
Assessing the impact of discretisation assumptions in a length-structured population growth model

H. Drouineau^{a,*}, S. Mahévas^a, M. Bertignac^b and A. Fertin^c

^a IFREMER Department EMH, Rue de l'Île d'Yeu, B.P. 21105, 44311 Nantes Cedex 3, France

^b IFREMER Centre de Brest, Laboratoire de Biologie Halieutique, STH/LBH, BP 70, F-29280 Plouzané, France

^c Université de Tours, IRBI UMR CNRS 6035, Parc Grandmont, 37200 Tours, France

*: Corresponding author : Drouineau H., email address : hdrouine@ifremer.fr

Abstract:

Most of the traditional assessment models are age-structured. However, many biological and exploitation processes are more length-dependent than age-dependent, and the required length–age conversion of available data is often not reliable. Consequently, length-structured or age–length structured models have undergone considerable development in recent years. The growth transition matrix used to model the mean growth and growth variability of the population, is of primary importance in a length-structured matrix model. Building this growth transition matrix is not trivial and it is necessary to assess the impact that various assumptions may have to identify robust model structures. In this study, we assess the effects of (1) time and length discretisation, (2) the distribution of individuals within length classes and (3) the statistical distribution used to describe growth variability, by fitting a growth matrix model to individual quasi-continuous simulated growth data. The study quantitatively demonstrates that the choice of the time step and of length class width is the key point when building a length-structured population growth model. The use of a gamma distribution for the growth increments and/or a uniform distribution of individuals within length classes were found to make the model more robust.

Keywords: Length-structured model; Growth; Discrete model; Sensitivity analysis

17

18 **Introduction**

19 From deterministic - single cohort analysis (Pope, 1972) to multi cohort analysis, age-structured
20 models (Fournier and Archibald, 1982 ; Virtala *et al.*, 1998 ; Shepherd, 1999) are widely used for
21 fisheries stock assessments. While these models have proved to be useful in estimating population
22 abundance and assessing stocks, several limitations have been pointed out. One limit, often
23 mentioned, is related to the need to convert catch at size into catch at age, which is often carried out
24 using an age-length key. For some species, the difficulties in determining the age at length result in
25 uncertainty in catch-at-age. Moreover, since the ageing techniques are very expensive, few fishes
26 can be aged, further increasing the sampling error and variability in the age-length key. Another
27 source of uncertainty is the size-dependent selectivity function which can not be explicitly taken
28 into account in age-structured model though a age selectivity function may be used as a proxy.
29 Large interindividual and/or interannual variations in size within an age class could thus result in
30 incorrect estimates of fishing mortality by age. Consequently, length-structured models or age-
31 length structured models have undergone considerable development in recent years (Schnute, 1987 ;
32 Schnute *et al.*, 1989a ; Schnute *et al.*, 1989b ; Sullivan *et al.*, 1990 ; Banks *et al.*, 1991 ; De Leo and
33 Gatto, 1995 ; Fournier *et al.*, 1998 ; DeLong *et al.*, 2001 ; Froysa *et al.*, 2002), but are still not often
34 used in routine stock assessments.

35

36 Different mathematical frameworks can be used to model length-structured population dynamics,
37 depending on whether population states are assumed discrete or continuous and whether the
38 projection time is discrete or continuous. Continuous approaches better match biological processes.
39 However, the disadvantage of this approach is the complexity of handling differential equations
40 which do not necessarily have analytical solutions. In addition, available observed data are
41 generally aggregated thereby reducing the advantages of a continuous model. By contrast, discrete

42 approximations of biological processes simplify model implementation and are easier to compute.
43 Discrete approaches require discrete assumptions on continuous processes. Following, discrete
44 growth modelling necessitates decisions on length classes width, time step duration, growth
45 increment model (stochastic or deterministic) and on the distribution of individuals within each
46 length class.

47 Fish growth is a major process of fish biology (Laslett *et al.*, 2002) and is part of the information
48 necessary to estimate stock size and fishing mortality in stock assessments models (Anda-Montañez
49 *et al.*, 1999). The importance of describing jointly mean growth and individual variability in growth
50 for stock assessment process has been widely acknowledged (Laslett *et al.*, 2002 ; Chen *et al.*,
51 2003). Two approaches are classically considered to model growth variability. The most common
52 model is a mean growth by length class given by a growth function, often a von Bertalanffy growth
53 curve, and a stochastic distribution for individual variability around the mean (Sullivan *et al.*, 1990 ;
54 De Leo and Gatto, 1995 ; Cruywagen, 1997 ; Froysa *et al.*, 2002). Another way to describe growth
55 variability is to integrate individual variability in the growth function with stochastic parameters
56 (Sainsbury, 1980 ; Smith *et al.*, 1998 ; Smith and Botsford, 1998 ; Pilling *et al.*, 2002). Several
57 approaches can be used to estimate growth parameters and corresponding variability. Length-at-age
58 can be back-calculated using information contained in fish hard parts, but this approach is often
59 imprecise due to difficulties in detecting growth increments. A second approach is tagging
60 (Shackell *et al.*, 1997 ; Kendall and Nichols, 2002 ; Laslett *et al.*, 2002 ; Eveson *et al.*, 2004 ; de
61 Pontual *et al.*, 2006). This technique is very expensive as many fishes have to be tagged in order to
62 be successful.

63

64 To date, very few studies have looked at the impact of time and length discretisation on the
65 ability of a population model to fit data and to estimate growth parameters. We chose in a first step
66 to work on a theoretical population only submitted to growth (no death and no recruitment) since it

67 is a key process of length-structured model (Chen, 2003). In this study we provide a methodology
68 to assess the impact of several assumptions of time and length discretisation and growth increments
69 distribution in a length-structured population growth model. Data on individual growth trajectories
70 are rarely available. Thus, we produced several synthetic data sets of individual growth trajectories
71 corresponding to several hypotheses on growth increments. Then we fitted length-structured growth
72 population models to each synthetic data set. We provided from this analysis a flexible length-
73 structured population growth model.

74

75 **Data and methods**

1 A length - structured population growth model

76 A matrix formulation of a discrete time length-structured population growth model is presented
77 below. Since we only focus on the growth process, natural and fishing mortality are not described in
78 the model. The length-structured abundance in number at time $t+1$ is given by the following
79 equation:

$$80 \quad N(t+1) = G \cdot N(t)$$

81 where $N(t)$: vector of abundance per size-class at time t and G is the matrix of probabilities of
82 transition between length classes

83 We assumed a constant growth transition matrix over time (i.e., no seasonality has been taken
84 into account). The population is supposed to grow on average according to a von Bertalanffy

85 growth function, parameterised by three parameters L_∞ , K and T_0 , $l(t) = L_\infty \times (1 - e^{-K(t-T_0)})$. We

86 used an alternative formulation of this equation $l(t+\Delta t) - l(t) = (L_\infty - l(t)) \times (1 - e^{-K \times \Delta t})$

87 (Fabens, 1965) where $l(t+\Delta t) - l(t)$ is here the growth increments during a time step Δt of an

88 individual of size $l(t)$ at the beginning of the time step. Growth increments within the population are

89 random variables (Sullivan *et al.*, 1990 ; Cruywagen, 1997 ; Froysa *et al.*, 2002) whose mean is
 90 given by the von Bertalanffy equation and whose variance is proportional to the square of its mean
 91 (DeLong *et al.*, 2001) (i.e., assuming a constant coefficient of variation of the growth increments):

$$92 \quad \begin{cases} E(X/l) = (L_{\infty} - l) \cdot (1 - e^{-K \cdot \Delta t}) \\ V(X/l) = C \cdot E^2(X/l) \end{cases}$$

93 with X/l the random variable describing the growth increment for fish of initial size l during a
 94 time step Δt and C a constant linking the mean to the variance equals to $CV^2(X/l)$.

95

96 Given the previous assumptions on the growth increments' mean and variance, the coefficients of
 97 the growth matrix were calculated according to the following equations:

- 98 ● if fish size is assumed to be at the midpoint size of the departure class i , denoted m_i , then
 99 the probability g_{ij} of transition to class j is given by the following single integral:

$$100 \quad g_{ij} = \int_{(m_j - \Delta l/2) - m_i}^{(m_j + \Delta l/2) - m_i} f(x) dx \quad \text{with } \Delta l \text{ the width of the length classes}$$

- 101 ● if fish size is assumed to be uniformly distributed within the departure class i , then the
 102 value of the following double integral is the probability g_{ij} of transition from class i to class
 103 j :

$$104 \quad g_{ij} = \int_{m_i - \Delta l/2}^{m_i + \Delta l/2} \left(\int_{(m_j - \Delta l/2) - y}^{(m_j + \Delta l/2) - y} f(x) dx \right) dy \quad \text{with } \Delta l \text{ the width of the length classes}$$

105 with f the assumed density function of growth increment.

106 We considered three different continuous distributions (normal, lognormal, gamma) to describe
 107 growth increments distribution (Table 1). The Gamma distribution (Table 2) is a two-parameters
 108 distribution, entirely defined by its two first moments. It is largely used in modelling thanks to its
 109 flexibility in describing many functional forms. More specifically in our context, it can describe

110 growth for small and large fish. The normal and lognormal (Table 2) statistical distributions were
111 also considered.

112 We considered classes of equal width in length and assumed two types of length classes (Table
113 1), which is the most common method to build classes (Sullivan *et al.*, 1990 ; De Leo and Gatto,
114 1995 ; Froysa *et al.*, 2002).

115 Finally, three different time steps were considered in this analysis: monthly, quarterly and annual
116 (Table 1).

117

118 Let us denote $Mod(Lm, \Delta t, \Delta l, ODep)$ the formulation of the length-structured population growth
119 model assuming a statistical distribution of growth increments Lm , a time step Δt , length classes of
120 size Δl , and an option of distribution of individuals within classes $ODep$ (Table 1). A simulation
121 corresponds to a ten-year cohort projection (we denoted T the number of time steps corresponding
122 to a ten-year projection) with an initial length distribution following a normal distribution of mean 5
123 cm and standard deviation of 1.

124

2 Synthetic Data

125 Individual growth data are necessary to assess the impact of both time and length discretisation
126 assumptions in the growth dynamics model. However, no such data were available: consequently
127 we simulated individual growth trajectories. We used a monthly time step to mimic time continuous
128 growth. Shorter time steps were also tested, but the differences in frequencies-at-length were minor.

129 Let us denote $S(\mathbf{K}, \mathbf{CV}, \mathbf{Ls})$ a simulation set of individual growth trajectories performed with, a
130 growth rate \mathbf{K} , a constant of variance of growth increments \mathbf{CV} and a statistical distribution of
131 growth increments \mathbf{Ls} . A set of 10000 individual trajectories over a ten-year period was simulated
132 for each combination of assumptions of growth variability $(\mathbf{K}, \mathbf{CV}, \mathbf{Ls})$ using a monthly time step

133 (Table 1). Two distinct von Bertalanffy growth rates K were considered (Table 1), respectively
134 corresponding to a slow growing species and a faster growing species. Three distinct constant of
135 variation were used (Table 1). These simulations aim at mimicking individual growth observations.
136 For each set, the initial length of each individual was generated according to a normal distribution
137 with mean 5cm and standard deviation of 1.

138

139 3 Analysis

140 3.1 Experimental design

141 We aimed at assessing the impact of discretisation assumptions on length-structured population
142 growth model ability to fit sets of individual growth trajectories and estimate growth parameters.
143 We used an experimental design (Kleijnen, 1998) that we analysed using standard linear models.
144 Each formulation of the length-structured population growth model $Mod(Lm, \Delta t, \Delta l, Odep)$ was
145 fitted to each simulated data set of individual growth trajectories $S(K, CV, Ls)$ by estimating K_{est}
146 and CV which minimize the sum of squared error:

$$147 \quad LS(K_{est}, CV) = \sum_{i=1}^I \sum_{t=1}^T (f_{est}(t, i) - f_{obs}(t, i))^2$$

148 with $f_{obs}(t, i)$ the simulated frequencies of individuals within class i at time step t , $f_{est}(t, i)$ the
149 frequencies of individuals within class i at time step t estimated by the matrix model, I the number
150 of classes and T the number of time steps. This design required 648 simulations (18 sets of
151 individuals growth trajectories times 36 formulations of the length-structured population growth
152 model).

153

154 The minimisation of the function $LS(K_{est}, CV)$ was carried out using a genetic algorithm coupled
155 with a quasi-Newton algorithm provided in the Autodif library (Otter Research Ltd. [7/25](http://otter-</p></div><div data-bbox=)

156 rsch.com). The genetic algorithm was used in a first step to provide a starting point not too far from
157 the optimum for the Autodif algorithm.

158 For each experiment, the adequacy of the length-structured population growth model is
159 quantified using two criteria:

160 ●The discrepancy between the K estimated (K_{est}) by the matrix model and the \mathbf{K} used to
161 generate the observations data (\mathbf{K}). It quantifies the goodness of the estimation of K

162 ●The Bayesian Information Criterion (BIC) is computed using the formula

163 $BIC = -2 \cdot \text{Log}L + p \cdot \log(n)$ with $p=2$ the number of estimated parameters (K and CV)

164 $\text{Log}L = n \times \log(\sqrt{2 \times \pi}) + \frac{1}{2} \times \left[n \times \left(\log \frac{n-1}{LS} - 1 \right) + 1 \right]$ and n the number of observations (number of

165 time steps X number of classes). The BIC is here a measure of model ability to fit the data. The BIC
166 balances the discrepancy between data and predictions (measured by LS) by the number of
167 estimated parameters and the number of observations (which depends on the time step and length
168 classes width in the model).

169

170 3.2 Assessing discretisation assumptions

171 We first used box-and-whisker plots of the estimated growth rate K_{est} for each modality of the
172 four assumptions in order to visually detect biases. Then, a statistical analysis of the criteria was
173 carried out to quantify the effect of each hypothesis. First, each criterion was analysed separately
174 using linear models step fitted on the transformed criterion, respectively $\log(|BIC|) = LBic$ (the
175 absolute value is necessary for the logarithmic transformation because the BIC were negative) and
176 $\log(|K - K_{est}|) = LK$, where $LBic$ and LK will refer to the two transformed variables. An appropriate
177 model is characterised by a high $LBic$ and a low $|K - K_{est}|$. A full experimental design allows

178 inclusion of all the main effect and first-order interaction in the model (Kleijnen, 1998), so that the
 179 models may be written under the general form:

$$180 \quad L_{Bic} \sim \mu + Lm + \Delta t + \Delta l + Odep + \mathbf{K} + \mathbf{CV} + \mathbf{Ls} + Lm : \Delta t + Lm : \Delta l + Lm : Odep + Lm : \mathbf{K} + \\
 Lm : \mathbf{CV} + Lm : \mathbf{Ls} + \Delta t : \Delta l + \Delta t : Odep + \Delta t : \mathbf{K} + \Delta t : \mathbf{CV} + \Delta t : \mathbf{Ls} + \Delta l : Odep + \Delta l : \mathbf{K} \quad (1) \\
 + \Delta l : \mathbf{CV} + \Delta l : \mathbf{Ls} + Odep : \mathbf{K} + Odep : \mathbf{CV} + Odep : \mathbf{Ls} + \mathbf{K} : \mathbf{CV} + \mathbf{K} : \mathbf{Ls} + \mathbf{CV} : \mathbf{Ls}$$

$$181 \quad L_K \sim \mu + Lm + \Delta t + \Delta l + Odep + \mathbf{K} + \mathbf{CV} + \mathbf{Ls} + Lm : \Delta t + Lm : \Delta l + Lm : Odep + Lm : \mathbf{K} + \\
 Lm : \mathbf{CV} + Lm : \mathbf{Ls} + \Delta t : \Delta l + \Delta t : Odep + \Delta t : \mathbf{K} + \Delta t : \mathbf{CV} + \Delta t : \mathbf{Ls} + \Delta l : Odep + \Delta l : \mathbf{K} \quad (2) \\
 + \Delta l : \mathbf{CV} + \Delta l : \mathbf{Ls} + Odep : \mathbf{K} + Odep : \mathbf{CV} + Odep : \mathbf{Ls} + \mathbf{K} : \mathbf{CV} + \mathbf{K} : \mathbf{Ls} + \mathbf{CV} : \mathbf{Ls}$$

182 with α_i the effect of the assumption i $\beta_{i,j}$ the effect of the interaction between assumption i and
 183 assumption j .

184 The coefficients of an effect are constrained to sum to 0.

185 These linear models enable us to quantify the impact of the assumptions of both quality of K
 186 estimation and model fit. In addition, we were also interested in selecting the most appropriate
 187 model with respect to both objectives. A multiple regression tree (De'Ath, 2002) was built to
 188 explain the variations of the two transformed variables (previously normalized and centered) by the
 189 different explanatory variables (i.e., different assumptions). The model is (bold terms correspond to
 190 assumptions for the quasi-continuous model., other terms correspond to assumptions on the matrix
 191 model):

192

$$193 \quad \frac{(L_{Bic} - \text{mean}(L_{Bic}))}{sd(L_{Bic})}, \frac{(L_K - \text{mean}(L_K))}{sd(L_K)} \sim \Delta t + \Delta l + \mathbf{Lm} + \mathbf{CV} + \mathbf{K} + \mathbf{Odep} + \mathbf{Ls} \quad (3)$$

194 The tree is grown by repeated binary partitioning of the data, maximizing the Euclidean distance
 195 between the two group centroids and minimizes the total Euclidean distance to the centroid within
 196 each group. Each partition is characterized by an explanatory variable and the rank of the
 197 explanatory variable selections in the tree reflects the magnitude of impact of the variable on both
 198 responses.

200 **Results**

201 *1 Experimental designs analysis*

202 Table 3 and Table 4 summarize the remaining effects of model (1) and (2) after performing
203 classical Fisher tests and residuals analysis. The R^2 of the linear models are 0.995 for the *LBIC*, and
204 0.674 for the *LK*. In those tables, the estimates quantify the strength of the effect of the considered
205 assumption. The reader should notice that for:

- 206 ● model (1) the assumptions which have a positive estimate improve the fit to observed
207 frequencies-at-length
- 208 ● model (2) the assumptions which have a negative estimate improve the estimation of the
209 growth rate.

210

211 1.1 Fitting observed frequencies-at-length (Table 3)

212 The significant effects of interaction factors are minor compared to the main effects and do not
213 influence the results. Among the main effects, most factors are significant, but few have a large
214 estimated value. Length class width and time step duration are the two factors which have the
215 strongest influence. The best fits were obtained with a monthly time step and 1 cm length classes
216 width. Results also demonstrated that a large inter-individual variability and a large growth rate are
217 more easily fitted by the matrix models.

218

219 1.2 Ability to estimate the growth rate K (Table 4)

220 The box-and-whisker plots (Fig. 1) did not show any bias in the estimation of the growth rate,

221 except when assuming a normal distribution for the growth increments. However, they showed that
222 the precision of the estimation varies across the different assumptions. The variability is particularly
223 high for a monthly time step, a normal distribution of growth increments and 5cm classes.

224 The linear models showed that fewer factors have a statistically significant effect on the
225 estimation of the growth rate, however many more factors have a strong impact the estimation. As
226 previously, classes of 1cm greatly improved K estimation. More surprisingly, short time steps do
227 not systematically improve the estimation of the growth rate. In fact, with a monthly (or quarterly)
228 step, individuals have a too small probability to change class (especially when classes are 5 cm
229 wide) so that K tends to be over-estimated to compensate. This highlights the links existing between
230 size classes and time steps (the interaction of the two factors is strongly significant). The choice of a
231 time step should be strongly linked to the choice of the size of classes, both choices being also
232 constrained by the available data.

233 The linear model demonstrates that, in contrast with the *BIC* analysis, a low growth rate and a
234 weak inter-individual variability favour a good estimation of K. Furthermore, if the individuals are
235 uniformly distributed within classes, the estimation is improved, especially with a short time step.

236 Finally, it highlights the fact that gamma and lognormal distributions used in the length-
237 structured population growth model yield very similar results. The gamma distribution tends
238 however to produce better fits than the lognormal even if a lognormal distribution is assumed for *S*.
239 A normal assumption in the length-structured population growth model gives poor estimation of **K**
240 when a gamma or lognormal distribution is assumed for *S*. The gamma distribution for *Mod* give
241 better results than a normal distribution even when a normal distribution is assumed for *S* (this can
242 be checked by summing the estimates of the main effects and of the interaction). Among the three
243 distributions tested, the gamma distribution appears to be the most flexible distribution to represent
244 the variability of the growth increments.

245

246 2 *Multivariate regression tree (Table 5 and Fig. 2)*

247 The first criterion to partition groups of fits is the width of the classes. Small length classes tend
248 to improve the estimation of K and especially the goodness of the fit of frequencies at length. Then
249 the fits are partitioned according to time steps : large time steps degrade the estimation of
250 frequencies at length, and this is amplified with wide length classes. We can notice that monthly
251 and quarterly time steps are opposed to yearly time step The next two partitions concern the
252 assumption on statistical distribution of growth increments: assuming a gamma or lognormal
253 improves the goodness of the fit.

254

255 **Discussion**

256 This study aimed at analysing the impact of various assumptions on a length-structured
257 population growth model, especially time and length discretisation, in order to detect some artefacts
258 caused by inappropriate assumptions in growth model and to provide the most flexible model. This
259 kind of sensitivity analysis is essential in a discrete model and the methods we provide can be
260 applied in many situations. This study is a preliminary analysis to the development of a complete
261 length-structured model for European hake. In this paper, we chose to only focus on growth because
262 it is a critical point in length-structured model of population dynamics. A von Bertalanffy growth
263 curve was used to model mean growth, but more general growth functions can be considered as
264 polynomial, Gompertz, Verhulst, Richards, Schnute. Inter-individual variability was modelled using
265 a statistical distribution around this mean. Theoretically, a growth increment variance could be
266 estimated for each length class but we made this assumption to reduce the number of parameters to
267 estimate. It should be noticed that this relationship between the mean and variance constrains the
268 statistical distributions. A similar analysis has been carried out assuming a growth increment
269 variance proportional to the mean (Sullivan *et al.*, 1990 ; Sullivan, 1992) (not presented here)
270 leading to very similar results. The Beta-Binomial distribution (Ennis and Bi, 1998) was primarily

271 used to model the distribution of growth increments, but rejected because of unsatisfactory results.

272 Individual growth data are necessary to assess the impact of both time and length discretisation
273 assumptions in the length-structured population growth model. Tagging data would have been an
274 interesting data source, but despite a recent tagging survey, the amount of tagging data for European
275 hake, the species we are currently working on, was insufficient. Consequently we decided to
276 simulate individual growth data, trying to mimic an average von Bertalanffy growth and
277 introducing inter-individual variability. It may have been interesting to simulate individual growth
278 trajectories considering a population with stochastic K and L_{∞} . The results may largely be
279 influenced by the methods used to generate these individual growth trajectories and therefore
280 should not be generalized in the broader context. More generally, the results we obtain are not
281 generic since they depend (1) on the method used to simulate data (2) on the considered model,
282 species and/or fisheries. However, the methodology we provide is generic and is appropriate to
283 assess the impact of any discretisation processes in a discret model.

284 In this analysis, we considered L_{∞} was known because it may be approximated by a function of
285 L_{max} and it avoids the problem of the correlation between K and L_{∞} . This assumption has already
286 been used for example in DeLong *et al.* (2001). The sets of von Bertalanffy parameters used in the
287 study are closed to those currently used for stock assessment of European hake ($K=0.1$) (Piñeiro
288 and Sainza, 2003) and to the recently assumed growth ($K=0.2$) (de Pontual *et al.*, 2003 ; Kacher and
289 Amara, 2005 ; de Pontual *et al.*, 2006). The growth rate K and the coefficient of variation CV were
290 estimated by minimising the sum of squared deviations between frequencies estimated by the
291 length-structured population growth model and simulated frequencies-at-length.

292 We chose two criteria to describe the goodness of fit of the length-structured population growth
293 model to frequencies generated by the quasi-continuous model. Those two criteria correspond to
294 two modelling aims. The first objective was to reproduce and/or predict the observed data. In that
295 case, we are less interested in the biological processes under-lying the model than in its ability to

296 reproduce observations. The other objective was to reproduce the biological process driving the
297 model (for example growth). In that case, the quality of the estimates (precision, bias) is much more
298 important. Selecting a model that achieves these two objectives should be of major importance.
299 However, it requires a method combining these two criteria. Indeed, in this study we showed that
300 the best fits (the ones with the lowest *BIC*) are not necessarily the ones which provide the best
301 estimates of unknown parameters. Until now, we have not found any satisfactory quantitative
302 methods to simultaneously assess the effect of the different assumptions on both criteria. A possible
303 solution would be to build a desirability function (Harrington, 1965) combining criteria, but the
304 choice of the function is rather subjective since the user must first define individual desirability
305 functions for each response. Multivariate regression trees provide a convenient graphical tool to
306 investigate the impact of assumptions in the length-structured population growth model on both
307 criteria simultaneously but this is only an explanatory analysis based on hierarchical clustering.

308 The statistical analysis of the two criteria enables identification of robust model structures for the
309 length-structured population growth model. It demonstrated that the choice of the time step and of
310 length class width was the key point when building a length-structured population growth model.
311 These choices are closely linked to available data and are strongly interdependent. A compromise
312 needs to be found to comply with the two modelling objectives of the model. Other assumptions
313 had a significant effect on the estimation of the growth rate. The gamma distribution was the most
314 flexible statistical distribution to describe growth increments variability. Assuming that individuals
315 are uniformly distributed within length classes, rather than centred, also improved significantly the
316 estimation of the growth rate. We only tried two kinds of distribution of individuals within length
317 classes though some other distributions are sometimes used, for example U-shaped distribution
318 which is especially appropriate for wide length classes. It would also be interesting to assess the
319 impact of the number of individual growth trajectories to quantify the number of trajectories
320 required for a reliable growth rate estimation.

321 This study was a preliminary analysis in the development of a length-based population model for
322 the European hake (*Merluccius merluccius*) stock dynamics. The results inform on the selection of
323 appropriate assumptions of time and length discretisation for this model. The European hake
324 dynamic model will have a quarterly time step and 1 cm width classes since these appear to be a
325 relevant compromise and they correspond to the time-scale of available data. A gamma distribution
326 will be used to describe the variability of growth increments and individuals will be uniformly
327 distributed within length classes.

328

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329

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418

419 Table 1: List of the abbreviations and their specifications. Bold terms correspond to assumptions
 420 on the quasi-continuous model. Other terms correspond to assumptions on the length-structured
 421 population growth model.

Abbreviation	Signification	Possible Values
Δt	Time steps of the length-structured population growth model	12: monthly time step 4: quaterly 1: yearly
Δl	Size of the length classes in the length-structured population growth model	1: 1cm 5: 5cm
Lm	Statistical distribution of the growth increments in the length-structured population growth model	0: gamma 1: normal 2: lognormal
$ODep$	Distribution of the individual within length classes in the length-structured population growth model	0: center 1: uniform
$C - CV$	Constant of variance in the quasi-continuous model corresponding coefficient of variance	- 0.4 – 0.6 1 - 1 4 - 2
K	Growth rate in the quasi-continuous model	0.1, 0.2
Ls	Statistical distribution of the growth increments in the quasi-continuous model	0: gamma 1: normal 2: lognormal
α	Parameter of the Beta-Binomial	0.1, 1, 10, 50
β	Parameter of the Beta-Binomial	1, 10, 50, 100
$Kest$	Estimated growth rate when fitting the length-structured population growth model on frequencies at length generated by the quasi-continuous model	
BIC	Bayesian Information Criterion when fitting the length-structured population growth model on frequencies at length generated by the quasi-continuous model	
$Lbic$	Neperian logarithm of the absolute value of BIC	
LK	Neperian logarithm of the absolute value of the difference bewteen $Kest$ and K	

423 Table 2: Distribution, mean and variance of the normal (N), lognormal (LN) and Gamma (G)
 424 statistical distributions. With $\Gamma(x) = \int_0^{\infty} e^{-u} u^{x-1} du$ the gamma function.

Distrib	Density	E	V
N	$f(x) = \frac{1}{\sigma \times \sqrt{2 \times \pi}} \times e^{-\frac{1}{2} \times \left(\frac{x-\mu}{\sigma}\right)^2}$	$E(X) = \mu$	$V(X) = \sigma^2$
LN	$f(x) = \frac{1}{\sigma \times x \times \sqrt{2 \times \pi}} \times e^{-\frac{1}{2} \times \left(\frac{\log(x)-\mu}{\sigma}\right)^2}$	$E(X) = e^{\mu + \frac{\sigma^2}{2}}$	$V(X) = (e^{\sigma^2} - 1) \times e^{2\mu + \sigma^2}$
G	$f(x) = \frac{1}{\beta^\alpha} x^{\alpha-1} e^{-\frac{x}{\beta}}$	$E(X) = \frac{\alpha}{\beta}$	$V(X) = \frac{\alpha}{\beta^2}$

425

426

427 Table 3: Significant effects in the linear model explaining *LBic* of the fits by the different
 428 assumptions .

429 *** (respectively **) stands for a p-value<0.01 (respectively <0.05)

	Estimate	P-value
Intercept	8.92	***
<i>Lm=0</i>	0.03	***
<i>Lm=1</i>	-0.05	***
<i>Δt=1</i>	-1.18	***
<i>Δt=4</i>	0.06	**
<i>Δl=1</i>	1.37	***
<i>CV=0.2</i>	-0.21	***
<i>K</i>	0.89	***
<i>Ls=0</i>	0.05	**
<i>Ls=1</i>	-0.06	***
<i>ODep=0</i>	-0.03	***
<i>Δt=1:Δl=1</i>	-0.07	***
<i>Δt=4:Δl=1</i>	0.04	***
<i>Δt=1:K</i>	0.67	***
<i>Δt=1:Lm=0</i>	-0.02	**
<i>Δt=1:Lm=1</i>	0.03	***
<i>Δt=4:Lm=1</i>	0.02	**
<i>Δt=1:Ls=1</i>	0.04	***
<i>Δl=1:K</i>	-0.49	***
<i>Δl=1:Ls=0</i>	-0.04	***
<i>Δl=1:Ls=1</i>	0.06	***
<i>Lm=1:CV=0.2</i>	0.03	***
<i>CV=0.2:K</i>	0.31	**
<i>CV=1:K</i>	0.22	**
<i>CV=0.2:Ls=0</i>	-0.05	***
<i>CV=0.2:Ls=1</i>	0.08	***
<i>K:Ls=1</i>	-0.42	***

430

431 Table 4: Significant effects in the linear model explaining LK of the fits by the different
 432 assumptions.

433 *** (respectively **) stands for a p-value < 0.01 (respectively < 0.05)

	Estimate	P-value
Intercept	-4.74	***
$\Delta t=1$	-0.49	***
$\Delta l=1$	-0.38	***
$Lm=0$	-0.35	***
$Lm=1$	0.66	***
$ODep=0$	0.21	***
$CV=0.2$	-0.65	***
K	4.93	***
$Ls=0$	-0.40	***
$Ls=1$	0.64	***
$\Delta t=1:\Delta l=1$	0.14	***
$\Delta t=1:ODep=0$	-0.22	***
$\Delta l=1:ODep=0$	-0.13	***
$\Delta l=1:Ls=0$	-0.23	***
$\Delta l=1:Ls=1$	0.35	***
$Lm=0:Ls=0$	-0.17	**
$Lm=1:Ls=0$	0.42	***
$Lm=0:Ls=1$	0.33	***
$Lm=1:Ls=1$	-0.68	***
$ODep=0:CV=0.2$	0.13	***
$Lm=1:CV=0.2$	-0.27	***
$\Delta t=1:Ls=0$	-0.15	**
$\Delta t=1:Ls=1$	0.18	**

434

435 Table 5: Information on the nodes of the multivariate regressions trees (Fig. 2). The best fits are
436 the ones with the lowest LK and the highest $Lbic$

Node number	Number of adjustments in the node	Mean $Lbic$ (centred and reduced)	Mean LK (centred and reduced)	Deviance
1	648	0.00	0.00	1294
2	324	0.26	-0.83	363
3	324	-0.26	0.83	72
4	108	-0.17	-1.46	195
5	216	0.48	-0.51	445
6	108	-0.51	0.10	97
7	216	-0.14	1.19	251
8	144	-0.48	1.20	134
9	72	0.53	1.16	26
10	96	-0.96	1.23	41
11	48	0.49	1.15	69

437

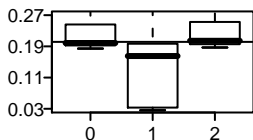
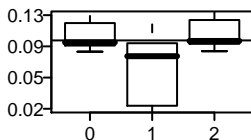
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439 Fig. 1: box-and-whisker plots of the estimated growth rate for the different assumptions of the
440 length-structured population model. Each row of plots corresponds to an assumption of the length-
441 structured population model while each column corresponds to a growth rate value used to generate
442 individual growth trajectories. In each plot, the different modalities of the considered assumption
443 are plotted in abscissa, the estimated growth rate being plotted on the Y-axis. The horizontal lines
444 represent the assumed growth rate for the simulated data.

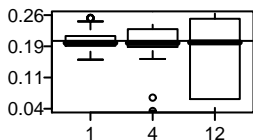
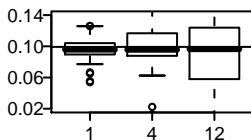
445 Fig. 2: Multivariate regressions trees of the fits of the length-structured population growth model
446 on simulated frequencies when n indicates the number of adjustments in the leaves. The
447 parameters are defined in Table 1. The grey numbers indicate the number of the nodes, more
448 information on each node can be found in Table 5

Kest

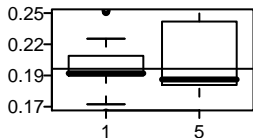
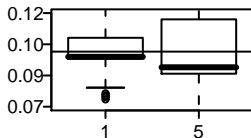
Lm



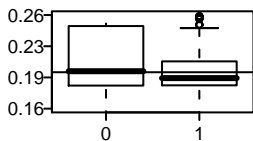
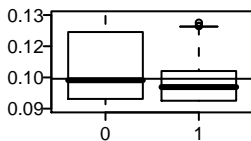
Δt



ΔI



ODep



$K = 0.1$

$K = 0.2$

