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Abstract

1 Tahitian pearls, artificially cultivated from the black-lipped pearl oyster
 2 *Pinctada margaritifera*, are renowned for their unique color and large
 3 size, making the pearl industry vital for the French Polynesian econ-
 4 omy. Understanding the mechanisms of pearl formation is essential for
 5 enabling quality and sustainable production. In this paper, we explore
 6 the process of pearl formation by studying pearl rotation. Here we
 7 show, using a deep convolutional neural network, a direct link between
 8 the rotation of the pearl during its formation in the oyster and its
 9 final shape. We propose a new method for non-invasive pearl moni-
 10 toring and a model for predicting the final shape of the pearl from
 11 rotation data with 81.9% accuracy. These novel resources provide a

12 fresh perspective to study and enhance our comprehension of the over-
13 all mechanism of pearl formation, with potential long-term applications
14 for improving pearl production and quality control in the industry.

Keywords: Tahitian Pearls, Magnetic Fields, Rotation, Transfer Learning,
Deep Convolutional Neural Networks

Introduction

15 The pearl industry is a vital sector in French Polynesia, representing a major
16 economic pillar for the region. In 2021, the production of Tahitian pearls was
17 estimated at around 10 million pearls per year, contributing to nearly 50%
18 of French Polynesia's exports [1]. This dynamic industry employs over 3,000
19 people, primarily in the atolls of the Tuamotu and Gambier archipelagos and
20 generates an estimated annual revenue of 4.75 billion XPF. Pearl farming is
21 also crucial for the sustainable development of remote islands, promoting local
22 economic growth while preserving the environment and marine resources.
23 Understanding the process of Tahitian pearl formation is thus critical for
24 achieving quality and sustainable pearl production in French Polynesia. By
25 gaining insights into the biological, environmental, and cultural factors that
26 influence pearl development, researchers can identify best practices for opti-
27 mizing pearl quality while minimizing the ecological impact of pearl farming.
28 Consequently, this knowledge can inform policies and management strategies
29 aimed at promoting the long-term viability of the Tahitian pearl industry in
30 French Polynesia.

31

32 Oysters are bivalve mollusks widely distributed in marine and estuarine envi-
33 ronments. They are commonly found in shallow coastal waters and are often
34 farmed for their edible meat and their ability to produce pearls. One species
35 of oyster that is particularly well-known for its ability to produce pearls is
36 the black-lipped pearl oyster, *Pinctada margaritifera* (Linnaeus, 1758). This
37 species is common in the coral reefs of the Indo-Pacific area [2], and is the
38 main source of Tahitian pearls, also known as black pearls.

39

40 Pearls are the only gemstones produced by living creatures [3]. Natural pearls
41 are rare, so to stimulate nacre production, also known as mother-of-pearl [4],
42 a foreign body can be intentionally introduced into an oyster [5]. Cultured
43 pearls are created through a grafting process in which a small piece of mantle
44 tissue from a donor oyster (the *saibo*), along with a nacre bead known as the
45 nucleus, is inserted into the gonad of the recipient oyster. Upon insertion, the
46 outer epithelial cells of the graft multiply and form a pearl sac around the
47 nucleus. The pearl sac then begins to deposit layers of nacre onto the nucleus,
48 marking the start of the pearl's formation. It takes 12 to 18 months of cultiva-
49 tion for the pearl to develop a thick enough layer of nacre to be sold [6]. The
50 formation of the pearl is achieved by the superposition of nacre layers around
51 the nucleus at a rate of 3 to 4 per day [7, 8]. The secreted nacre is primarily
52 composed of calcium carbonate ($CaCO_3$) crystals, known as aragonite, that
53 are arranged in a brick-and-mortar structure, also called aragonite tablets.
54 Tahitian pearls can exhibit a wide range of phenotypes, including variations
55 in size, shape, color, and luster [9].

56

57 In recent years, several studies have focused on understanding the factors and
58 genes that contribute to the quality and characteristics of Tahitian pearls,

59 highlighting the environmental and genetic factors that can influence pearl
60 quality [10, 11], as well as the Mendelian inheritance of rare flesh and shell
61 colors in *Pinctada margaritifera* and how it controls the color of the pearls
62 [12]. Among these studies, it has been found that the growth fronts of nacre
63 on Tahitian pearls can be observed at the microscopic level and may take the
64 form of spirals or targets [9]. The shape of these lines, similar to fingerprints,
65 suggested that the pearl moves within the pearl sac. Cartwright et al. [9] then
66 proposed a theory of pearl rotation based on the idea that forces during the
67 deposit of aragonite tablets can cause pearl movement. It is believed that the
68 orientation of aragonite layers on the surface gives momentum to the pearl
69 during its growth, leading to movement, and that different rotational move-
70 ments may occur, depending on the presence or absence of defects. Further
71 verification of this theory and analysis of pearl rotation was still necessary to
72 determine its potential effects on the final phenotype of the pearl.

73
74 In 2015, evidence of pearl rotation in the pearl sac of *Pinctada margaritifera*
75 was obtained using a magnet inserted in the nucleus of a grafted pearl oyster,
76 and magnetic field sensors [13]. A hypothetical link between the rotation and
77 the final shape of the pearl had been suggested, and the effects of temperature
78 on rotation have also been studied with the same device [14], but the device
79 used was not precise enough to allow reliable conclusions.

80
81 Acknowledging the necessity for more accurate and reliable methods to inves-
82 tigate pearl rotation and its relationship with the final shape of the pearl, we
83 took advantage of the field of deep learning, specifically deep neural networks
84 (DNNs). These networks have become the standard approach for various
85 classification tasks, largely due to their exceptional performance in image
86 recognition challenges. This success can be attributed to the availability of
87 extensive, well-annotated datasets like the ImageNet dataset [15], as well
88 as the use of transfer learning. Transfer learning enables the utilization of
89 pre-trained neural network models to enhance performance on related tasks.
90 In our study, we apply this technique to our data, evaluating the link between
91 pearl rotation and its final shape.

92
93 This paper presents an innovative, accurate and reliable device to study pearl
94 rotation, as well as initial experiments and findings. Our study aims to better
95 understand the rotation of Tahitian pearls during their formation and its
96 relationship with the attributes of the pearl, especially its shape. We present
97 the first rotation follow-up from graft to harvest, with continuous acquisitions
98 for one year on multiple pearls ($n = 52$ oysters).

99
100 Through transfer learning and deep convolutional neural networks, using the
101 VGG-16 architecture [16], we establish a strong correlation between the rota-
102 tion patterns of the pearl during its formation and its final shape. For all our
103 pearls, we demonstrate an average rotation speed of 0.72 ± 0.14 rad.h⁻¹, and

104 we highlight that in every individual case, the absence of rotation during for-
105 mation was associated with no aragonite deposition around the nucleus. This
106 confirms the crucial role of rotation in aragonite formation, and consequently,
107 in the creation of a Tahitian pearl. We thus provide a first rotation database
108 for the pearl, as well as a model to predict the final shape of the pearl from
109 new rotation data. This non-invasive method of rotational tracking allows for
110 the monitoring of pearl grafting and development without sacrificing the pearl
111 oysters. It has potential applications in a variety of studies, including those
112 focused on understanding the factors that influence pearl quality, optimizing
113 pearl production in the pearl industry, and studying the mechanisms of pearl
114 formation. By tracking pearl rotation and other characteristics during devel-
115 opment, we may be able to gain new insights into the complex process of pearl
116 formation and identify new ways to improve pearl quality.

Material and Methods

117 In this section, we present our complete methodology for studying pearl rota-
118 tion. The first part of our approach involves the creation of magnetized nuclei,
119 which are essential for our experiments. In the second part, we introduce our
120 data acquisition device that allows us to collect high-quality data. To ensure
121 accurate results, we describe our calibration process in the third part. The
122 fourth part details the different grafts that have been made for our exper-
123 iments. In the fifth part, we describe the process of data acquisition and
124 processing, with dedicated software that we have developed. The classification
125 model used to predict the final shape of the pearl from its rotation data over
126 time is detailed in the sixth part. Overall, our methodology provides a compre-
127 hensive approach to studying pearl rotation and offers valuable insights into
128 their behavior and demonstrates a direct link between the rotation patterns
129 and the final shape of the pearl.

Preparation of the magnetized nucleus

130 To perform all our experiments, magnetized nuclei were made manually in the
131 following steps:

- 132 1. Spherical nacre beads (2.1 bu, Imai Seikaku Co. Ltd, Sumoto, Japan, made
133 from the shells of the freshwater mussel *Amblema* sp.) and cylindrical
134 neodymium magnets (5-mm diameter, 1-mm thick, N52 magnetic strength,
135 Supermagnete, Gottmadingen, Germany) were commercially purchased.
- 136 2. The beads were drilled for 5.6-mm in the parallel direction to the rings
137 observed on the surface, and the magnets were inserted at the bottom, so
138 that the magnet was inserted exactly in the middle of the nuclei.
- 139 3. The holes were covered with dental resin and the nuclei were exposed to
140 UV light for 1 hour (254 nm, 10J).
- 141 4. Sander was used to smooth the dental paste and restore a spherical shape
142 to the nuclei.

143 The result is shown Figure. 1. It is crucial to restore the final spherical shape
144 of the nucleus to avoid any impact on the graft. To obtain larger pearls, larger
145 nuclei could have been used, but with a greater risk of rejection on the graft
146 [17].

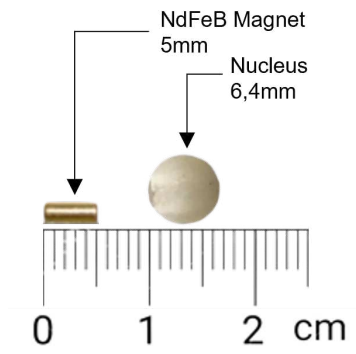


Fig. 1: Magnet and nucleus used, to scale

Magnetometer System

147 Based on the preliminary work and experimental setup of Gueguen et al, in
148 2015, which proved the rotation of the pearl [13], a dedicated room has been
149 set up at Ifremer, Vairao, Tahiti (Figure. 2.a,b,c). The room is composed
150 of eight domes, with each dome specifically designed to accommodate an
151 oyster and equipped with 25 magnetic sensors. These sensors consist of two
152 components: the HCM1021, a one-axis magnetic sensor from Honeywell, and
153 an offset compensation circuit. They are strategically distributed at varying
154 angles to the base of the half-sphere dome: 6°, 30°, 60°, and one additional sensor
155 placed at 90°. Figure. 2.e illustrates the arrangement of these sensors. All
156 sensors were affixed to the dome using a cyanoacrylate paste and are encased
157 in a Plexiglas tube for protection against water. All sensors associated with a
158 dome are connected to independent magnetometers with an acquisition card.
159 These magnetometers are then connected to a dedicated computer by an
160 Ethernet cable so that the data can be transferred and processed by software
161 called *Magneto*, which was designed in 2015 and last updated in 2022 by
162 the company Vega Industrie (Avrainville, France). This interface allows for
163 real-time visualization of the sensor values and offers different configurations
164 and parameters for recording the data (Figure. 2.d). Special care is taken
165 to avoid any external magnetic fields in the room, as this could distort the
166 acquisitions. This setup enables the performance of eight parallel acquisitions,
167 with sensor values being collected every second. This enhanced precision is
168 crucial for ensuring the reliability of our acquisitions.

169

170 To continuously monitor living oysters, a system of water circulation and pump
171 for algae supply was set up. The systems can be adjusted to control the flow of
172 food, water, and temperature. Each dome is supplied with 1 μm filtered sea-
173 water continuously. The pearl oysters are fed continuously with a mixture of
174 microalgae consisting of *Isochrysis lutea* and *Chaetoceros gracilis* at a concen-
175 tration of 30 cells μL^{-1} in each dome. The concentration of microalgae in the
176 experimental domes is checked daily to ensure that the oysters are consistently
177 fed the same amount and that the food doesn't affect the rotation.

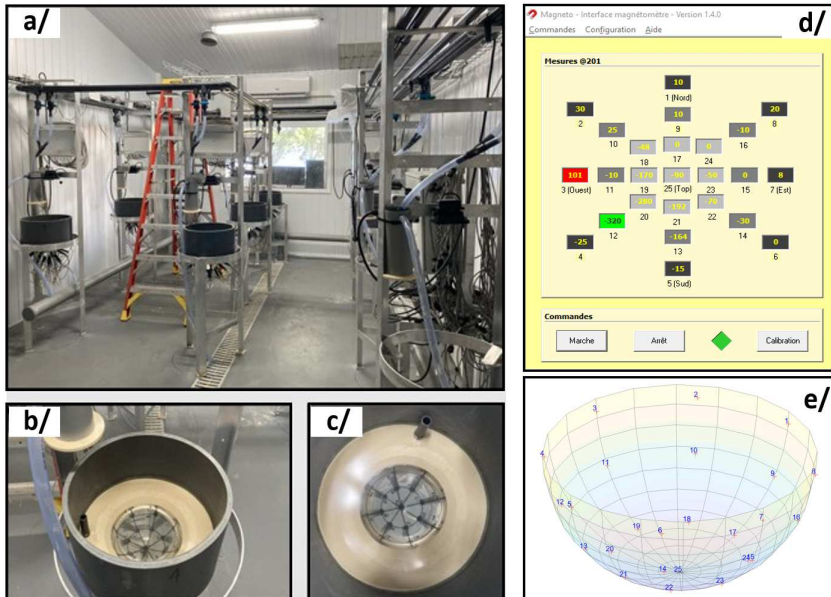


Fig. 2: Description of the magnetometer system.

a/ Full dedicated room with 8 domes. **b, c/** View from the top of a dome and its 25 associated magnetic sensors. **d/** Direct magnetic field data acquisition interface, developed by Vega Industrie. **e/** Theoretical representation of a dome via Matlab [18] with each of the associated sensors.

Data Calibration and Performance Evaluation

178 To calibrate and ensure the accuracy of our magnetic sensors, we built a cali-
179 bration device using a clock mechanism and a magnet (Figure. 3). The purpose
180 of the device was to enable us to determine suitable noise filters, optimal oys-
181 ter positions, and sensor performance. The magnet, which is placed at the end
182 of the rod, is positioned in three different locations within our dome - at the
183 center of each of the sensor lines. The magnet was oriented at three different
184 angles with respect to the axis of rotation - parallel, diagonal, or perpendicular
185 - to evaluate the accuracy of our measurements. By comparing the data from
186 our magnetic field acquisition to the clock's rotation speed, we calculated the
187 accuracy of our measurements for each sensor line, averaging over the three dif-
188 ferent orientations of the magnet. After applying a Gaussian-weighted moving
189 average filter with a window length of 60, we achieved accuracies of 97.75%,
190 98.71%, and 58.5% in the first, second, and third sensor lines, respectively.
191 Thus, an appropriate base was created to place our oysters in the middle of the
192 second row of sensors for optimal measurements. The clock device was criti-
193 cal for calibration as the rotational speed of pearls inside oysters is uncertain,
194 making it challenging to evaluate the measurement accuracy based solely on
195 pearl data.

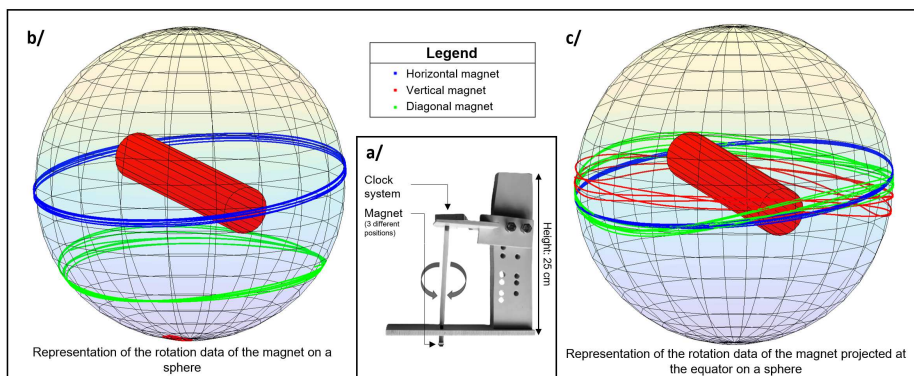


Fig. 3: Description of the calibration of our system using a clock system.

a/ Diagram of the device used: a clock mechanism is fixed at the top of a rod, allowing it to rotate at a fixed speed of one revolution per hour. At the bottom of the rod, a magnet is fixed in a variable position (parallel, perpendicular, or diagonal to the rotation axis). During the acquisition, the magnet is centered at different positions of the dome, in the middle of each of the 3 rows of sensors. **b/** Representation of the magnetic field data of the magnet projected on a sphere, assimilated to a pearl. **c/** Representation of the magnetic field data of the magnet projected on the equator, to simulate the real movement of the pearl. The final accuracies are calculated from the projected data at the equator, averaged over the 3 different positions of the magnet at the end of the rod.

Grafts

196 All donor and recipient oysters were adult individuals with an average diam-
 197 eter of 110mm. Three grafting experiments were conducted with wild pearl
 198 oysters, *Pinctada margaritifera* (Linnaeus 1758). The first experiment (n =
 199 47 oysters) was conducted at Ifremer facilities in Vairao, Tahiti. The second
 200 experiment (n = 40 oysters) used animals collected and cultured at the Pahai
 201 Poe pearl farm on Apataki Atoll, French Polynesia. The third experiment (n
 202 = 50 oysters) was conducted at the Tahiti Iti Pearl Farm in Vairao, Tahiti,
 203 using animals collected and cultured in the Takapoto atoll. After grafting, the
 204 pearl oysters were observed for nucleus retention for a month, and after the
 205 closure of the pearl sac, they were air-transferred to Ifremer facilities.

206
 207 We evaluated post-grafting survival results, related to the quality of the
 208 magnetized nuclei, shown in Table. 1. The importance of using high-quality
 209 magnetized nuclei has been established, as better outcomes were observed
 210 with well-crafted or medium-crafted nuclei compared to poor-quality ones,
 211 and these outcomes were comparable to those obtained with standard nuclei.
 212 Additionally, 25 oysters were lost from multiple causes (death, falling off the
 213 string, problems in air transport) during cultivation. Therefore, a total of
 214 52 oysters have been in our magnetometer device over a one-year timespan.
 215 The information and final photos of the corresponding pearls are presented in
 216 Supplementary Figure 1 and Supplementary Table 1.

a/ Quality of the nucleus grafted:	Number	% Alive	Remaining
Excellent	15	60	9
Medium	22	63	14
Poor	10	20	2
b/ Quality of the nucleus grafted:	Number	% Alive	Remaining
Medium	20	70	14
Poor	20	0	0
c/ Quality of the nucleus grafted:	Number	% Alive	Remaining
Medium	50	76	38

Table 1: Graft survival after one month. The quality of the nuclei was determined by their irregularity compared to a standard nucleus. All nuclei were reviewed by 3 experts. The grafts were carried out at the following pearl farms: **a/** Tahiti Iti Pearl Farm (Teahupoo, Tahiti) **b/** Harry's Pearl Farm (Apataki) **c/** IFREMER (Vairao, Tahiti) by Josh, Kamoka Pearl.

Data Processing

217 To process the collected data, software has been implemented in Matlab, avail-
218 able at <https://doi.org/10.5281/zenodo.7872014>. The software takes raw data
219 from the sensors as input and filters the noise using a Gaussian-weighted mov-
220 ing average filter. It then calculates and displays the orientation of the magnet
221 over time. The orientation of the magnet at a given time is represented by a
222 3-dimensional coordinate (XYZ) in a space centered at the center of the pearl.
223 To obtain each of the 3 coordinates, the values of each sensor are multiplied by
224 the relative position of the sensors in the given space, and then summed (see
225 Supplementary Table 2). To transform our magnet rotation data into real rota-
226 tion data of the pearl, a set of projections is needed. For a detailed description
227 of the entire process, please refer to Supplementary Note 1.

228 In addition to saving all the orientation data of the magnet and the pearl,
229 images are captured to record the movement from the 3D visualization. Start-
230 ing from the point of view that maximizes the visible rotation data, through
231 a barycenter calculation, 6 images rotated by 60° are acquired for each acqui-
232 sition (one pearl, one week). These images will then be used to classify the
233 shape of the pearl.

234
235 After classification tests, we found out that the first image taken on the 3D
236 representation, which contains the most data, was sufficient, as the addition
237 of the other images introduced noise. Thus, each sample in our dataset, which
238 represents one week's data for one pearl, consists of a single RGB color image
239 of size 224x224. Weekly acquisitions were firstly made for practical reasons -
240 the device used must be cleaned every week to maintain favorable conditions
241 for the pearl oysters' development, and the oysters must be removed from the
242 device for cleaning. As such, it was not possible to acquire continuous rotation
243 data for more than one week. More details and examples are provided in the
244 Results section.

Classification Model

245 Our classification model was designed to make predictions in two different
246 ways: either sample by sample, corresponding to the rotation of a pearl over
247 a week, or for the entire acquisition period of the pearl's rotation data. For
248 the latter prediction method, we exported the set of weekly predictions for
249 each pearl and retained the class with the highest frequency.

250

251 To determine the amount of rotation data required to predict the final shape
252 of a pearl with precision, we created several datasets in addition to the origi-
253 nal one. One dataset comprised data from the last week before the oyster's
254 sacrifice (with one sample per pearl), while another contained data from the
255 last month before the oyster's sacrifice (with up to four samples per pearl).
256 Additionally, we constructed a dataset from last week's data, with data sep-
257 arated by the day, to assess the predictive potential of rotation data over a
258 short 24-hour period.

259

260 To train the model, we partitioned the datasets into train, validation, and test
261 sets using the repeated holdout technique ($n = 100$). We carefully separated
262 the data linked to individual pearls to ensure exclusivity to one set, thereby
263 reducing overfitting risks. The class balance across splits was maintained, and
264 we allocated 70% of the data to the train set, 15% to the validation set, and
265 another 15% to the test set.

266

267 To predict the pearl shape using rotation data and account for the limited
268 dataset size, we employed transfer learning with pre-trained neural networks.
269 After evaluating multiple options, presented in the Material and Methods
270 section, we determined that the VGG-16 convolutional neural network archi-
271 tecture [16] was the best-suited model for our task, owing to its balance
272 between accuracy and execution time. Previous studies [19, 20] have consis-
273 tently demonstrated the effectiveness of the VGG-16 model across a diverse
274 range of tasks when compared to alternative architectures. The VGG-16 model
275 is pre-loaded with weights from the ImageNet [15] dataset and used to extract
276 features from the input images. To use this model, we normalized and resized
277 our datasets images to $224 \times 224 \times 3$. The complete architecture of our VGG-16
278 model, along with examples from our images, is illustrated in Figure. 4. The
279 architecture includes 18 weight layers and 5 max-pooling layers, each with
280 various functions. A detailed explanation of these functions can be found in
281 Supplementary Note 2.

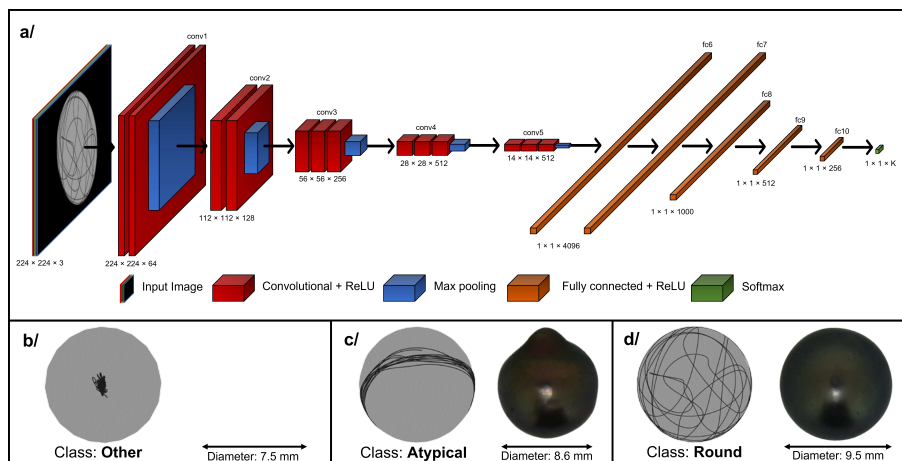


Fig. 4: Model architecture and class-associated image and pearl examples.
a/ Overview of VGG-16 architecture and its component layers **b/** Example of one image and its corresponding pearl associated with the "Other" class, which includes pearls with no mineral deposits or those with very irregular deposits. **c/** Example of one image and its corresponding pearl associated with the "Atypical" class, which includes baroque, drop, button, and circled pearls. **d/** Example of one image and its corresponding pearl associated with the "Round" class, which includes semi-round and round pearls.

282 After feature selection, the output is flattened to add two specific features
 283 to each sample with specific weights: the number of days of pearl cultivation
 284 until the oyster was sacrificed and the number of days between grafting and
 285 rotation acquisition, as rotation is not uniformly distributed during pearl formation.
 286 Additional custom layers, including Dense and dropout layers, are
 287 then incorporated to prevent overfitting. Finally, the output layer with Soft-
 288 Max activation is added to classify the pearls' shapes into three categories. The
 289 entire process, from data acquisition to final shape prediction with new data,
 290 is summarized in Figure. 5. Each step is elaborated further in Supplementary
 291 Note 3.

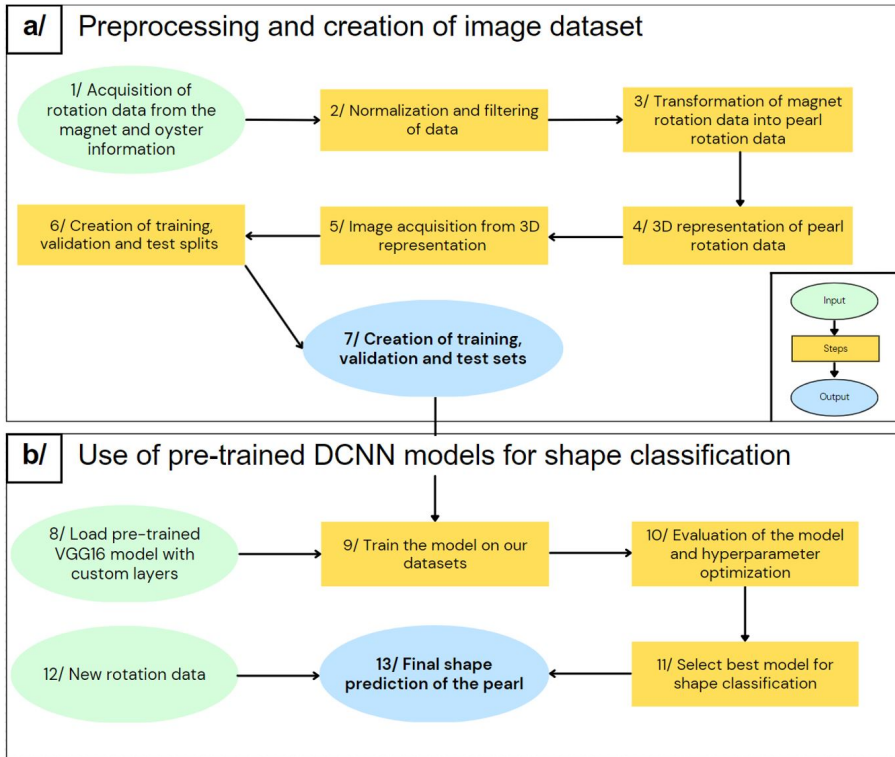


Fig. 5: Full description of the entire data handling process, from acquisition to classification.

a/ Pre-processing and creation of the image dataset, using Matlab [18]. **b/** Use of pre-trained Deep Convolutional Neural Networks (DCNN) for pearl shape classification using Python and Keras [21].

292 We evaluated our model's performance on various datasets using the repeated
 293 holdout method with 100 splits. The model accuracy and the weighted-average
 294 F1-score were determined for all splits, with associated standard deviations.
 295 A grid search was conducted to optimize the model's hyperparameters on
 296 each dataset and find the best model. Our main results are summarized and
 297 discussed in the Results section.

Results and Discussion

298 Our goal was to investigate the hypothesis that there exists a correlation
299 between the rotational behavior of a pearl and its final shape. Specifically, we
300 sought to predict the final class of a pearl based on its rotation. The pearls
301 we analyzed were classified into three distinct categories, which were manually
302 labeled by three experts in the field:

- 303 • Round: includes semi-round and round pearls (27.6%)
- 304 • Atypical: includes baroque, drop, button, and circled pearls (21.3%)
- 305 • Other: includes pearls with no mineral deposits, or very irregular deposits
306 (51.1%)

Machine Learning: First Classification Approach

307 Initially, we conducted exploratory analysis using conventional machine learn-
308 ing techniques to classify our pearls based on the acquired data. To process
309 the dataset, we calculated features for each sample that captured the pearl's
310 velocity and acceleration over time. These features were then subjected to
311 binning in order to reduce their overall number. After experimenting with
312 various binning numbers, we determined that selecting 100 features per day
313 was the optimal choice. We utilized the BioDiscML tool [22] to optimize
314 and evaluate multiple models from our dataset, allowing for effective model
315 comparison. Additionally, we explored the application of LSTM algorithms,
316 which are specifically designed for time-series data analysis, as a means of
317 classification. The outcomes of both approaches are summarized in Supple-
318 mentary Table 3, highlighting accuracy levels ranging from 20.3% to 51.6%.

319
320 All of the above calculations were exclusively performed using the complete
321 dataset. However, the classification results were significantly unsatisfactory,
322 with the highest achieved accuracy being only 51.6% using a random for-
323 est classification approach. As a result of these disappointing outcomes from
324 the previous methods that relied on direct features, our attention shifted
325 towards deep learning methods for image classification. Visual observations of
326 the movement representation served as inspiration for this approach, as they
327 suggested a potential correlation between rotation and form.

Deep Learning: VGG-16 Architecture and Image Classification

328 We subsequently directed our focus to the VGG-16 architecture and converted
 329 our data into the image format, as explained in the Material and Methods
 330 section. Our final dataset consisted of 218 images, with each image depicting
 331 a week's worth of pearl rotation. We removed outliers from the dataset, and a
 332 total of 47 distinct pearls were included in the images, with each pearl having
 333 a varying number of samples.

334

335 To gain insight into the image processing approach of the VGG-16 architecture,
 336 we present in Figure. 6 the results of feature extraction from our images. The
 337 figure displays examples of averaged feature maps for a subset of VGG-16
 338 layers for our three different classes. A comprehensive description of each block
 339 is provided in Supplementary Note 4.

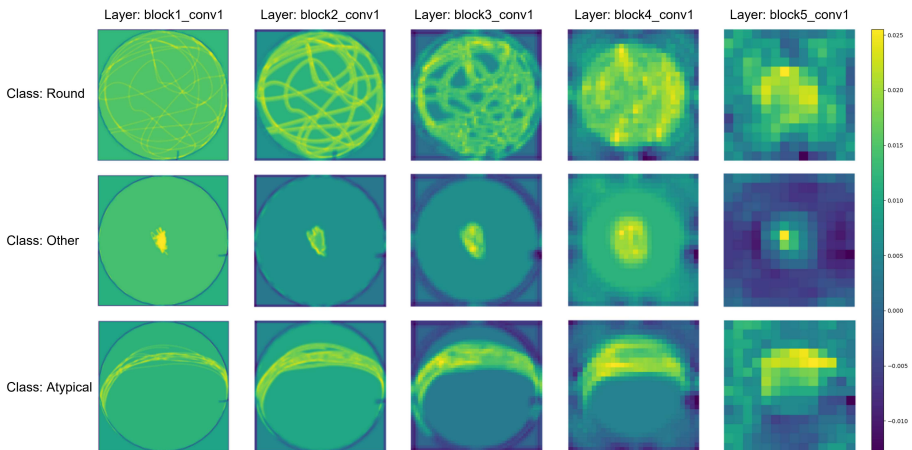


Fig. 6: Examples of averaged feature maps for a subset of VGG-16 layers for our three different classes. Feature maps represent the activation values of each filter in a convolutional layer. High activation values (brighter regions in the visualization) indicate that the filter has detected a specific feature in the corresponding region of the input image. Low activation values (darker regions) mean that the filter does not recognize its corresponding feature in that region.

340 The VGG-16 model typically makes its decision based on the final layer,
341 which has the highest level of abstraction and simplifies the problem. From
342 the three displayed images, a clear pattern emerges where a random rotation
343 indicates "Round" pearls, an axial rotation signifies "Atypical" pearls, and
344 no rotation is associated "Other" pearls. These observations confirm the pre-
345 liminary observations obtained by Gueguen et al. [13]. However, the rotation
346 patterns are more varied than these three categories suggest, and they are
347 often difficult for an observer to classify. This highlights the pertinence of
348 using a classification model.

349
350 The evaluation of the model, as well as all the calculated metrics, are pre-
351 sented in Figure. 7. For the daily, weekly, monthly, and full datasets, we
352 obtained accuracies of 47.1%, 73.4%, 70.1%, and 81.9%, respectively, over the
353 test set and for the final pearl predictions. These results validate that there
354 is a correlation between the pearl's rotation and its final shape, which can be
355 observed even by analyzing the pearl's rotation data only from the last week
356 before the oyster's sacrifice. However, analyzing the rotation daily seems to
357 be insufficient to make a prediction. The calculation of the weighted-average
358 F1-score was performed to verify that the prediction is correctly performed
359 regardless of the predicted class and the potential imbalance according to the
360 dataset. Values of 49.1%, 69.9%, 66%, and 81% were obtained, for the daily,
361 weekly, monthly, and full datasets, respectively. These high values, except for
362 the one-day dataset, confirm the high quality of our classification, regardless
363 of the predicted class.

364
365 The model achieved the best accuracy when trained on the entire dataset
366 collected over a one-year period. Our findings confirm that obtaining rotation
367 data throughout the entire pearl formation period improves pearl classifica-
368 tion, despite the irregularity of the rotation, compared to using only the last
369 rotation patterns from the final week. In addition, the results indicate that
370 using only the last month of rotation leads to lower performance compared to
371 using either the entire dataset or only the last week.

372
373 Although obtaining rotation data from the entire pearl formation period yields
374 the best prediction results, it is not practical to repeat such a lengthy data
375 acquisition for future experiments. The model trained on the weekly dataset
376 achieved an accuracy of 73.4%, allowing shape predictions with just one week
377 of rotation acquisition. We are providing the model trained on our full dataset
378 as a reference for future predictions, regardless of the duration of future acqui-
379 sitions, and to achieve the best possible prediction. Our model was trained on
380 the data of 47 distinct oysters, from 3 different grafts performed in 3 distinct
381 locations, which reduces the risk of overfitting on a specific graft and should
382 allow reliable predictions for different oysters and grafts.

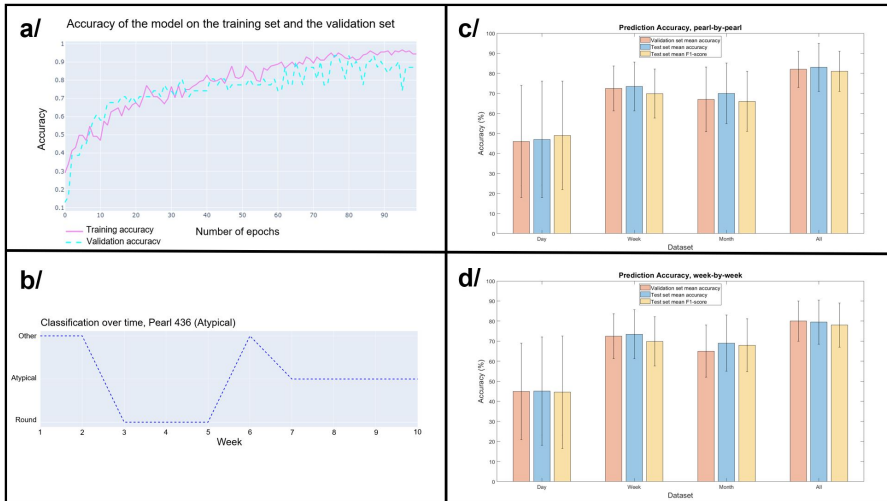


Fig. 7: Model evaluation and classification results.

a/ Example of the evolution of the accuracy on the train (in blue, dotted line) and validation set (in pink, full line) as a function of the number of epochs, used to monitor overfitting. **b/** Example of classification over time for a pearl. The irregularity of the classification can be explained by the irregularity of the rotation that we observed. **c/** Different accuracy metrics, on week-by-week classifications, depending on the dataset (day, week, month, all). **d/** Different accuracy metrics, on pearl-by-pearl classifications, depending on the dataset (day, week, month, all).

383 With an accuracy of 79.5% for weekly classification and 81.9% for bead clas-
384 sification with rotation data acquired over several weeks, our final model
385 establishes a strong correlation between pearl rotation during its formation
386 and its final shape. The provided model and software offer a reliable, turnkey
387 solution for predicting pearl shape from newly acquired rotation data, which
388 can handle input of any size.

Global Observations and Measurements of Rotation Speed

389 Through our study, we were able to determine the average rotation speed of
390 oysters during pearl formation to be $0.72 \pm 0.14 \text{ rad.h}^{-1}$ (equivalent to 8.66
391 ± 1.67 hours per revolution), based solely on the rotating pearls during their
392 formation. We also confirmed that rotation is necessary to obtain aragonite
393 deposits on pearls, with 100% of pearls with confirmed deposits having under-
394 gone rotation during their formation. However, we did not find a significant
395 difference in rotation speed between pearls of different shapes. Additionally,
396 we observed a sudden acceleration of rotation for two individuals, up to a
397 speed of 5 rad.h^{-1} , which led to rejection. This observation could provide
398 valuable insight into the mechanism of pearl rejection during formation. To
399 take it a step further, our observations contradict the hypotheses proposed by
400 Cartwright et al. [9]. While we did not observe any deposition without rota-
401 tion, we did observe rotations occurring without deposition, particularly in
402 the initial stages of the pearl's growth. This contradicts the initial hypoth-
403 esis that the deposit of aragonite causes pearl rotation. The initial rotation
404 patterns were identified 21 days after grafting, whereas the first deposits were
405 only visible from the third month onwards. Overall, our findings have impor-
406 tant implications for understanding the factors that contribute to successful
407 pearl formation.

Limitations

408 Our model currently has some limitations, including the requirement of mag-
409 netized nuclei to study rotation. The introduction of a magnet has a weak
410 influence on the graft and final pearl, confirmed by the proportion of round
411 pearls we get, similar to a standard graft [23], of approximately 30%. Nev-
412 ertheless, the manual production of these nuclei prevents large-scale studies.
413 Additionally, our rotation measurements do not account for the movement of
414 the oyster during the experiments. Distinguishing rotation along the magnet's
415 axis from immobility is also challenging. Although our database was acquired
416 over a year, it is small and limited to reliable data from 47 individuals. While a
417 larger study could yield more reliable results, predicting the shape of more than
418 three different classes of pearls would be costly and time-consuming. More-
419 over, external factors, independent of the rotation, can influence the shape of
420 a pearl. Therefore, we cannot expect significantly higher accuracy than what
421 we currently achieve. Replicating our study is challenging due to the unique

422 nature of each individual and the influence of the timing of data collection rel-
423 ative to the initial grafting date. The methodology presented in the Material
424 and Methods section provides a framework for reproducing our experimental
425 process, except for the grafting protocol. This aspect is left to the discretion
426 of individual grafters, who maintain confidentiality regarding their specific
427 techniques.

Future Perspectives

428 The aim of this model and associated acquisition device is to enable non-
429 invasive monitoring of pearl formation through rotation data. Numerous
430 possibilities arise from studying the relationships between rotation and various
431 attributes of the pearl or the oysters that produced it. Additionally, study-
432 ing the parameters that influence rotation, such as temperature and food,
433 and attempting to link it to the oyster's muscle activity and respiratory cycle
434 would allow us to identify ideal conditions for controlling the final shape of
435 the pearl after grafting. Studying different patterns and speeds of rotation
436 can help us understand the impact of parameter changes on rotation patterns
437 and speed without sacrificing the oyster. Our observations suggest that a sud-
438 den increase in rotation speed could cause rejection, highlighting the need for
439 further research into the rejection mechanism. Understanding this mechanism
440 could potentially help prevent rejection from occurring, leading to significant
441 improvements in the control and quality of pearl production. Therefore, it is
442 important to gain an extensive understanding of the impact of rotation on
443 pearl attributes to advance research in this area.

Conclusion

444 In conclusion, this study has confirmed the correlation between rotation and
445 the final shape of the pearl, as well as the capital importance of the rotation in
446 the creation and the deposit of aragonite on the nucleus. This study also intro-
447 duced a device that enables non-invasive monitoring for scientific research on
448 pearls. This device allows for accessible and small-scale studies on parameters
449 that can affect pearl formation and its final attributes. Compared to conven-
450 tional methods, which require waiting for the entire pearl production process
451 (12-18 months) to study parameter influences, the non-invasive monitoring
452 offered by our device over any short period of time offers a more accessible
453 approach.

Data Availability

The data that supports the findings of this study and used to train the given model are available from the corresponding author upon reasonable request.

Code Availability

The codes for processing rotation data and predicting pearl shape are available online: <https://doi.org/10.5281/zenodo.7872014>. All other codes used in our study, especially for training our model, are available from the corresponding author upon reasonable request.

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Author contributions

P.E.E collected the data, designed and conducted the experiments, analyzed results and drafted the manuscript. M.L and S.C analyzed and discussed the results. S.C, J.L.L and A.D supervised the experiments. All authors have reviewed the manuscript.

Competing interests

The authors declare no competing interests.

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