## Supplementary Materials



Figure 1: Pearl image acquired using an optical microscope:  $\mathbf{a}$ / With suboptimal illumination parameters, featuring light directed perpendicularly to the pearl.  $\mathbf{b}$ / With optimal illumination, where light is directed parallel to the pearl. This highlights the importance of careful light management in our context.

ThorlabsCameraGUI				- 0 X
Connect			I I I I	1
06933 V Refresh List Open camera Close camera				
Start Stop	100 -			- 0.9
Camera Settings	and the second second			
Dynamic settings Exposure (ms) Gain Black level	200 -			
5 0 48	100			- 0.8
Region of Interest Binning Data Rate	300 -			
Origin - X Bin - X Bin - Y 1200 1 1 1				- 0.7
Origin - Y 1500	400 -			
Width (Max: 2896) Frame Settings				0.6
Height (Max: 1660) Continuous Image Type				A CONTRACTOR
1100 sRGB ¥	500	IN LEADING		The second s
Reset R01	CALL STREET			0.5
Hardware Trigger Settings	600			A COLORED DE
None     Standard     PDX				0.4
Hardware Trigger Polarity	700	and the second second		
On High On Low				0.3
Color Balance	800	C N N N		A A A A A A A A A A A A A A A A A A A
Pet Gain 4				CONTRACTOR OF THE OWNER
	900 - 000			- 0.2
Green Gain 🖌 🔰 1	200 million 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			
Blue Gain 🖌 341	1000 -			_ 0.1
				A CONTRACTOR OF THE OWNER
	1100	ALC: NO		
	200	400 600	800 1000 1200 1400 1	600 1800 2000
Acquisition parameters		- 0	Autofocus parameters	c/
Horizontal step			Autofocus step	-7
0.4			0.01	
Vertical step			Autofocus travel range	
0.4			Autorocus traverrange	
Horizontal travel range			0.4	
19.6			Autorocus every Finames	
Vertical travel range			I Caracterization and iter (hashed	
19.6		Focus stacking radius (betw	een 1 and 50)	
Uprimental or vertical string (0 havinental 1	uartical		50	ter and the second s
Horizontal of vertical strips (o nonizontal, 1	vertical)		Focus Stacking smoothing (I	between 1 and 10)
Autofocus (O No. 1 Yos)			1	
Autolocus (o No, 1 Tes)			Focus Stacking method (0, 1	or 2)
1			2	
Focus Stack (U No, 1 Yes)				
1				
Pearl number				
50				
Pearl origin				
Save path				
Display temporary images (0 No, 1 Yes)				
0				

Figure 2: Full Interface for Automated Image Capture.

**a**/ Camera Settings (including exposure, cropping, black level, etc.). **b**/ Displacement Parameters (such as step size and range). **c**/ Autofocus and Focus Stacking Settings (covering focus range and steps). All these parameters were chosen empirically.



Figure 3: Pearl image acquired using an optical microscope.  $\mathbf{a}$ / Before cropping to an optimal illumination area, 4096\*2160 pixels.  $\mathbf{b}$ / After cropping to an optimal illumination area, 2100\*1100 pixels. This underscores the fact that, due to the pearl's curvature, the area that can be optimally illuminated is quite limited.



Figure 4: Various metrics were evaluated using the fmeasure function in Matlab. The abscissa represents different images captured at the same point but with varying focus levels. GRAS was chosen for autofocus implementation, as it effectively identified the sharpest images in our test dataset.



Figure 5: Photogrammetric reconstruction of blender-made moon through Metashape. The full moon was reconstructed, through multiple successive rings reconstruction.



Figure 6: Example of manually adding markers: a) Image 1, with two markers added manually. b) Image 2, showing the placement of the corresponding two markers from Image 1. This method is employed when successive images fail to reconstruct, often due to insufficient overlap between them. It is done through the 'Add Markers' feature in Agisoft Metashape Professional Edition.



Figure 7: Example of alignment without importing camera positions. This underscores the fact that, without this step in our process, we encountered difficulties in achieving correct alignment between our images, which is crucial for successfully creating a 3D model of our pearl.

Align Photos	×		Build Mesh		$\times$
▼ General			✓ General		
Accuracy:	High 👻		Source data:	Depth maps	Ŧ
✓ Generic preselection			Surface type:	Arbitrary (3D)	-
Reference preselection	Source 🔻		Quality:	Ultra high	-
Reset current alignment			Face count:	High	Y
<ul> <li>Advanced</li> </ul>			Advanced		
Key point limit:	40,000		ОК	Cancel	
Tie point limit:	4,000	L L		Uniter	
Apply masks to:	None				
Exclude stationary tie points					
			Build Texture		×
Guided image matching			✓ General		
<ul> <li>Adaptive camera model fitting</li> </ul>			Texture type:	Diffuse map	· ·
OK	Creat		Source data:	Images	Y
UK	Cancel		Mapping mode:	Keep uv	<b>Y</b>
		_	Blending mode:	Mosaic (default)	Y
Build Point Cloud		$\times$	Texture size/count:	8192 x 1	
✓ General			Advanced		
Source data:	Depth maps	<b>*</b>	OK	Consul	
Quality:	Ultra high	<b>-</b>	UK	Cancel	
Reuse depth maps					
Advanced					
ОК	Cancel				

Figure 8: Final alignment parameters. Alignment was made using generic preselection, high quality, and aligning images one-by-one, using metashape python API. Next steps were done using Agisoft Metashape Professional interface.  $\mathbf{a}$ / Dense Cloud generation parameters.  $\mathbf{b}$ / Mesh generation paremeters.  $\mathbf{c}$ / Texture application parameters.

Class	В	
Shape	Round	
Luster	Good	
Color Intensity	Medium	
Weight (g)	1.00681	
Min. Nacre Thickness (mm)	1.18	
Max. Nacre Thickness (mm)	1.31	
Min . Diameter (mm)	8.452	
Max. Diameter (mm)	8.242	

Table 1: Pearl attributes.Classification made by Direction des RessourcesMarines, Tahiti.



Figure 9: Photography of the pearl used for acquisition, taken with a Nikon D7100.

## Supplementary Note 1 : Diagram Description

From Fig. 3 : Complete overview of the data process, from pearl image acquisition to 3D reconstruction. Details of each steps :

- 1/ Preparation: Positioning the pearl under the microscope.
- 2/ Illumination Adjustment: Modifying the light intensity and brightness for optimal visibility.
- 3/ System Integration: Connecting the microscope to the computer, including the camera and motorized stage.
- 4/ Configure the image acquisition parameters.
- 5/ Automated Capture: Initiating automatic image capture process.
- 6/ Image Enhancement: Applying digital filtering to the captured images.
- 7/ Compilation: Assembling our dataset of microscopic images of the pearl.
- 8/ Simulation Creation: Generating a simulated dataset of microscopic Moon images, through Blender.
- 9/ Parameter Configuration: Setting the camera and Metashape software parameters.
- 10/ Process for Extracting Camera Positions : a) Determining the displacement between each image and converting these into angular coordinates θ and φ. b) Image Subset Creation: Generating a modified set of Moon images representing only the calculated pearl positions. c) Image Alignment in Agisoft Metashape: aligning the selected Moon images.
  d) Camera Position Extraction : Retrieving camera positions from the alignment in Metashape format.
- 11/ Pearl Image Alignment: Aligning the pearl images using the imported camera positions.
- 12/ Manual Adjustment (Optional): Adding markers manually to refine alignment if necessary.
- 13/ Mesh Generation: Creating a digital mesh of the pearl's surface, from the alignment.
- 14/ Texture Application: Adding surface texture to the generated mesh.
- 15/ 3D Model Export: Producing and exporting the final 3D model of the pearl's surface at a microscopic scale.

## Supplementary Note 2 : Measure minimum and maximum diameter from our model

To begin, based on our optical design and camera specifications, we establish the relationship between our image pixels and their actual size in millimeters:

$$\Rightarrow \begin{cases} 2092 & \text{pixels} = 1.020 & \text{mm} \\ 926 & \text{pixels} = 0.428 & \text{mm} \end{cases}$$

In order to scale our model, we obtained measurements of the ring's width at various points around its circumference, with a 20° interval. All measurements were conducted using MeshLab, and the calculated average width is as follows:

$$Width_{model} = 2.80 \pm 0.04 \text{ u.m}$$

Given that the width of our model matches the width of our image, we can establish the following ratio between the dimensions of our model and the actual size in millimeters: (where u.m represents the unit of measurement in MeshLab).

$$\begin{split} \mathrm{Width_{model}} &= 2.80 \pm 0.04 = 0.428 \ \mathrm{mm} \\ & \Longleftrightarrow \\ 1 \ \mathrm{u.m} &= 0.153 \pm 0.014 \ \mathrm{mm} \end{split}$$

Subsequently, diameters of our model were measured at multiple locations along its circumference, at intervals of 10 degrees. We recorded both the smallest and largest diameters observed:

$$\left\{ \begin{array}{rll} Diameter_{min} & = & 54.04 & u.m \\ Diameter_{max} & = & 54.95 & u.m \\ \end{array} \right.$$
$$\longleftrightarrow \left\{ \begin{array}{rll} Diameter_{min} & = & 8.268 & mm \\ Diameter_{max} & = & 8.407 & mm \end{array} \right.$$

While this details the calculations for Ring 1, the exact same method was applied to Ring 2.



Figure 10: Example of rings intersection in our final model. **a**/ Image 1: Acquisition of Ring 1. **b**/ Image 2: Acquisition of Ring 2. **c**) A zoomed-in view of the model, highlighting the reconstructed area corresponding to the overlap between Images 1 and 2. This figure effectively demonstrates that our model accurately reconstructs the area where the two rings overlap.