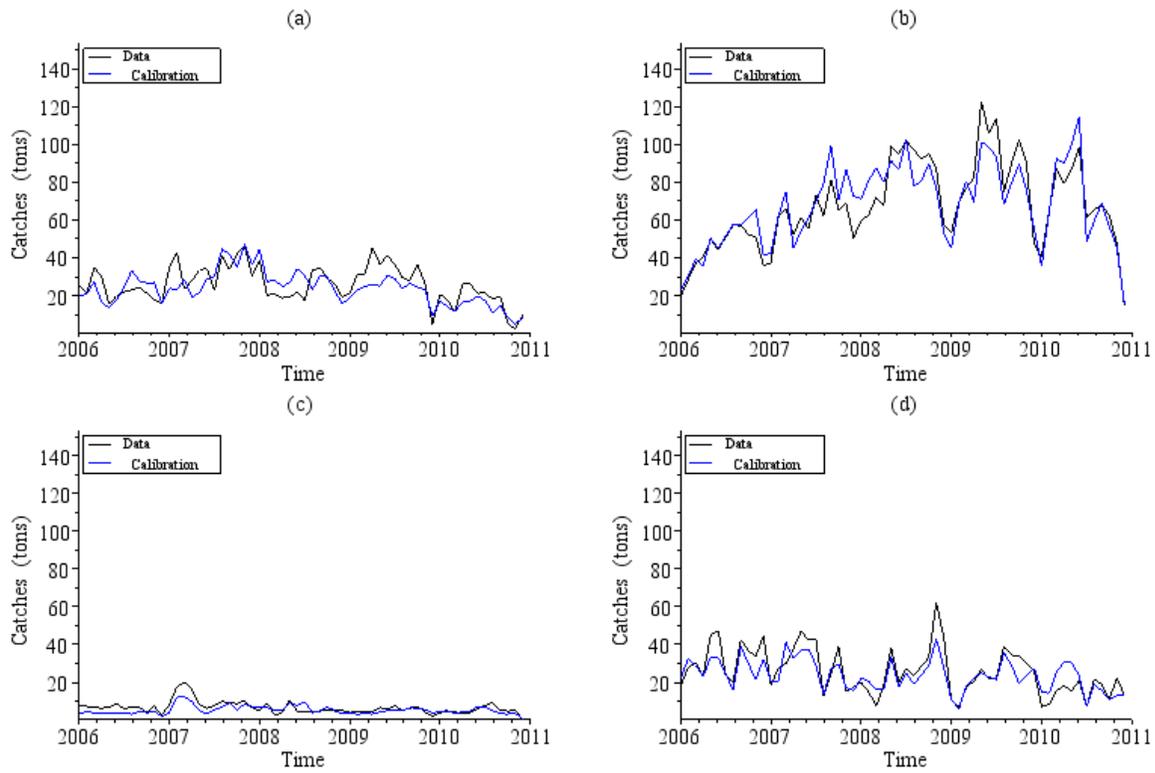


Figure S.1 – French Guiana: Comparison by fleet k between historical catches $\sum_i h_{i,k}^{\text{data}}(t)$ and simulated catches $\sum_i h_{i,k}(t)$.

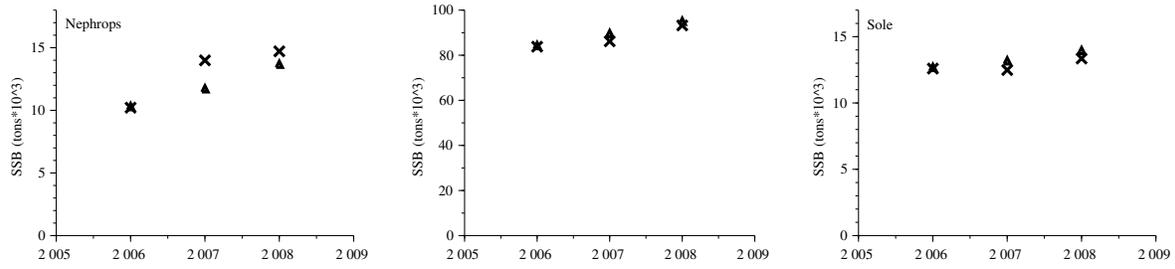


Figure S.2 – Bay of Biscay: Comparison between historical and simulated spawning biomass $SSI_i(t)$ for the three species at play over 2006-2008. Crosses stands for the historical values while the triangles stands for the values estimated by the model.

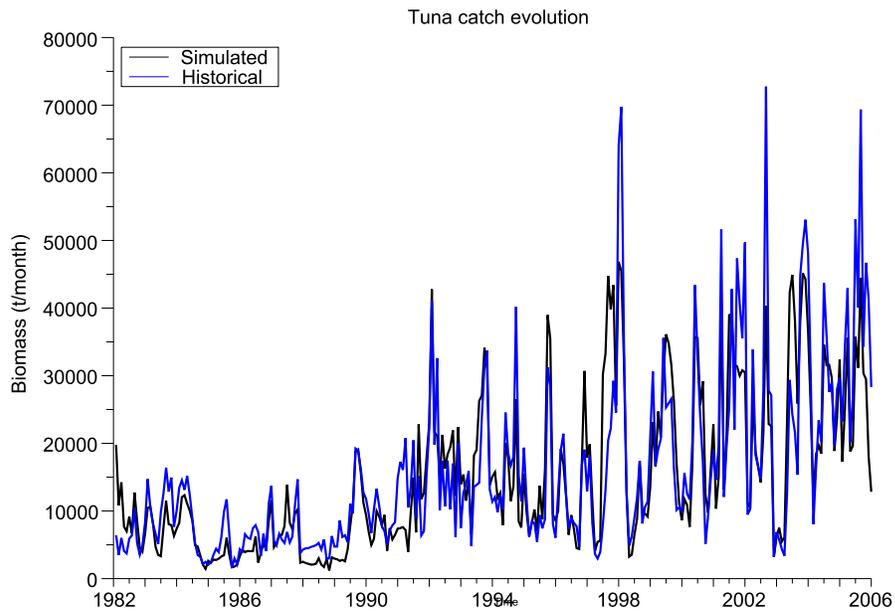


Figure S.3 – Solomon Islands: The historical $h_{8,3}^{data}(t)$ (in blue) and simulated catch $h_{8,3}(t)$ (in black) for the pole and line tuna fishery.

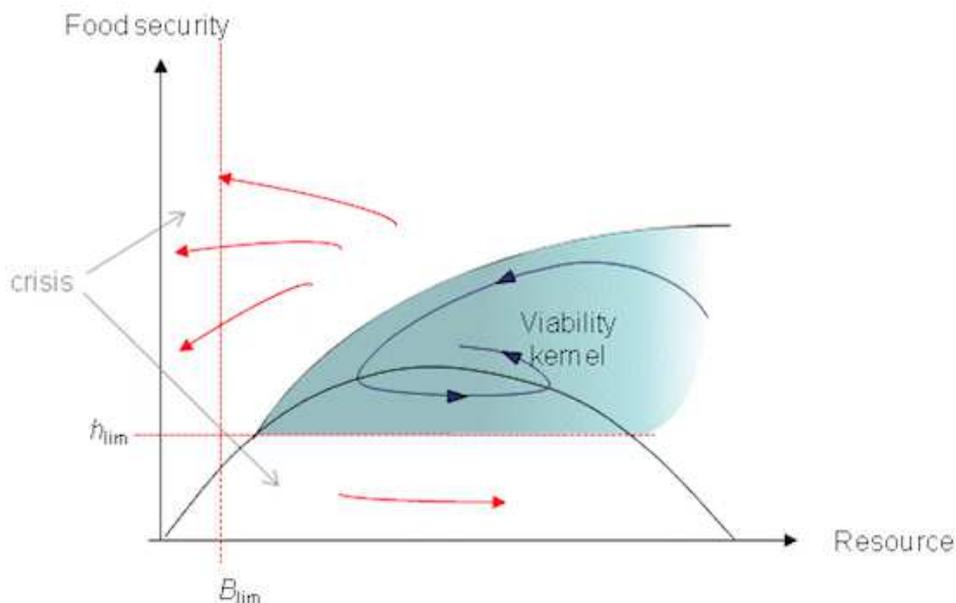


Figure S.4 – Viability kernel and bio-economic viability: In blue the viability kernel represents the set of initial conditions of the system which ensures that the controlled dynamics (illustrated by the system trajectories) will satisfy the viability constraints at any time. In the present case, (for sake of simplicity) we only represent two constraints: the ecological and food security ones (the economic constraint is omitted). These constraints are indicated on the diagram by the two green dotted lines and the associated two thresholds: B_{lim} and h_{lim} . Below these two thresholds the viability constraints are violated (the system is in crisis). Above the thresholds, for red trajectories, initial conditions are viable at $t = 0$ but the dynamics of the system is such that future crisis can not be avoided. Only within the viability kernel is the system viable and will remain so at any time in the future (blue trajectories).