An agent‐ **based model accurately predicts larval dispersal and identifies restoration and monitoring priorities for eastern oyster (** *Crassostrea virginica* **) in a Southwest Florida estuary**

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Abstract :

An agent-based modeling (ABM) framework was developed to support oyster reef restoration efforts in the Caloosahatchee River Estuary located within the encompassing Charlotte Harbor estuarine system, Southwest Florida. The modeling approach is novel for this shallow estuary which experiences heavily managed freshwater inflow known to be an ecological stressor to the estuary's oysters. The aims of the study were to (1) determine the ABM's accuracy in simulating larval dispersal patterns when compared with measured in situ larval settlement data; (2) establish connectivity patterns between various oyster reefs within the estuary; and (3) discover larval transport pathways within the Charlotte Harbor estuarine system. Key characteristics of the ABM, in particular the agents serving as simulated larvae, include settlement behavior and salinity tolerance and associated mortality. The ABM accurately recreated larval dispersal patterns during the peak spawning season, providing fundamental insight into the importance of protecting the furthest upstream oyster reef as a sustained larval source to the downstream reefs. Thus, supporting the effectiveness of using field measurements for the validation of ABMs and subsequently using ABM simulations to bolster future field studies. Ultimately, this study provides an effective, generally applicable, approach to model larval ecology for restoration purposes.

Keywords : ABM Lab, agent-based model, Caloosahatchee River Estuary, larval transport and dispersal, MIKE ECO Lab template, population connectivity

Implications for Practice

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- A novel approach to study oyster larval transport and dispersal within the Caloosahatchee
- River Estuary and the broader Charlotte Harbor estuarine system was performed using an
- agent-based model (ABM).
- The ABM incorporates agent (oyster larvae) settlement behavior and salinity related
- tolerances and mortality which, when validated with existing field data, provides insight
- into an upstream oyster reef as a vital larval source.

 • This study was able to develop a working, generally applicable modelling framework serving as the foundation for future modeling and field based studies focused on oyster reef restoration.

Introduction

 Oyster reefs have declined in many estuarine and coastal ecosystems from overharvesting, diseases, and deteriorated water quality (Beck et al. 2011). The once flourishing Chesapeake Bay oyster population has been reduced to 1 percent of its historical abundance from a myriad of issues (Rothschild et al. 1994). In 2012, Florida's Apalachicola Bay, a region producing 10 percent of the United States' annual oyster harvest, experienced an oyster fishery collapse attributed to low juvenile survival in the years prior to the collapse (Pine et al. 2015). Although the Caloosahatchee River Estuary (hereinafter CRE) does not support a commercial oyster fishery, the estuary's oyster reefs are valued ecosystem components (Chamberlain & Doering 1998; Barnes et al. 2007).

 Historically, the CRE (Fig. 1 cross hatch region) located in Southwest Florida supported extensive *Crassostrea virginica* (Eastern oyster) reefs; however oyster reef removal and man-made alterations to the estuary's hydrology have reduced the oyster population (Chamberlain & Doering 1998). Presently, CRE oysters experience vastly differing freshwater inflow depending on the season as Florida's subtropical climate produces wet (June-Oct.) and dry (Nov.-May) seasonal patterns. In addition, a lock and dam structure (S-79) controls 70% of the freshwater entering the estuary (Sun et al. 2016). Typically, freshwater releases from the dam are minimal during the dry season. In contrast, the estuary can be driven fresh by high inflow throughout the wet season (Chamberlain & Doering 1998) coinciding with the oyster's spawning period (late spring to early fall; Volety et al. 2015). Therefore, large pulsed and or sustained inflow may result in larval

 mortality, downstream larval flushing, and or larvae flushed entirely out of the estuary (Chamberlain & Doering 1998; Volety et al. 2015).

 Prior studies have been conducted within the estuary regarding inflow, oyster health, and habitat. Altered hydrology, including the unnaturally high and low inflow, has been identified as the key ecological stressor within the CRE (Barnes 2005). Barnes (2005) identified additional key CRE stressors (estuarine salinity, inflow, nutrient inputs, and physical alterations) which were implemented into a CRE habitat suitability index model (HSI). The HSI study by Barnes et al. (2007) found preferred inflow conditions (i.e. seasonally managed frequency distribution of inflow) and storing excess inflow in a constructed reservoir would provide more suitable habitat conditions than existing conditions without management. Volety et al. (2009) labelled the CRE oyster population at stage "caution" by accounting for biological responses (e.g. oyster density, larval recruitment, disease prevalence) and the estuary's hydrological conditions (temperature and salinity). Buzzelli et al. (2013) simulated potential oyster densities resulting from varying inflow thereby providing a range of inflow to promote healthy oyster densities. However, agent-based modeling of oyster larval transport (larval movement between two locations), considering the behavioral aspects of the agents (larvae), and dispersal (spread of larvae from spawning source to settlement site; Pineda et al. 2007) has not been conducted for the CRE and was recommended by Volety et al. (2015) as an important future study to better understand the influence of inflow on CRE oyster populations.

 Previous studies by Kim et al. (2010, 2013) in Mobile Bay, Alabama utilized a hydrodynamic and larval transport model along with field data to investigate Eastern oyster larval transport and dispersal patterns under both realistic and idealized physical transport scenarios. Those studies provided a better understanding of larval movement among Mobile Bay's various

 regions and associated oyster reefs, thus providing a management tool to aid in the development and implementation of oyster reef restoration strategies. The ability to predict larval transport and dispersal under different inflow conditions is critical to a highly managed system because interannual differences in inflow could shift the target for oyster reef restoration from upstream (dry years) to downstream (wet years). A system-wide approach should consider adult oyster suitability indicators such as salinity, reef elevation, food supply, and substrate availability (Barnes et al. 2007). Additional consideration is needed to determine reef connectivity and larval supply for restoring and maintaining estuarine oyster populations. The present study uses an agent-based model (ABM) comprised of a hydrodynamic model of the Charlotte Harbor estuarine system (Dye et al. 2020) and an ecological modeling module (MIKE ECO Lab; DHI 2017) to simulate oyster larval transport and dispersal within the CRE and the larger, encompassing Charlotte Harbor estuarine system hereafter CHES (Fig. 1). MIKE ECO Lab is a process-based customizable ecosystem modeling tool widely used to study the transport, dispersal, as well as foraging traits of various organisms such as eelgrass, coral larvae, starfish, sea birds, and marine mammals (Tay et 124 al. 2012; Elsäβer et al. 2013; Canal-Vergés et al. 2014; Heinänen et al. 2018; Kussemäe et al. 2018; Cavalcante et al. 2020). The MIKE ECO Lab model template created specifically for *C. virginica* oyster larvae was tested in its ability to simulate dispersal patterns observed in situ the CRE. Furthermore, simulated model outputs were used to: (1) establish the connectivity patterns between the monitored oyster reef sites and (2) determine larval transport within the CHES.

- **Materials and Methods**
- **Site Description**

The CHES is a large $(\sim 700-800 \text{ km}^2)$, shallow, subtropical estuary located in Southwest Florida with an average microtidal range of 0.6 m (Scarlatos 1998). Marine water from the Gulf of Mexico enters the estuary through various inlets (e.g., Gasparilla Pass, Boca Grande Pass, Captiva Pass, Redfish Pass, Blind Pass, San Carlos Bay; Fig. 1) between the barrier islands as well as San Carlos Bay. Freshwater enters the CHES by precipitation, watershed runoff, and three rivers; Myakka and Peace Rivers supply the northern portion while the Caloosahatchee River supplies freshwater to the southern region.

 Located in the southern region of the CHES, the CRE (Fig. 1 cross hatch region) has depths ranging from 0.3–6.0 m (1.5 m mean depth; Scarlatos 1988). Various man-made changes have altered the morphology and hydrology of the CRE. In the late 1800s the Caloosahatchee River was artificially connected to Lake Okeechobee (Flaig et al. 1998). Modifications continued as the Caloosahatchee River, originally a meandering river, was straighten and deepened, and three lock and dam structures were constructed to improve flood control measures of Lake Okeechobee (Sun et al. 2016). Additionally, the furthest downstream lock and dam (S-79) acts as a salinity barrier between the fresh river water and the estuary's brackish water (Chamberlain & Doering 1998; Sun et al. 2016). The CHES is unique because of the more natural conditions in the northern region as compared to the very unnatural, man-made conditions in the CRE portion of the system.

The Model

 This ABM presented in this study was built in ABM Lab, the Lagrangian module available in MIKE ECO Lab (DHI 2017), in order to describe Eastern oyster, *C. virginica*, larval transport within the CHES and more specifically larval transport and dispersal within the CRE (Fig. 1 cross hatch region). The Eulerian-Lagrangian modelling framework applied in this study consists of a MIKE 21 hydrodynamic flexible mesh model (HD) (DHI 2016) integrated with the MIKE ECO Lab (DHI 2017) ecological modeling module. The HD uses a finite volume method to solve shallow water, depth-integrated incompressible Reynolds averaged Navier-Stokes Equations (DHI 2016). The MIKE ECO Lab module provides a customizable model template for users to develop mathematical equations and descriptions of target species, including their behavioral tendencies, and the environmental parameters (e.g. state variables, constants, forcing). The physical environment was simulated by the HD and the Eastern oyster-specific mathematical equations and descriptions were customized in the MIKE ECO Lab template for the study area. The movement and environmental interaction of simulated oyster larvae, hereinafter referred to as agents, were modelled by the overarching ABM.

 The model description follows the ODD (Overview, Design concepts, Details) protocol (Grimm et al. 2006, 2010) for describing individual and agent-based models developed "to standardize published model descriptions in order to make descriptions more understandable and complete."

Purpose

 This ABM was developed to test the model's ability to numerically simulate measured Eastern oyster larval settlement at four monitored oyster reef sites within the CRE.

Entities, State Variables, and Scales

 Four groups of agents are simulated with each group representing one of the four oyster reef locations (Fig. 1, 1-4; Please see **Field Data - In situ oyster and larval characteristics** for description of reefs). Individuals of each group are characterized by their release site (1-4), position (x, y, z coordinates), and settlement status (i.e. settled or not settled onto Sites 1-4).

 An existing HD model of the CHES (Dye et al. 2020) generated the physical environment (time series of two-dimensional current vectors, surface water elevations, fluxes) for the ABM under the forcing of realistic wind, tide, and inflow. The HD spatial domain encompasses the entire CHES, all major tributaries, and extends 80 km offshore into the Gulf of Mexico (Fig. 2 A). The

 HD accurately simulates the system's water levels, tidal heights, and flow dynamics and has been used to study the circulation dynamics as well as the effect of inflow and wind on neutrally buoyant simulated particles within the system (Dye et al. 2020). The HD's flexible triangular mesh (FM) (DHI 2016) resolution is ~250 m within the focus area of the study (CRE), ~700 m in the surrounding estuarine regions, and increases to 2.7 km at the outer boundary (Fig. 2A & 2B). A more detailed model description is provided in Dye et al. 2020.

 Salinity was included in the ABM by interpolating in situ salinity data from 6 stations which are part of the RECON monitoring system [\(http://recon.sccf.org/\)](http://recon.sccf.org/) (Fig. 1, A - G) and 3 gauges deployed and maintained by the Charlotte Harbor Aquatic Preserve in Matlacha Pass (Fig. 1, H - J). Long-term salinity data were collected at each environmental monitoring site within the study area (Table S1; Fig. 1, A - J) and interpolated (distance weighted) into a high-resolution grid 190 for the model domain, grid resolution of \sim 200m (Fig. 2C). Hourly salinity values were extracted using the DHI MATLAB Toolbox [\(https://github.com/DHI/DHI-MATLAB-](https://github.com/DHI/DHI-MATLAB-Toolbox/blob/master/Documentation/DHI_MATLAB_Toolbox_User_Guide.pdf) [Toolbox/blob/master/Documentation/DHI_MATLAB_Toolbox_User_Guide.pdf\)](https://github.com/DHI/DHI-MATLAB-Toolbox/blob/master/Documentation/DHI_MATLAB_Toolbox_User_Guide.pdf). The resulting two-dimensional grids were converted into dfs2 file format and subsequently converted into a MIKE ECO Lab compatible file.

Process Overview and Scheduling

 The simulation was executed with an 8 second time step in the following order: hydrodynamics, advection-dispersion, salinity, agent sensitivity to salinity (discussed in section Sensing), agent movement (x,y,z), and agent settlement behavior (discussed in section Basic Principles).

Design Concepts

Basic Principles

 Agents were released in the model domain from the sites (Fig. 1, 1-4) found to be spawning during the study period (please see sections Field data and Simulation for further description). Every agent is considered a successfully fertilized zygote and therefore capable of development into a competent larva. During the simulation, every agent becomes competent (i.e. larvae has metamorphosed into the pediveliger stage thereby developing a foot to search for and subsequently attach (settle) onto hard substrate (Wallace et al. 2008)) to settle if the agent survives beyond the development period (Table 1).

 Four requirements must be fulfilled for an agent to successfully settle onto a mesh grid cell classified as a settlement substrate (Fig. 1, 1-4). (1) An agent has developed and gained competency, (2) an agent's x, y coordinates in a given model time step coincide with a settlement substrate, (3) the agent is less than 0.5 m away from the settlement substrate, and (4) the current velocity must be less than 1.0 m/s at the time step of settlement (Table 1). Once agents settle onto a settlement substrate, the agents are considered successfully settled and are no longer subjected to any mortality, natural or salinity-based (please see sections Sensing and Stochasticity for further details).

 Agent transport is regulated by current direction and velocities – both horizontal and depth- averaged vertical velocities – as well as settling velocities assigned to agents (Table 1). During the development period an agent is assigned a neutral buoyancy with a settling speed of 0 m/s. Once an agent has progressed through the development period and is thereby competent to settle, an agent is assigned a settling speed of 0.007 m/s (Table 1).

Adaptation

 After gaining competency, an agent will actively swim towards the benthic zone in a settlement attempt if the agent, in its current simulation time step, is located within a model mesh cell designated as settlement substrate (Fig. 1, 1-4).

Sensing

 Specific salinity tolerance ranges for agents and the complementing time durations were included in the MIKE ECO Lab template (Table 2). Agent salinity tolerance ranges (Davis 1958; Davis & Calabrese 1964) provide the lower threshold of salinity values before salinity timers are initiated. The required durations that agents must spend above each salinity threshold to reset the 231 duration timer were user-defined, however durations were largely based on the study by Kinne & Kinne (1962). If the salinity duration timer for an individual agent exceeds the maximum time in the corresponding salinity range (Table 2), the agent is classified as dead and removed from the simulation.

Stochasticity

 A constant horizontal dispersion value, based on hydrodynamic model resolution, was assigned throughout the model domain (Table 1) because of the importance of horizontal dispersion (i.e. transport from non-resolved turbulence or eddies in numerical models) in coastal and estuarine environments (Geyer & Signell 1992). No vertical dispersion was included in the template. Considering the shallow nature of the study area, it is safe to assume that horizontal dispersion is the primary mode of agent transport (Suara et al. 2018). Additionally, particle resuspension was activated in the ABM which forces agents contacting the benthic substrate back into resuspension unless the agents have settled onto a suitable substrate.

 To reduce the overestimation of agent survival (Connolly & Baird 2010; Tay et al. 2012), natural mortality, beginning at the time of agent release, was included by an age-dependent decreasing Weibull function mimicking a Type III survivorship curve (Pinder et al. 1978; Table 1).

Collectives

 One individual collective of agents is assigned to each of the four sites. No differences exist between the collectives apart from their release location from one of the four sites. All state variables and traits are consistent for all agents within the simulation, regardless of collective.

Observations

253 Outputs obtained from the model include agent location (x, y) , total surviving (i.e. non settled agents remaining in simulation) agents, and agent settlement assessed at each site (1-4). Outputs were saved every 1 hour, however only outputs at the final time step (conclusion of simulation) were used to determine transport patterns and for further comparison with field data collected from the study area.

Initialization

 Twenty-five hundred agents were released from the individual sites during the 25 day simulations, thus representing a typical larval duration (Kennedy 1996; Narvaez et al. 2012). Natural variability as well as uncertainty exists in the literature regarding the specific values chosen to represent the larval characteristics (e.g. larval salinity tolerance ranges) (Tay et al. 2012). Therefore, all values (Tables 1 and 2) were kept constant throughout each simulation to normalize comparisons between the different simulations.

Input data

 Forcing of this ABM model were obtained from the HD (water levels, current velocities and direction; Dye et al. 2020) and the two-dimensional depth-averaged salinity grids (Table 1).

Sensitivity Analysis

 Since it was unknown how many larvae were released at each site during the spawning periods, model sensitivity to the number of agents released was tested. The sensitivity analysis provided an understanding of any difference between larval recruitment success and number of larvae (agents) released. Sensitivity analysis was performed for August 2011 by releasing 2,500, 5,000, or 10,000 agents from Sites 1 and 3 in three separate simulations. The relative percentage of agent settlement at the Sites 1-4 were compared to determine any relative variability between simulations. Differences in percent total settlement at the four sites consisted of 1.04% between simulations releasing 2,500 and 5,000 and 0.38% between simulations releasing 5,000 and 10,000 agents (Table 3). This decreasing trend in the percentage of settlement with greater amounts of agents released occurred at Sites 2 and 3 with less than 0.46% differences in percent settlement between simulations (Table 3). At Sites 1 and 4, settlement percentage was lowest during the 5,000 agent release simulations. Minor differences in percent settlement of 0.02% occurred between simulations at Site 4 while greater differences of 0.16% resulted between simulations at Site 1 (Table 3). Sensitivity analysis provided evidence that greater amounts of agents released did not drastically enhance settlement and differences can be partially attributed to randomness in the stochastic processes of both dispersion and particle process descriptions. Therefore, it was decided to release 2,500 agents at the respective sites in each simulation.

Field Data - In situ oyster and larval characteristics

 A long-term (2000-2016), oyster monitoring study was performed by Volety et al. (2015) at four oyster reef sites (Fig. 1, 1-4) along the CRE's salinity gradient. Site 1 marks the farthest 289 upstream extent of living oysters, and Sites $2 - 4$ are situated progressively downstream within increasingly higher salinity regimes. Live oyster density is generally high, exceeding 800 291 oysters/ $m²$ at all sites except at Site 1 during years of extremely high inflow. Adult oysters are

 reproductively active in the summer months (May - October) with larval settlement subsequently peaking (June - November) and correlated with inflow (i.e. reduced settlement with high inflow; Volety et al. 2015). The 2011 field season provided larval settlement and histological analysis data used in this study.

 Larval settlement was evaluated monthly from the four sites by deploying three shell strings suspended within the water column, approximately 10-15 cm above the bottom of the estuary. Each shell string consisted of 12 oyster shells with a shell heights of about 5.0-7.5 cm, stacked inner shell surface oriented downwards, and suspended by galvanized wire via PVC poles (Volety et al. 2015). Field measurements of larval settlement were compared with simulated settlement to test the model's ability to accurately reproduce the measured settlement patterns.

 Histological analysis was performed to determine the reproductive state of oysters within the estuary using methods by Fisher et al. (1996) and the International Mussel Watch Program (1980). Each month, ten oysters were collected, analyzed, and assigned a value ranging from 1-5 indicating the oyster's gonadal condition. Gonad index values ranging from 4-5 were classified as oyster spawning events and subsequently used to determine from which site to release agents within the model simulations.

ABM Simulations

 Individual model simulations were performed for the months of July, August, and September 2011 with monthly simulation periods coinciding with observed site specific spawning 311 (Table 4). Agents were released synchronously on the $5th$ of each simulation month, one hour after the larger high tide, during the ebbing tide. Uncertainty in the timing of oyster spawning resulted in the decision to release agents on the ebbing tidal phase as it would provide the "worst case scenario" for larval retention within the estuarine system.

 Field measurements determining site specific spawning by means of histological analysis 316 were conducted within the first week of each month. The model release date $(5th$ of each month) was chosen to standardize the simulations and reduce field measurement bias as much as possible. Twenty-five hundred agents were released from the individual sites (Table 4; Fig. 1, 1-3) indicated by the field observations to be spawning based on the gonad index values. The simulations were conducted for 25 days to represent a typical planktonic larval phase (Kennedy 1996; Narvaez et al. 2012).

Comparison of Simulated and Observed Larval Settlement within the CRE

 In situ oyster settlement measurements (see **Field Observations -In situ oyster and larval characteristics**) were compared to the simulated settlement to test model performance in predicting observed settlement. However, simulated settlement does not account for post-larval settlement mortality (Osman et al. 1989; Narvaez et al. 2012) and cannot be directly compared to the observed measurements in terms of magnitude. Therefore, comparisons between simulated and observed settlement are in terms of trends, an ecologically viable method used by Narvaez et al. (2012), with differences indicating the potential importance of post-settlement mortality.

 Variability existed between element sizes of the hydrodynamic model's triangular mesh which serve as the available settlement substate at the sites (1-4). Therefore, to normalize the simulated settlement data, the total simulated larval settlement at each site were divided by the 333 site's settlement area (m^{\land}2 grid size) to calculate a settlement/m² value (e.g. settlement density).

Results

Percentage of Agent Survival and Settlement

 The percentage of agent survival at the end of each simulation period was calculated ((settled + non settled agents/total # of agents released) x100). Agent survival ranged from 13-

 16% with lowest survival during the July simulation and highest survival subsequently in August (Table 5).

 The percentage of agent settlement for each simulation was additionally calculated ((total settled/total # of agents released) x100; Table 5). Variability in percentage of settlement existed between the simulated months. The July simulation experienced the lowest settlement success with 1.2% of released agents successfully settling. Agents experienced the greatest settlement of 3.6% during August, while the September simulation had a settlement of 2.0%.

Comparison of Simulated and Measured Settlement

 Figure 3 displays settlement percentage comparisons between the measured (min = 3.3%, max = 47.0%) and simulated (min = 4.3%, max = 56.3%) settlement at each site for the individual monthly simulations. The pattern of increased measured settlement from Site 1 to 3 followed by a reduction at Site 4 is reflected in the simulated data. In July, measured and simulated percentages at Sites 1 and 2 differed by less than 6.3%, while greater differences (18.3%) were found at Sites 3 and 4. August and September display similar trends between measured and simulated settlement as July; however, with closer matches at Sites 1 and 3 as compared to Sites 1 and 2 in July (Fig. 3). Generally, the overall simulated settlement was greater than the measured settlement at Sites 1-3; however, measured settlement was always greater at Site 4.

 In order to test how well the ABM performs overall in simulating specific site settlement, comparisons between the percentage ((total settlement from each simulation at a specific site/total settlement from each simulation at all sites) x100; e.g. (July + Aug. + Sept. settlement at Site 1)/ (July + Aug. + Sept. settlement at all sites) x100) of total measured and simulated settlement at each individual site are presented in Figure 4. At Site 1, both measured and simulated total settlement exhibit similar percentages. The measured and simulated settlement at Sites 2 and 3 are

 within 11.2% of each other, with a lesser proportion of measured settlement at both sites. Although the simulated settlement is underestimated compared to the measured at Site 4, a trend of increasing settlement from Site 1 to 3, followed by a reduction in settlement from Site 3 to 4 is found in both measured and simulated settlement. The ability of the simulations to acceptably reproduce measured settlement allowed connectivity patterns between the sites to be examined.

Connectivity Patterns

 Agents were released from Sites 1 and 3 in the July 2011 simulation (Table 4). Self- recruitment dominated at Site 1 with 67.0% of the total settlement being agents released from Site 1 (Fig. 5). Similarly, total settlement of 75.0, 63.0, and 80.0% at the downstream Sites 2-4 respectively, resulted from agents released from Site 1 thus indicating downstream movement of agents (Fig. 5). Once again, agents were released from Sites 1 and 3 in the August simulation (Table 4). The percentage of agent settlement in the August simulation were similar to the July simulation except settlement at Site 4 consisted entirely of agents released from Site 1 (Fig. 5). In contrast to the other simulations, agents were released from Sites 1, 2, and 3 in the September simulation (Table 4). Settlement at Site 1 consisted entirely of self-recruited agents while settlement from Site 1 agents progressively diminished moving downstream, as agents released from Site 2 made up 14.0, 9.0, and 38.0% of total site settlement at Sites 2-4, respectively. However, settlement at the downstream sites was still dominated (50-64%) by the downstream movement of agents released from Site 1 (Fig. 5).

Agent surplus

 The present study termed "agent surplus" as non-settled agents present at the completion of each simulation. Percentage of agent surplus was calculated in each region (identified by colored regions in Fig. 6) by dividing the number of agents in each region by the total number of agents

 remaining in the simulation. Overall, the percentage of agent surplus displayed similar trends between the three simulations, with the greatest variability existing in the Charlotte Harbor and Gulf of Mexico regions. In each simulation, 56.9-65.7% of the agent surplus existed within the Gulf of Mexico (Fig. 6 dark blue) as agents were transported out of the system through various inlets. Pine Island Sound (Fig. 6 blue) and Matlacha Pass (Fig. 6 red) contained 13.0-15.4 and 8.9- 10.9% of the total surplus, respectively (Fig. 6). Surplus in the CRE (Fig. 6 black) was consistently less than 2.5% (Fig. 6). Charlotte Harbor (Fig. 6 yellow) received 7.7 and 8.9% of the surplus in the August and September simulations, respectively, with 18.8% surplus in July (Fig. 6).

Discussion

 The study's promising results serve as a proof of concept that this ABM model can be used as a viable tool for simulating oyster transport and dispersal dynamics, considering salinity stress and behavioral aspects of the agents (oyster larvae). Agent survival and settlement data shows that greater settlement percentage resulted with greater agent survival, which was to be expected as a larger number of surviving agents would increase the chances of settlement. An in-depth analysis of the influence of inflow, salinity, and resulting agent survival and settlement is beyond the scope of this study. However, it is interesting to note that the lowest percentage of agent survival and settlement occurred in July which also had the lowest minimum, maximum, and mean inflow as compared to the other simulation months; while the August simulation with the greatest agent survival and settlement percentages had the greatest mean inflow (Table 5). It was expected that the simulation month with the greatest inflow (causing reduced salinity) would have resulted in the lowest agent survival and subsequent settlement. However, these interesting and unexpected results warrant further investigation in a subsequent study.

 Overall, the ABM presented in this study reproduced measured larval settlement at the four monitored sites within the estuarine system. The model recreated the measured settlement pattern of increasing settlement from Sites 1-3 followed by a reduction in settlement at Site 4 (Figs. 3 - 4). Additionally, although the model generally (apart from Site 4) overpredicted settlement (at most by 21.5%) at the individual sites, there was still reasonable agreement between the measured and simulated settlement (Figs. 3 - 4). However, discrepancies did exist between the measured and simulated settlement which could be attributed to inaccuracies introduced into the simulations by the chosen MIKE ECO Lab template parameters (Tables 1-2).

 For example, the number of agents remaining at the completion of the simulations (calculated as percentage agent survival; Table 5) provides insight into the combined effects of natural and salinity-induced mortality. Natural mortality was incorporated into the simulations through the age-dependent decreasing Weibull function mimicking a Type III survivorship curve (Table 1; Pinder et al. 1978). Nonetheless, the natural mortality parameters, based on *C. gigas* oyster larvae, may be over or under-estimating natural mortality found in Gulf of Mexico *C. virginica* larvae. The variability in agent survival can also be attributed to salinity-related mortality based on salinity tolerance ranges of *C. virginica* oyster larvae from Chesapeake Bay and Long Island Sound because no tolerance studies were available for the Gulf of Mexico. The template could be improved through laboratory experiments to determine the specific CHES's larval salinity tolerances ranges in addition to more accurate information regarding natural mortality within the system. Furthermore, although the investigation of the influence of inflow, salinity, and resulting agent mortality is beyond the scope of this study; brief simulation analyses did not indicate a specific time period(s) within the simulations resulting in an abundance of instantaneous agent mortality. Rather the agents gradually suffered salinity-induced mortality and were removed from the simulation by low salinities associated with inflow.

 Despite the differences between measured and simulated settlement, the reasonable comparison results provided the opportunity to determine connectivity patterns between the four sites. The simulated results provide strong supporting evidence to Volety et al. (2015) findings of Site 1's (Fig. 1) role as an important larval source to the downstream Sites (2-4) as well as the contributions Sites 2 and 3 provide to each other. In summary, agents released from Site 1 provided at least 50.0% of total settlement at the downstream sites. Additionally, even when agents were released from three sites as opposed to two, agents released from Site 1 still provided at least 50.0% of the total settlement at the downstream sites. Site 1's furthest upstream location and importance as a larval source to the downstream sites could be cause for concern as its upstream location is likely more impacted by sustained inflow as compared to the other sites (Buzzelli et al. 2013 - Table 1).

 Investigation of each simulation revealed four key agent transport patterns (Fig. 6). (1) A cluster of agents is always transported in the southerly direction out of San Carlos Bay into the Gulf of Mexico, where the agents generally remain congregated outside of the bay and do not return into the system. (2) A portion of agents are transported from the CRE into Matlacha Pass and Pine Island Sound and remain or are further transported into northern Charlotte Harbor. (3) Agents are transported from the CRE through Matlacha Pass and Pine Island Sound into northern Charlotte Harbor, and then move through Boca Grande Pass out into the Gulf of Mexico. (4) Few 448 agents, compared to the total amount released, remain in the CRE near the settlement sites ~12-20 days post release. At the completion of the simulations 56.9-65.7% of surviving, unsettled agents were transported into the Gulf of Mexico and therefore can be considered lost to the system as

 those agents generally did not move back into the system (Fig. 6). However, the remaining 34.3- 43.1% of unsettled agents remain within the system's various regions (Fig. 6) and represent an "agent surplus". This surplus has important oyster management and restoration implications by providing evidence that (1) a large portion of unsettled agents are retained within the system and (2) a greater abundance of settlement may have occurred if additional settlement sites were available; future work should include the mapping and monitoring of additional oyster reefs (i.e. simulation settlement sites), or identification of suitable areas for the creation or enhancement of reefs. For example, greater measured settlement occurred at Site 4 (Figs. 3 - 4) possibly resulting from Site 4's location in Tarpon Bay, a semi-enclosed bay and extension of San Carlos Bay, and because no agents were released from Site 4 during any simulation (i.e. no measured spawning at Site 4). However, additional oyster reefs exist within the bay which may have been spawning during the simulation period, therefore providing larvae to the neighboring sites not captured in the simulations. Expanding on the most recent oyster reef mapping efforts [\(https://geodata.myfwc.com/datasets/oyster-beds-in-florida?geometry=-82.094%2C26.504%2C-](https://geodata.myfwc.com/datasets/oyster-beds-in-florida?geometry=-82.094%2C26.504%2C-82.012%2C26.518)[82.012%2C26.518\)](https://geodata.myfwc.com/datasets/oyster-beds-in-florida?geometry=-82.094%2C26.504%2C-82.012%2C26.518) and monitoring additional oyster reefs within the CRE will hopefully close this knowledge gap and improve simulation results.

 The ABM results provided dispersal patterns between field measured oyster reef sites thus supporting evidence to previous field based studies (Volety et al. 2015), insight into agent transport pathways, and resulting "agent surplus". Insights into transport pathways and "agent surplus" can aid in selecting locations to construct new oyster reefs as well as deciding which degraded oyster reefs show the greatest potential for successful restoration (Kim et al. 2013; Smythe et al. 2016; Arnold et al. 2017). This system-wide approach highlights the oyster reef connectivity and the relative value of specific reefs and restoration sites in relation to larval supply.

 Oyster reef restoration efforts since 2016 have occurred throughout San Carlos Bay and Tarpon Bay with projects adding 10 cm washed fossil shell at elevations from -0.25 m to -0.75 m National Geodetic Vertical Datum (NGVD). All of the sites (Fig. 7, RS1-RS9) have exhibited 477 recruitment and have exceeded the targeted live oyster densities greater than $100/m^2$ (Fig. 8)(Please see Text S1 for more detailed description of oyster density calculation). The restoration projects were planned using habitat suitability models for adult oysters and did not consider the supply and transport of larvae between existing and restored reefs. The results from this study will be applied to future restoration planning that seeks a system-wide approach considering larval dispersal dynamics to improve site selection for future restoration efforts.

 This ABM framework and study approach is an important tool for the restoration and management of oyster reefs and can be implemented in other estuaries. Hydrodynamic modeling of estuaries has greatly increased in the past decades (Brush & Harris 2010), therefore modeling outputs needed to force the ABM are likely available for most estuaries. The MIKE ECO Lab template can also be customized to an organism's estuary specific biological characteristics (e.g. salinity tolerances of Chesapeake Bay oyster larvae). Ultimately, in situ field measurements (e.g. spawning periods, settlement) may be the limiting factor(s) to attempt a similar study, however alternative methods are possible. Water temperature measurements are generally available in most estuaries and can serve as a proxy for histological analysis to initiate spawning events in the simulations (i.e. agent release)(North et al. 2008; Kim et al. 2010). For example, Volety et al. (2015) found a range of annual spawning periods in the CRE lasting between 2-9 months depending on the oyster reef location and inflow, however active spawning closely followed seasonal water temperature periods greater than 21 ºC. Additionally, larval settlement collection and analysis may be too laborious. An alternative would be to collect bivalve larval concentrations

 at specific suitable settlement locations (i.e. oyster reefs) and compare field to simulated data with the assumption that upon reaching a suitable settlement location (i.e. oyster reef), the bivalve (agent) is classified as settled (Elsäßer et al. 2013). Alternatively, this modeling framework could first determine locations to implement a field monitoring program, subsequently using the field measurements to validate the simulated larval transport and dispersal.

 The utility of using field measurements to validate ABMs and subsequently using ABM simulation results to pursue future field studies and restoration efforts (or vice versa), is an iterative process allowing managers and modelers to improve their restoration and research efforts continuously and collaboratively (Buzzelli et al. 2013). There are inherent positives and negatives associated with field and modeling studies, as some questions cannot be answered through field or modeling work alone. However, when used together, field and modeling studies can bolster one method's finding while introducing new findings and questions that may not have been previously considered or possible to identify (Ahn et al. 2020; Skogen et al. 2021).

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- **Illustrations**
- **Tables**
- Table 1. Mathematical formulations of the oyster larval agent-based model including functions,
- parameters, constants, and forcing. VTS refers to varying in time and space.
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656
657 657 Table 2. Mathematical formulations of the Eastern oyster (*C. virginica*) larval agent-based model

658 salinity tolerance ranges.

 $SALDUR(1,2,3)$ refers to Maximum time before mortality (days) saldur_thres(1,2,3) refers to Salinity tolerance range (PSU)

OYS refers to "Particle Classes" in ECOLab template

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661 Table 3. Model sensitivity testing performed with the August 2011 simulation comparing the

662 relative percentage of total and individual site settlement.

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665 Table 4. Model simulation periods, locations, and number of agents released.

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Year Simulation period Agent survival (%) Agent settlement (%) Inflow $min - max$; $mean \pm SD$ (m^{3}/s) July 1-30 13.4 1.2 5.7 - 59.5; 30.9 ± 14.1 August 1-30 15.8 3.6 12.7 - 84.6; 48.4 ± 18.3 September 1-30 14.8 2.0 12.7 - 135.1; 45.6 ± 30.2

Table 5. Percent agent survival (agents in the water column + settled) and agent settlement at the

Figure captions

 Figure 1. Map of the Charlotte Harbor estuarine system (CHES) study area showing the Caloosahatchee River Estuary (CRE) (cross hatch region), oyster reef monitoring sites and agent release locations (1-4), and water quality monitoring stations (A-J).

 Figure 2. The hydrodynamic model (HD) computational mesh (A), zoomed-in view of the Caloosahatchee River Estuary (CRE) (B), and two-dimensional depth-averaged salinity grid (C).

 Figure 3. Percentage of monthly settlement measured (gray bars) and simulated (black bars) at Sites 1 to 4. Calculated by (specific monthly settlement (simulated or measured) at a specific site/total specific monthly settlement (simulated or measured) at all sites) x100.

1 to 4. Calculated by (total settlement from each (simulation or measurement) at a specific site/total

settlement from each (simulation or measurement) at all sites) x100.

 Figure 5. Connectivity between the four oyster reefs (numbers 1 to 4 in the top left map) established from July, August, and September 2011 simulations. The different colored sectors represent the percentage of agents settled at each site respectively released at Sites 1 (blue), 2 (yellow), and 3 (gray).

 Figure 6. Distribution of agents (white circles) and percentage of agent surplus in each region (demarcated by colored areas) at the conclusion of each 2011 monthly simulation.

 Figure 7. Oyster reef sites 2016-2020: reference (RS1,4,7), restored (RS2,5,8), and control (RS3,6,9).

 Figure 8. Eastern oyster (*Crassostrea virginica*) density and error bars indicating the standard error at restored, reference, and control sites. Please note the different y axis values. (A) upper San Carlos Bay, (B) lower San Carlos Bay, (C) Tarpon Bay. Fossil shell substrate was added to Restored Reefs at time = 0. Pre-construction monitoring at all sites occurred 1 year prior to construction (year = -1). Reference reefs are near restored reefs and are thought to represent healthy reefs. Control sites were at similar elevations to reference and restored reefs but had few live oysters.

Figures

Supporting Information

 Text S1. In a separate oyster monitoring study (2015-2020), oyster densities were collected during pre- and post-restoration at restored, reference, and control sites following Baggett et al. (2016). The footprint and elevation of each site were determined using a Trimble RTK GPS. A grid of points was overlaid on the footprint to determine quadrat placement. The points were assigned a random number and then each quadrat was collected using a handheld Garmin GPS to locate the point. Five quadrats were placed and all shell and material within the quadrats were collected in a bucket and returned to the lab for enumeration and measurement. Quadrat size was determined

- 740 Table S1. Continuous environmental data series available within the Charlotte Harbor estuarine
- 741 system: data source, stations names, and parameters measured (RECON hourly, CHAP 15
- 742 minute) at the different stations. SCCF: Sanibel-Captiva Conservation Foundation; CHAP:
- 743 Charlotte Harbor Aquatic Preserve.

